Lorem ipsum dolor sit amet, consectetur adipiscing elit. Fusce molestie turpis nec urna dictum, non convallis ante fermentum. In aliquam magna mauris, vel bibendum quam vulputate non. Quisque vel ex congue, consequat risus id, aliquam felis. Nulla id venenatis enim. Nam faucibus, nibh eget tempus interdum, justo lectus blandit velit, a pellentesque orci velit a lectus. Duis feugiat elit eget eleifend feugiat. Suspendisse posuere convallis lorem, sit amet tempor turpis gravida eu. Integer ipsum nulla, rutrum id ante in, lobortis tempor metus. Integer ac pharetra velit, in molestie augue. Praesent tincidunt pulvinar varius

Olympia Publishers
General
ISBN 978-184897-316-9
Author: **Tejaswi Ramesh**
£0.00 $0.00
www.olympiapublishers.com

TALES FROM THE ARCHITECT

TEJASWI RAMESH

TEJASWI P RAMESH

TALES FROM THE ARCHITECT

Part 5 : The End of Eternal Time

Tales from the Architect : The End of Eternal Time

Tejaswi P Ramesh

July 2025

Contents

1 Energy and rotational movement **5**
1.1 Classification of Individuals 5
1.2 Purpose of Creative potential energy 6
1.3 Location and State 7
1.4 Multiple state setting 8
1.4.1 Interception of the Prime observer 8

2 The Energy Trail of consciousness **10**
2.1 Observation 10
2.2 Interaction 11
2.3 Experience 12

3 The Masculine Observer **14**
3.1 The observer Perception 15
3.2 Engineering the interruption 16
3.2.1 The observer's perception of the interruption 17

4 The observers and the transition states **19**
4.1 Evolution and the observers 21
4.2 The Species 22
4.3 The leadership and the target state 23
4.4 Independent Observers and masculinity 24
4.5 The exchange of external geometric information 25
4.6 Deception in geometric configuration 26

5 Unobserved time for the multiverse state **30**
5.1 Time spent with individual A 31

6 Energy and Geometric association **34**
6.1 Deceptive Energy transfer 35
6.2 The interaction observers 36
6.3 The hierarchy of the interaction observers 38
6.4 The identification of the past , present and future by the observing masculine. 39
6.5 The Interaction of the observing masculine with the interacting masculine 40
6.6 Perception of movement and frequency 41

7 Perception of Geometry **43**
7.1 The timeline of each individual in the location X has the following form 43
7.2 Convergence of perception 44
7.3 The Deception time component of perception 45
7.4 The perception of deception in location geometry 46

8 Interacting observers and the trajectory **47**
8.1 The interaction mechanics between the prime observer and the sub-masculine observers 48
8.2 Defining the forecasting ability of the observers 48
8.2.1 Individual A's trajectory in the sub-location x1 50
8.2.2 Individual B's trajectory in the sub-location x1 50
8.2.3 Defining the observing masculine 50

9 The Mechanism of the observers **52**
9.1 Masculine Interacting Observer 52
9.2 The functioning of the masculine observer 53
9.3 The State Change process 53
9.4 The transition of one target state to another 54
9.5 Creation of movement drag from the state change 55
9.6 The Relocation of State 55

10 The mechanics of state separation of the interacting observers **56**
10.1 Prime observer 56
10.2 The observers 57
10.3 The interacting observers 58
10.4 The consequences of interaction 58
10.5 The Mechanics of the interruption 61

11 Consciousness Attention mapping **63**
11.1 Higher order geometric definition of the attention vector of consciousness 63
11.2 Individual consciousness (Lower intent mass) 64
11.3 Engineering the trajectory of the energy source 65

12 The dance of the prime observers **67**
12.1 Geometrical communication by the observers 67
12.2 The hierarchical creation of observers 69
12.3 The dimensional information set 69
12.4 Perception and the continuous flow of attention energy 70

13 The interacting observers and the energy distribution from the prime observer **72**
13.1 The hierarchy of the interacting observers 73
13.2 The Transient observers in the location 74

14 Creating transition states based on false realities **76**
14.1 The Observers 76
14.2 Intercepting the transition state 76
14.3 Engineering the interception 77
14.4 Energy mechanics of the interaction 78
14.5 Observing the attention energy trail to engineer the projected intent 79
14.6 Transition of states 80
14.7 The perception of the projected intent 81
14.7.1 The umbrella perception 81
14.8 The recreation of the observers if their interruption fails 82
14.8.1 The Observer O_2 83
14.9 Engineering long term attention Traps 84

15 new **86**

16 The multiverse observation trajectory **87**
16.1 Movement drag 87
16.2 Mechanics of mixed intents 88
16.3 State, Time and movement frequency 89
16.3.1 Probabilities for the multiverse 89
16.4 Masculine Interacting Observer 90
16.5 Second order observer 91

17 Location State Interactions **93**
17.1 Location defined by geometric dimensional information 93
17.2 Correlating states through movement 94
17.3 Engineering the interruptions 97
17.4 Introducing deception into the states 98
17.5 Defining state exclusively for energy transfer 98
17.6 The reflection of the state through geometric actions 98

18 Creativity and location trajectories **100**
18.1 Creative potential energy 100
18.2 Movement and Static locations 100
18.3 Creative potential energy and access tostatic locations 101
18.4 Conscious awareness and locations 102
18.5 Visualization as a matrix 102
18.6 Forcing Trajectories 103
18.7 Laws of Continuity 104

19 Energy and sub-locations **107**
19.1 The Strategy of the masculine for navigation of projected intent (deceptive intent) 109

20 Prime Masculine observation of states **111**
20.1 Outward state change 113
20.2 The contradictory states 114
20.3 Hierarchy of control 115
20.4 Illustration 116
20.5 observational states 118
20.6 Defining the masculine prime 122
20.6.1 Defining the current moment 123
20.7 Defining the hierarchical sequence of observers starting from the masculine prime 124
20.8 Interaction of multiple observers based on contradictory states . 126
20.8.1 Defining the transition states where the hierarchical sequence of observers choose to interact becomes the current movement 127
20.8.2 The Engineering process of the misaligned" k " masculines 128
20.9 The objective reality 129
20.9.1 Interruption of the " k " unaligned masculine observers . 130

21 The diagonal timeline **132**
21.1 The transition state 135
21.2 A 137
21.3 B 140
21.4 C 142

1 Energy and rotational movement

Let there be a prime observer who creates a location " X " at time T = 0 with " N " individuals with a defined a purpose in the location.

The exact relative locations of the " N " individuals with respect to the external boundary of the location defines the state of the location because their locations define their purpose in the location and their collective purpose in the location define the state of the location. The creation is assumed to be a four-dimensional geometric structure where the locations of the N individuals are assumed to be locations with respect to the origin which in this case is assumed to be the location of the prime observer which maybe inside or outside the geometric boundary of the location.

1.1 Classification of Individuals

Assuming that each individual was placed in a particular location for a particular purpose based on his ability or functionality to interact in the location which could either be to absorb energy from one location and transfer it to another location. The interaction mechanism of the individual could be defined exclusively defined based on his ability to absorb energy from various kinds of relative movement .

Let the " N " individuals be classified based on the following types :

The ability to extract and create potential energy from the location directly at a constant rate

The ability to extract and create potential energy from the location directly at regular intervals

The ability to extract and create potential energy from the surrounding individuals at a constant rate (inability to extract from the surroundings directly)

The ability to extract and create potential energy from the surrounding individuals at a regular rate (inability to extract from the surroundings directly)

1.2 Purpose of Creative potential energy

The creative potential energy could be used for the following purposes :

1. Alter the geometry of the location " X "

2. Expand the geometry of the location " X "

3. Control the movement or the location of one or more individuals by re-defining purpose

Suppose if each individual has a purpose that is defined by his purpose that has a specific goal with respect to the above three functionalities that define his contribution to the overall state of the location. There the collective overall state is then the contribution of every individual's purpose.

Let the individual create another state of the location at time of observation t = T1 where the new state is defined by altering the relative locations of the " N " individuals with respect to the external boundary of the location for a new purpose.

Then the transition state between the two static four-dimensional images could be represented as follows :

Initial state t = 0

Locations of " N " individuals at (X1 Y1 Z1 0) ,...., (Xn Yn Zn 0)

Target state t = T1

Locations of " N " individuals at (X_t1 Y_t1 Z_t1 T1) ,...., (X_tn Y_tn Z_tn T1)

Each of the N individuals has to shift locations in the following format :

(X1 Y1 Z1 0) to (X_t1 Y_t1 Z_t1 T1)

....

(Xn Yn Zn 0) to (X_tn Y_tn Z_tn T1)

This means that each individual has to change his location based on his purpose that is defined by interaction with creative potential energy based on the three functionalities. This is because changing the overall state of the location implies rearranging the geometry of the location " X " .

Suppose if the location " X" could be classified into " K " sub locations then ,

each of the sub-locations could have a purpose to meet the overall state of the location in X. Each sub-location could either be used to extract energy or divert energy that flows through a channel of various sub-locations in the location .

Therefore each location " X " could have the following :

" K " total sub-locations

" P " locations where energy could be extracted

" Q " locations where energy could diverted

1.3 Location and State

Thus" K " locations of the location " X " are segmented into " P " and " Q " locations such that each of the " N " individuals is placed in one of these sub-locations where at any given location he is either absorbing energy or diverting energy from the sub-location. It is assumed that the location of each of these individuals is placed based on his probability to absorb or divert energy defined by his purpose defined by the overall state of the location " X ".

Furthermore the criteria for each of the locations " P " and " Q " to place an individual is as below.

Suppose if individuals who produce a lot of creative potential energy at a constant rate are placed in locations where there are individuals who absorb creative potential energy at a constant rate and similarly individuals who produce creative potential energy are placed in locations where there are individuals who absorb energy at a regular rate.

The state that defines the location " X " could either be one of the following :

1. Alter the geometric parameters of the location X

2. Expand the boundary of the location X

3. Maintain the geometric integrity of the location X

4. Reduce the geometric integrity of the location X

The energy that is used for the above three process is navigated by the movement of the individuals in the transition states between the current state and the target state. Therefore the transition between the current state locations (

four dimensional image) and the target state locations (four dimensional image) does one of the above to the location " X ".

Therefore the movement of the individuals from their current locations t = 0 to the target locations t = T that is assumed to occur could be assumed in either discrete form or continuous form such as :

In continuous form of time , the individual's trajectory in the duration of time T units

In discrete form of time , the individual's trajectory through a set of "Z" discrete point transitions .

1.4 Multiple state setting

Suppose if there are " x " number of state observers in the location " X " such that each state observer creates the current state of each sub-location at time t = 0 and then the target state of the sub-location t = T based on the overall state set by the prime observer.

Then the same process is applied on a smaller scale where there could N_1,N_2,...,N_k individuals in each sub-location.

However if the target state that is set by the state observers is mis-aligned with the overall target state set by the prime observer , then there is a conflict of the overall expected states of the territory " X " where some sub-locations could have a state to expands territory , some states could have a state to reduce the geometric integrity of the location " X " , while some might have a state to maintain the geometric integrity of the location X while others might have the states to alter parameters of the location " X ". All of the states are correlated to the proportion of the variety of the individuals in each location and their relative movement .

1.4.1 Interception of the Prime observer

Since the prime observer has the primary source of energy from the state was created then he could eventually observe the state observer that is contradicting his defined state and re-locate the individuals based on their functionality to the new state.

Suppose if the " x " state observers start integrating all the states together such the alignment of all the " K " states could occur to misalign with the

overall state of the location " X " by defining the locations of all or most " N " individuals to diverge from the prime observer's state definition at time t = T , then the locations of " N " individuals will not be recognizable by the prime observer . There he could observe the relative movement of various individuals in each sub-location and start identifying the rotational movement patterns which have the same following pattern :

Several Non-Masculines show geometric rotational movement around the same sub-masculine.

Several Sub-Masculines show geometric rotational movement around the same masculine

Several masculines show geometric rotational movement around the same prime masculine

Under the prime observer's definition of states , the individuals who produce creative potential energy at a constant rate are made the masculine and the sub-masculines show rotational movement around the masculine to absorb his energy and the non masculines show rotational movement around the sub-masculine to absorb his energy. The definition of masculinity is therefore strictly defined by his ability to provide energy.

However under the manipulated system where the collective " K " states have been aligned to the mis-align with the overall state set by the prime observer , the movement pattern is the same , the energy flow is referenced. The individuals who produce creative potential energy are made the non - masculines and the masculines are individuals who have the highest conscious awareness without the ability to produce creative potential energy. The individual uses his conscious awareness specifically the movement of the " N " individuals and geometric information of the location " X " and the various " K " sub-locations to engineer the energy flow such that it flows to the masculine (of which he has none as a result of his mis alignment with the prime observer) .

2 The Energy Trail of consciousness

Suppose the consciousness of the individual could be defined as having the following functions :

Observation

Interaction

Experience

2.1 Observation

The consciousness of the individual A could be defined as having a finite amount of energy E units which could be used for the above functions. Observing the current location of the consciousness relative to the surroundings specifically the surrounding consciousness could be done through the energy trail of creation. The surrounding consciousness could be defined as the family tree / territory tree of the consciousness specifically the where the consciousness originates specifically the energy that was used to create the consciousness that could be a mixture of several independent existing consciousness in the location of creation . Since each independent consciousness is created from various other sources of energy from other independent consciousness . Therefore this creates an energy trail for the consciousness of individual A that liked to various other independent consciousness. The consciousness tree therefore could be described through various the relative locations of the chain of locations through which energy is being transferred to the newly created consciousness of individual A.

Therefore the functionality of consciousness could simple be defined as observing the energy trail of its current location to the various other independent sources of consciousness. Those other independent sources of consciousness could have their own tree of energetic trails of consciousness and tracing this could be a core function of consciousness.

This could be achieved by observing the movement capabilities of the independent consciousness that is in the surroundings of individual A. The ability to plot various trajectories or locations from the point of origin could be define the amount of potential energy that is stored in each consciousness . This would be because if the origin location of the consciousness of individual A is assumed to be the starting point and then the distance from the origin that it could travel could define its ability to access potential energy in the surroundings. This is because the longer the distance , the higher the amount of energy that is needed to travel the distance because the movement process would require a movement trajectory to the target destination. Since the trajectory requires a continuous

observation of other locations that may also be plotting trajectories for their movement , a continuous stream of energy for the consciousness of individual A.

The stream of potential energy originates from the trail of the energy that originates from one or more consciousness that had created the consciousness of individual A. Thus the movement trajectory of individual A could only occur with the consent of the creating consciousness. If the consent of the creating consciousness is broken then the consciousness would have to absorb energy from various other trajectories in the location trajectory of its destination.

2.2 Interaction

The mechanism of interaction for the consciousness of individual A could follow the observation process. The observing consciousness of individual could identify its current location relative to the locations of consciousness that have the required amount of potential energy to advance its trajectory. Whether the consciousness of individual A could either use the energy from the independent consciousnesses (by identifying their locations) which are part of its creation tree or it could observe the various other independent consciousness that is part of a different creation tree.

Once the observation of the relative locations are noted in a sequential pattern , the movement pattern of the independent consciousness could be identified relative to its own location. The movement trajectory of the consciousness of individual A could then be altered to intercept the expected location of the consciousness that holds the potential energy for its own trajectory from its own creation tree.

The consciousness of individual A then interacts with the other consciousness by identifying all the location trajectories that are possible for its movement and then spends an amount of energy delta E to alter the trajectory of the other consciousness. This process could be achieved by diverting the attention vector of the other consciousness that has the stored potential energy to a new location. This would allow the potential energy that is stored for its movement of its current trajectory which is in the form of kinetic energy to be utilized by the intercepting consciousness of individual A . Therefore the total energy that was stored for the movement trajectory of the creation tree to be harvested because the momentum of that trajectory would be initiated to various other interconnected consciousness for their own independent trajectories.

This process of momentum hijacking of various trajectories which have an amount of potential energy that is dispersed to alter or set the trajectories of various other trajectories could then be observed by the intercepting individual

A and then he could repeat the same process after intercepting their locations and diverting their attention vector while hijacking the various trajectories and using the momentum to set alternative trajectories that are aligned to the trajectory of individual A .

This process allows of diverting a small amount of energy delta E by individual A after intercepting the trajectories of various other consciousness that hold kinetic energy is known as interaction. Therefore in the dimension of geometry , the process of interaction is limited to the process of altering the attention vector of various other consciousness such that their location trajectory could be diverted either temporarily or permanently .

While the temporary interception of various creation tree trajectories could be done by individual A , the permanent redirection of location trajectories of various creation trees could occur by creating one or more intercepting consciousness to interact with the creation trajectories of various other consciousness that hold potential energy. The accumulated kinetic energy that has created momentum for various trajectory movements could be harvested for other objectives set by the individual A who is the masculine. In this context , the created consciousness could serve as the sub-masculine who interact on behalf of the intercepting consciousness of individual A.

2.3 Experience

While the process of observation and interaction could simplified to observation of various locations and identifying the next potential target location trajectories by explicitly communication between one or more attention vectors of various independent or collective consciousness, The process of experiencing the trajectory from the current location to the target location could be the process of continually observing and interacting with the attention vectors of various other independent or collective consciousness in the surrounding areas within an established current location to the target location trajectory.

Suppose if a creation tree has a target location trajectory then its movement trajectory towards the target location could involve the observing the relative locations of various other consciousness that provide the source of energy for its movement towards the target location . Suppose if the target location has been determined by the one or more consciousness that created the independent consciousness at the origin location , then the independent consciousness then starts its movement trajectory towards the target location by continually observing and interacting with the relative movements of various locations of the consciousness family tree that is diverting energy to the individual consciousness.

Then the repeated sequential observation and interaction of locations that occurs with the exchange of energy that propels the individual consciousness towards the target location could be described as experience of the trajectory. The experience of the trajectory in the geometric form could simply be observation and interaction with various other consciousness where energy is diverted or absorbed such that the attention vector of various consciousness could be altered. However the ability to alter the location trajectory of various other consciousness through the attention vector could depend on various energy metrics such as :

1. The amount of kinetic energy that any consciousness has in its ongoing trajectory that has been set up by the creating collective consciousness.

2. The amount of potential energy that any consciousness has to intercept the attention vector of the consciousness in movement which has to exceed the kinetic energy of the consciousness in movement.

3. The ability to interact of an individual A towards any consciousness and its attention vector is there a function of energy.

The experience of this set trajectory from the current location of its creation to the target location of its destination could observed through various possibilities other than the objective geometric movement pattern . The movement could be interpreted in various subjective forms based on the exact intent for the movement towards the target location . Suppose the entire movement towards the target location could have a singular purpose then the entire trajectory could be discretized into various segments before its target destination.

The geometric intent could always be deterministic which is exchange energy with the surrounding consciousness that eventually leads to its target location.

This process could take many perceptions based on the exact purpose of its creation when it is observed by various other surrounding individuals. Since the target location could not be determined without consistent long term trajectory observation , the determination of the intent of the target trajectory of any individual by the observers could depend on the dimensions of information that they are observing which would be their perception.

The perception of any trajectory of movement that is occurring is defined explicitly by the observer based on the dimensions of movement parameters that he is observing which could vary or intersect between observers. The independent consciousness could observe various dimensions to define the perception of its own movement , however varying the dimensions that are correlating the movement specifically the locations of various consciousness that is diverting energy towards its movement. The consciousness awareness of movement is therefore identifying the exact locations that is diverting the energy for its movement

and the more accurate the dimensions of information become , the higher the conscious awareness becomes.

The perception functionality of the consciousness therefore expands by identifying and increasing the dimensions of information that is correlating towards its movement. The more accurately the location dimensions of information could observed , the interaction mechanics becomes easier and thus the control of the trajectory for the consciousness becomes easier to control.

3 The Masculine Observer

Let there be a location X with an observer who observes and interacts with the " n " sub locations of the location X. The overall transient state Y_observer of the location is maintained by the observer . The observer had interacted with the location X in various sub-locations in continuous form throughout the duration of his life T units. The purpose of the transient state Y_observer is to ensure that the overall geometric external boundary of the location X is maintained which is defined during his duration of interaction in various locations.

The geometric consciousness of the observer maintains the transient state by ensuring that the eight geometric co-ordinates that define its volume of the location are maintained according to his definition. The geometric consciousness of the observer is maintained through the attention energy that is diverted to it by the territory and family tree of the observer who interact in continuous form in various locations to carry out his intent to maintain the geometric integrity of the location defined by him.

The geometric consciousness could then merge its movement vector field to various interacting individuals in each sub-location or sub-sub location to interact with a higher conscious awareness to observe the directional intent of various individuals that have a probability of disrupting the transient state Y_observer set by the observer.

The geometric observer observers each location through the discrete form of time or specifically a three dimensional geometric image along the geometric time axis at various instants of time such as t = T_1,T_2 etc where the duration of length or time between each observation (T_2 - T_1) , (T_3 - T_2) is assumed to be nearly zero or negligible.

At each moment of observation at any location ,the three dimensional frozen image of the location is observed with the energetic trial of intent (from his attention vector) from each individual towards his probable next location. Suppose if there are " z1 " possibilities for the movement of the individual in the

next instant of time t = T_2 which is also a frozen three dimensional image , there could be " z " possible timelines that could diverge from T_1 to T_2.

Thus there could " z1 " possible realities or timelines to go from T_1 to T_2 , each of which could be observed for continuity by extending the three dimensional images such as :

T_1 to T_2 = z1 possibilities where z1 realities could be probable each defined by its own geometrical configuration of three dimensional geometry in the location implying that there could be " z1 " photographic images for the observation at T_2.

T_2 to T_3 = z2 possibilities where z1 realities could be probable each defined by its own geometrical configuration of three dimensional geometry in the location implying that there could be " z2 " photographic images for the observation at T_3.

.....

Therefore the number of possible realities to go from T_1 to T_3 could be (z1 * z2)

Thus the number of realities increases by increasing the distance between observations i.e if the distance between (T_2 - T_1) , (T_3 - T_1) starts increasing , the number of realities specifically the magnitude of z1,z2 starts increasing exponentially.

3.1 The observer Perception

The number of possible realities " z1 " is defined by the number of ways the attention vector of the individual is split in the three dimensional image observed by the masculine. The attention vector of any individual is associated with various objects or individuals or locations naturally associated with the memory . The stronger the memory association of the individual , the stronger the energy trail of his attention vector is likely to be towards the object or individual which alters favours his directional movement towards the object or individual or location that is aligned with his intent towards the focus of his attention.

Since in any given instant of time the individual could have " z1 " things (people or objects or locations) that is associated with his memory , the trail of energy from his attention vector is likely to be sorted based on the memory association towards the object. Therefore the movement of the individual could be forecasted by the observer at the next instant of his observation T_2 as " z1 "possible three dimensional photographic images .

Suppose if the target state of the overall location " X " is defined in the same manner then the three dimensional photographic image of the location X is observed through the external geometric boundary of the location X in its entirety through its volume which could be defined by eight geometric co-ordinates that enclose the location X within these points.

Suppose if the one or more of these eight geometric co-ordinates that enclose the location X starts to diverge , then it would be visible at any time of observation T_x made by the masculine observer. Then the masculine obserfver then identifies the exact moment of observation that the change starts to occur (the state Y_observer starts to diverge) in the overall location X at t = T_divergence.

The masculine observer then identifies the exact sub-location within the location X and identifies the individual A that is diverging the state Y_observer and tracks his movement by identifying the distance between various times of observation T_1,T_2,... and calculates the distance between the time of divergence of the state and his actions at various time periods of observation such as (T_divergence - T_1) , (T_divergence - T_2),...

The exact energy trial of individual A at the time of observation T_1 is identified through his attention vector which defines his possible " z1 " possibilities that his reality could diverge to from the point T_1. In the sequence of events where the divergence that occurs , the attention vector and the location of individual A is observed at time T_2 . At this point of observation , the number of possibilities at " z1 " for his next location would have collapsed to a single possibility at time T_2.

The masculine observer then engineers a situation such that attention vector of the individual A could be diverted at time T_1 such that his location could differ to the one observed at T_2 which creates the divergence in the state Y_observer. Thus creating a parallel geometric configuration that could preserve his origin intended state Y_observer , however there is no guarantee that one interruption at T_1 would prevent the disruption of the state at T_divergence , therefore the process is likely to be iterative at various subsequent observation points T_1,T_2 etc. because if the divergence cannot be prevented after the interruption at T_1 , then the process could at any points of time between T_1 and T_divergence where the probability of disruption is high which is estimated by the observer.

3.2 Engineering the interruption

Suppose individual A is identified to be interrupter that causes the divergence at the location X and at time t = T_1 , he is observed to be in the sub-location x6. The masculine observer then chooses to divert his directional trajectory such that the interference to location X at T_divergence does not occur.

The masculine observer has a masculine interactor in each sub-location of the location X with whom he has merged his movement vector field such that his intents are quantum entangled with those masculine interactors such that their movement in the surroundings would mirror the movement of the masculine observer to a significant degree. Each interacting observer is also assumed to have a team of sub-masculines and non-masculines that operate under his leadership . The team then operates under his leadership to either distract , disrupt , or divert the trajectory of the individual by altering his attention vector such that the probability of individual A to cause the disruption at the time T_divergence is reduced to zero or non existent.

The observing interactor at x6 could then start an interaction with individual A around the time T_1 such that his attention vector diverts his trajectory as divergent as possible from his original indented trajectory. The masculine observer could also involve the observing interactors in the sub-locations surrounding x6 such as x5.x4 and x7 to assemble their team of (sub-masculines and non masculines) to interact with individual A through various intersecting individuals to align in the location x6 to cause the interruption.

3.2.1 The observer's perception of the interruption

At time T_0 , the masculine observer identifies the location of the various interacting observers independently in the location x4,x5 and x7 which is observed as a three dimensional geometric image in those independent locations. Each of the interacting observers would have " z0 " number of possibilities for their next location trajectory at T_1. Since the attention vector of the observing interactors is likely to be a function of the their specific sub-locations of operation , their movement vector field is likely to be different or specific to those locations and they would have their own independent trajectories at time t = T_1,T_2,T_3

The intent of each of the observing interactors would likely be aligned to those locations at time T_0 which would be independently altered by the masculine observer such that their movement vector field starting from their respective sub-locations would converge in the location x6 such that the observing interactors would converge their trajectories at time T_1 to interact with individual A in location x6.

If the observing interactors succeed, then the trajectory of observing interactors would likely converge back to their original trajectories at T_2 as they had originally intended. If however , the interactors fail to prevent the trajectory of individual A , then trajectory will merge at T_1 until one of the events will likely occur :

The observing interactors will continue to intercept individual A at various times such as T_2,T_3 etc until a suitable outcome is achieved

or

lose access eventually to the location of individual A as he progresses along the sub-location trajectories at T_2,T_3,... etc . While the location may still be available the state of the location that is set by the masculine before he enters it may not be available as a result of the diverging timelines of the masculine observer and individual A . Since by definition the masculine observer has control over the trajectories of individuals in his location specifically the state Y_observer , the contradictory movement of individual A will shift masculinity from the observing masculine to individual A in the location X . The interacting observers will become integrated into the trajectory of individual A such that their interaction will serve as a catalyst for the divergence of the state Y_divergence to occur at which point their locations at T_2,T_3 etc will become a function of individual A rather than the observing masculine.

4 The observers and the transition states

Suppose if a prime observer creates a location " X " defined by a geometric external boundary that is defined by eight geometric co-ordinates that define its shape in three dimensional space that has volume V.

Let the location " X " have " n " sub-locations (X1,X2,...,Xn) each of which has its own geometric external boundary that is defined by eight geometric co-ordinates that define its shape in three dimensional space with volume V1,V2,...,Vn.

Where V = V1 + V2 +...+ Vn

Let each sub-location be defined as have " N " sub-sub-locations (x1,x2,...xn) each of which has its own geometric external boundary that is defined by eight geometric co-ordinates that define its shape in three-dimensional space with volume v1,v2,...,v_n

Where V = v1 + v2 + v3 +....

N greater than n

Suppose if the prime observer created the location at time t = T_1 and creates a target state for the location X at time t = T_2 such that geometric external boundary would be redefined such that its shape in three dimensional space could be redefined to have a new volume V_new.

Let there be " D " transition states between the T_1 and T_2 such that each transition state is created when an observer is observing the geometric external boundary defined by eight geometric-co-ordinates of each sub-location relative to the location X, the other sub-locations X1,X2,...Xn and consequently the sub-sub locations defined by x1,x2,...,xn .

Let there be " K " observers for each sub-locations and sub-location sch that they exclusively observe the geometric co-ordinates of their corresponding sub-location or sub-sub location relative to the surrounding sub-locations or the sub-sub locations and the overall location X. Where the number of observers created " K " is assumed to occur through the law of minimal action where it would define the deterministic set of transitions that would occur to match the target state set by the observer.

Suppose if the prime-observer explicitly defines the geometric external geometric boundary through the change in the eight geometric co-ordinates such that the change in volume occurs from V to V_new.

Then the change in co-ordinates by exclusively creating the bare minimum observers for the corresponding sub-location and sub-sub locations such that

there are " K " masculine observers created that either observe the transition of their respective sub-locations or sub-sub locations such that external geometric boundaries change through their eight geometric co-ordinates change such that the overall geometric external boundary defined by the eight geometric co-ordinates that define the location X change to match the new volume defined by V_new.

If there are a total of N sub locations and n sub-sub locations then there could potentially be (N + n) overall observers in the location X each defined hierarchically based on the total volume V_k that they are able to observe as a percentage of the overall volume V of the location X.

Therefore if the total number of observers possible is O_total = N + n , and " K " of those observers that are observing the external geometric boundaries and defining the eight geometric co-ordinates deterministically , then there are O_ind = (O_total - K) independent observers each with their own location or sub-location and a percentage of control over the total volume stochastically.

Thus the independent observers O_total observe their corresponding sub-locations or sub-sub locations independently at each of the " D " transition states that occur between between the current state T_1 and target state T_2 set by the prime observer.

If the state of transition is defined by " State Y " that defines the external geometric co-ordinates deterministically for the " K " sub-locations and the sub-sub locations such the target state defined by the geometric co-ordinates for the location X with volume V_new is achieved. The independent observers observe the remaining O_ind locations and sub-locations and define their transition state for the overall location X. The independent observers may or may not align with the overall target state defined by the prime observer depending on the dimensions of information that they choose to observe during their definition of transition states for their sub-locations or their sub-sub locations.

It could also be possible that such independent observers may choose transition states to contradict the overall target state set by the prime observer for the location X. Thus the " D " transition states between the current state T_1 and the target state T_2 becomes a stochastic variable creating the multiverse state where after each transition the number of transitions required to reach the target state may increase or decrease.

Therefore the transition state to go from the current state to the target state depend on the number of transitions " D " where the value of D resets after each transition creating a new timeline defined by the number of exclusive transitions that are required to meet the target state.

The exact state at which the target state is reached with " D_final " num-

ber of transitions could only be observed by the prime observer because the " K " number of observers that he chooses to observe implies that the observes " K " number of transitions . If the prime observer could explicitly any of the transition states at t = T_d_final and explicitly define the number of transitions " D_final " to the target destination , then the number of external boundaries for the sub-locations or sub-sub locations that the independent observers O_ind could control starts to decrease as the number of transitions D_final becomes deterministic. This forces the transition states of various sub-locations and sub-sub locations controlled by O_ind to start becoming deterministic until the target state is met.

4.1 Evolution and the observers

Evolution could be defined through consciousness awareness of the territory tree of any particular species. The conscious awareness in this particular context occurs by increasing the state awareness of the geometric boundary that that the transition movement is occurring in.

Specifically the external geometric information or the eight geometric co-ordinates (three dimensional volume) of the external boundary of the location where the movement is occurring from the current location at t = T_1 to the target location t = T_2.

The increase in awareness of geometric co-ordinates of the current location, sub-location and the sub-sub location will allow the accurate trajectory plotting for the movement of the species which is established through the information flow through the hierarchy of the observers originating from the prime observer of the species.

The prime observer of the species specifically tracks the external geometric boundary of the current state of the location and alters the state such the trajectory for the target state could be plotted. This is done by random sampling the territory at various sub-locations and sub-sub locations to observe the movement trajectory that is occurring in those locations to deduce the exact state of the location.

The exact state of the location could be observed by observing the global movement vector of the location X which is approximated by observing the local movement vector of various sub-locations and sub-sub locations.

The movement vector field identifies the net energy flow at various sub-locations and the sub-sub locations. If net energy flow is positive then the sub-location is masculine if its negative the sub-location is feminine.

For territory expansion the masculine observes and provides energy to the sub-masculines for their interaction movement to expand territories specifically the eight geometric co-coordinates that define the respective volume for their regions.

To identify the movement vector field in any sub-location or sub-sub location , the sphere of influence of the masculine would have to be observed by tracking the movement of their sub masculines and their region of control by identifying the external boundaries (geometric co-ordinates) which is the limit of their influence.

Once the exact geometric boundaries of the sub -locations or sub-sub locations that each masculine controls are identified then the external geometric co-ordinates of their control could be identified. Once identified , it could be altered by redefining those exact coordinators to expand or contract relative to the external geometric co-ordinates of the other masculines or sub-masculines.

Thus the process of evolution is therefore identifying the hierarchical command structure that is defining the movement limit boundaries of the collective and then redefining it such that the movement trajectories are updated with new external geometric limit co-ordinates for each sub-location or sub-sub location.

4.2 The Species

For a species that is complex as human beings , the social structure would have to be identified based on movement, time distribution and the attention vector relative to each other. Then a joint correlation between those metrics for the trajectories in the corresponding sub-locations or sub-sub locations could be identified.

Once the trajectories in the current sub-locations and the sub-sub locations are identified based on their joint correlation of the sensory perception on both on an individual and a collective level (family and the territory tree) , the trajectories could be redirected towards the target state to increase the survival probability.

This is achieved by the prime observer by first identifying the current state of transition that is set by the independent observers O_obs and then altering the various states of the sub location or sub sub location such that it affects the overall state of the location X to meet the new target state at T_2 where the movement trajectories of the individuals are altered to meet the desired target state set by the prime observer.

Altering the state literally means the geometric external boundaries of each

sub-location or sub-sub sub location through the eight co-ordinates

4.3 The leadership and the target state

If the co-ordinates need to be expanded then there needs to be a masculine whose intent or purpose is aligned to expand,

if the co-ordinates to be held stable or constant then there needs to be a masculine who can keep the geometric boundary stable will need to be identified.

If the geometric boundary need to be reduced then the masculine who reduces the geometric boundaries will need to be identified .

All of the above functions will need to be identified through the management of energy where if the net energy is zero then the sub location and sub-sub boundaries will be stable.

If the net energy in the specific sub location or the sub-sub location is positive then the energy could be used for the expansion of the geometric boundaries.

If the net energy is negative , then energy from the current geometric structure is absorbed and the overall boundaries set by the eight geometric boundaries automatically shrinks.

Thus the process of evolution could be summarized as :

Observe the co-ordinates of the state Y

Redefine the coordinates of the state Y

The change of masculine would occur naturally to align with the new defined co-ordinates and if the process requires expansion of geometric boundaries then the masculine would be replaced accordingly Altering the state literally means the geometric external boundaries of the location or sub location through he eight co-ordinates

If the co-ordinates need to be expanded then there needs to be a masculine whose intent or purpose is to expand, if it's needs to be ket stable then the masculine who has the ability to keep the geometric boundary stable will need to be identified. If the geometric boundary need to be reduced then the masculine who reduces the geometric boundaries will need to be identified for the location or sub location

Thus the process of evolution would be :

Observe the co-ordinates of the state Y

Redefine the co-ordinates of the state Y

Where State Y (In three dimensional space) holds the eight geometric co-ordinates that define the structure of the location, sub-location and sub-sub locations respectively at each transition state.

Where State Y_int is the co-ordinates observed at time T_1

State Y_final is the co-ordinates observed at time T_2

The change of masculines would occur naturally at each sub-location or sub-sublocation to align with the newly defined co-ordinates for the target state depending on whether expansion , contraction or stability is required.

4.4 Independent Observers and masculinity

Let there be O_ind independent observers that communicate geometric external boundaries through their respective " sub-locations" or " sub-sub locations "

The independent observers interact in their respective domains by creating offspring in their respective domains who movement is limited to the external geometric boundaries set by the observers. The observers are assumed to be geometric in nature and they perceive time in geometric form where the dimension of time becomes a geometric axis.

The observers then create an offspring or an interactor at any point along the geometric axis to start interacting in the sub location or sub-sub locations of their domain. This point would be the initiation of a new transition state and if it is made at particular point along the axis , then it could be assumed as t = 0. The observers could create a transient state to change the state Y of the sub-location or sub-sub location such that a point along the geometric time axis , the target state of the specific location is altered to the geometric external boundary set by the observer.

The new transition state is created as a continuous process where the observation of the rate of change of geometry occurs in continuous form until the point t = T units where the death of the transient state occurs. Suppose if the purpose of the transient state is observe the sub location or the sub-sub location , then occurs by observing the State Y in continuous form. Particularly , the continuous observation of the external geometric boundaries of their specific assigned territories.

The observation of the geometric shape specifically the eight co-ordinates defining the external volume of their territories then becomes the purpose of the interactors.

While the role of the observes is to observe the exact transition state that is occurring in their respective sub-locations or the sub-sub locations in accordance with the masculine observing over their transition states. In other words, each observer of the transient state in various sub locations or sub-sub locations would have to be created by the masculine observers whose territory extends beyond the territory of the observers observing the transient state in each sub location or sub-sub location.

Therefore the definition of masculinity in the observer context becomes the individual with the largest geometric external boundary of control . The observer who could perform rotational observation over his territory which includes the entire territories of various other observers who could perform rotational observation in their sub locations or sub-sub locations.

4.5 The exchange of external geometric information

Suppose if there are " R " number of individuals in each sub-location or sub-sub location which could be a random number, one of the random individuals could interact with another random individual in the surrounding sub location or sub-sub locations to transmit the state information which is the set Y which contains the eight geometric coordinates that describe the external boundaries of their corresponding locations . The exchange of state information through the set Y describes the flow of transition towards the target state set by the masculine. The exchange of geometric information that occurs between two individuals between the neighbouring sub locations or sub-sub locations is the change of state that occurs simultaneously for the corresponding sub locations or sub-sub locations involved.

Since the transition state of the location X has a correlation to the respective transition state in each sub location or sub-sub locations through the continuity of geometry , any transition of state that is initiated at any sub-location or the sub-sub location has a parallel effect on all the sub locations or sub-sub locations that is aligned with the current transient state through the flow of energy.

There is net flow of energy that is occurring from each sub-location or sub-sub location to another such that the hierarchy of transient states could maintain the hierarchy of the decision flow and the energy is used to observe and interact with various sub-locations or the sub-sub locations and the expansion of various boundaries for any sub-location or sub-sub locations. This would re-

sult in the growth in the volume of various sub locations or sub-sub locations . However if this process occurs without alignment with the prime observer who determines the external geometric boundary of the overall location X , then the the geometric structure starts skewing within the external boundary set by the prime observer. The skewing occurs as a result of mis-alignment with each sub location or sub-sub location with the surrounding locations. This occurs particularly due to the eight geometric co-ordinates that defines the outermost boundaries of various sub-locations or sub-sub locations starts overlapping thus creating the skewness .

Since the objective reality of the movement perception in the location X is defined by the trail of geometry , the objective reality of perception starts to degrade or distorts the perception of the " R " individuals in the location X , thus reducing their ability to perceive the surroundings accurately and consequently being unable to identify the trajectories for the growth of creative trajectories for the overall location X.

The movement that is occurring in each sub location or sub-sub location no longer produces stable creative potential energy over the growth the overall geometric co-ordinates of X which occurs by observation and interaction outside the current boundaries. The skewing in the internal structure of the overall location X occurs because when net potential energy from each sub location or sub-sub location is extracted beyond the available free energy in each sub-location or sub-sub location. This increases the entropy in the locations at an accelerated rate thus deteriorating the geometric structure in the particular sub location or sub-sub-location.

Thus the uneven increase in enthropy of the various sub locations or sub-sub locations will deteriorate the overall location in various regions as a result of the mis-alignment with the prime observer.

4.6 Deception in geometric configuration

Suppose if there is a location X with N sub locations .

Suppose if each of the independent observers O_ind were created as interactors at various sub-locations and sub-sub locations. Following their creation at various time t = 0 and their death at t = T, their interaction could be represented through their interaction period at various locations and sub-sub locations described by the continuous transition period of observation and interaction which i of the form :

t = 0

observer is born as an interactor in the sub-location x1

the observer interacts in the sub-location for a duration of t1 units

there are " n_1 " individuals in the sub-location that the observer interacts with .

t = t+t1

observer is born as an interactor in the sub-location x2

the observer interacts in the sub-location for a duration of t2 units

there are " n_2 " individuals in the sub-location that the observer interacts with .

t = t+t2

observer is in the sub-location x3

the observer interacts in the sub-location for a duration of t3 units

there are " n_3 " individuals in the sub-location that the observer interacts with .

.....

t = T-tn

observer dies in the sub-location x1

the observer interacts in the sub-location for a duration of tn units

there are " n_n " individuals in the sub-location that the observer interacts with .

Therefore the total interaction period of the observer is T units where T = t1+t2+...+tn covering the locations x1,x2,...,xn and the transition state of the observer is set for the state Y by defining the external geometric co-ordinates (set Y) for the locations in alignment with the prime observer.

The consciousness of the individual is assumed to hold the external geometric co-ordinates of various locations he has interacted with such that the transition occurs in each location towards the overall state Y set by the prime observer after his death. Since the individual has died and can no longer interact with the various sub-locations because his biological body is assumed to hold the potential energy for the interaction , the target state of each location occurs by observation of the transition state at each location relative to the target external geometric co-ordinates (set Y) .

The consciousness of the observer is assumed to observe each transition state of the locations that he has interacted with in a geometric context , and the potential energy for this process is assumed to originate from the attention energy from the total number of individuals that he has interacted with (n_1,n_2,...n_n) individuals.

If the state Y that is set for the target state set by the observer after his death is maintained by the family and territory tree of the observer and / or the (n_1, n_2,...,n_n) individuals, then this occurs by the attention energy drained from each location that is provided to the observer from the extended individuals (family and territory tree of the observer and n_1,n_2,..,n_n individuals in various locations). Therefore the attention that is fuelling the potential energy for the observing consciousness to interact to realign the geometric external coordinates of the locations is drained from the " R " random individuals that exist in the location whenever there is an interruption in the state Y that is set by the observer.

If the observers in the location are receiving attention from the " R " individuals that exist in the location either through the products, enterprises , groups or any interaction that bring attention to the observer through one or more intents that he has set up in each location that becomes integral to maintain the geometric external boundary for each location.

Suppose if there are O_ind observers in the location X who are independently maintaining their states in the sub-location or the sub-sub locations that they are interacting with then alignment of intents could occur to merge the states of one or more locations. Similarly if there are contradictions then , the contradictory intents will interact for a duration or length of time " T_cont " units until the intent that has the higher amount of potential energy will stabilize in the sub or sub-sub location.

Therefore if there are broadly " N " sub-locations in the location X , then out of the O_ind observers there could " K_mas " observers who have aligned their states with the largest number of locations and consequently the attention of the largest group of individuals.

Therefore the " K_ mas " masculine observers control the dominating impact of the overall state of the location X.

Since the states Y1,Y2,..,Y_mas set by the masculine observes are created at a random intitation time T_1 and target destination time T_2 , the expected overall geometric structure of the location X based on their specfic intents that align each sub-location to their target destination could vary slightly or significantly depending on the number of alignments or contradictions.

Therefore this could create a kind of conflicting overall intent for the external gemetric boundary of the location X and the interaction that occurs between the masculine observers K_mas could occur through the constant interaction with various random individuals " R " in each location depending on the amount of potential energy that is accessible to each of those interacting individuals to set the external geometric co-ordinates based on their target state Y.

Therefore if there are too many conflicting intents to define the external geometric boundaries of each sub-location, sub-sub location then there is contradictory information flow for the eight geometric co-ordinates that define the volume of each location thus creating skewness the overall structure of the sub-location or sub-sub location. This primarily occurs as a result introducing deception based alignment particular any intent that is aligned by the observer in any location based on his projected intent of geometric external boundaries rather than this true intent for eight geometric co-ordinates .

This could occur by projecting an intent (State Y_projected) for a sub-location specifically the geometric external boundary and then draining the attention energy of the " R " random individuals then the true intet (State Y_true) is reflected for the geometric external boundaries . In a geometric sense , the attention of the individuals is absorbed by projecting a set of eight geometric co-ordinates set Y_projected for the sub-location or the sub-sub location while secretly directing a set of eight geometric co-ordinates set Y_true to the location the hirachial territory and family tree.

5 Unobserved time for the multiverse state

Let an individual's life be defined as a function of locations , time and other individuals's he interacts with.

An individual's life takes the format :

At t = 0

Individual A is in location x1

time spent in location " x1 " = t1 units

the number of individuals in location x1 = n1

At t = t + t1

Individual A is in location x2

time spent in location " x2 " = t2 units

the number of individuals in location x2 = n2

....

At current time t = t + t_n-1

Individual A is in location xn

time spent in location " xn " = tn units

the number of individuals in location xn = n_n

Until the current time t = t + t_n-1, individual A spends an amount of time with each of the individuals such as :

At time = t + t_n-1 , individuals A spends an amount of time tn units with n_n individuals

Individual A spends T1 units of time with individual one (from the set of n_n individuals in the location xn)

Individual A spends T2 units of time with individual two (from the set of n_n individuals in the location xn)

.....

Individual A spends Tn units of time with individual n_n (from the set of n_n individuals in the location xn)

Therefore the total time distribution of Individual A in the location xn is thus given by :

tn = T1 + T2 + ...+ Tn

Since all " n_n " individuals are also assumed to spend the same out amount of time tn units in the location " xn ", their time distribution may differ with respect to the

5.1 Time spent with individual A

To illustrate individual one (from the set of n_n individuals in the location xn) could have the following distribution :

Individual one spends T1 units of time with individual A (This should be the same with respect to individual A)

Individual one spends (tn - T1) units of time with any one or group from the remaining set of individuals (n_n - 2)

Similarly each of the individuals other than individual A would have the following time distribution unobserved by individual A in the location xn

Individual one has (tn - T1) units of time which is a black box to individual A

Individual two has (tn - T2) units of time which is a black box to individual A

.....

Individual n_n has (tn - Tn) units of time which is a black box to individual A

Therefore the total amount of time that is unobserved by individual A , from all the individuals interacting with individual A is given by

T_unobserved = (n_n * tn) - (T1 + T2 +...+ Tn)

Suppose if there are " K " observers in the location xn who are communicating geometric co-ordinates based on the transition states that they have created for their next point of observation T_2. Each observer is assumed to assumed to

observe the location at time t = T_1 and create a target state for the location t = T_2 and thus each observer creates or generates movement in the transition state towards his own target states Y_1, Y_2,...Y_K. If there are n_n individuals in the location xn then , each of the individuals is assumed to be part of the territory tree of one or more of these observers depending on their movement trajectory pattern in the location xn. Each of the observers could be using a different code or frequency of communication to transmit the geometric co-ordinate information to the surrounding individuals in the location trajectory of each individual.

The observers are assumed to have hierarchy of creation based on their intent or purpose of observation. If there are are " K " observers in or for the location xn , then the observers are assumed to be created alongside the creation of location " xn " by the prime obser or the prime masculine that created the location " xn "

The prime observers then observers the overall outer boundary co-ordinates of the location to determine its overall shape in the three dimensional form that describe its overall volume and transmit co-ordinate information through his territory tree which could be comprised of one or more of the n_n individuals in the location xn. The frequency of communication by the prime observer would be unable to be determined by the any of the subsequent observers because his bandwidth of scale and dimension of observation is assumed to be much higher along with enough having the entire geometric dimensional information about the location xn.

Let the individual A be transmitting information the geometric dimensional information from the observer prime.

If the intent of individual A to interact with the n_n individuals in the location xn is assumed to be correlated and added up then individual A spends

tn = (T1+T2 +...+ Tn) for the following two main components :

t_int - The time distribution used for the territory intent which is used to maintain the geometric integrity of the location . This is assumed to be the deterministic component of the interaction where the geometric co-ordinates of the location are exchanged specifically the eight co-ordinates that define the outer vertices of the three dimensional geometric structure of the location xn. (Set Y that defines the overall transition state set by the prime observer)

t_other - The time distribution that is assumed to random, replaceable and mostly part of the illusion that is maintained by the perception of consciousness that creates a narrative for the movement that aligns with the intent of the individual.

Similarly each of the n_n individuals would have the same time distribution

set for transmitting geometric dimensional information based on the transition states set by their respective observers.

Where the magnitude of t_int an t_other for each of the (n_n + 1) individuals in the location xn would be different and unique. Where t_other units of time is reserved for their narrative and perception of movement that occurs in the location xn. It could also define their intent in the location xn that may or not be correlated their role in the hierarchy of information exchange as it is assumed to be a purely geometric function of information exchange from the consciousness of the individual.

In theory it could be programmed into the consciousness of the individual through perception engineering based on the purpose and intent that could be observed from T_other time distribution with various individuals.

Since T_unobserved is the total unobserved time for individual A , the narrative that is created for movement in that time is assumed to be random , iterative and dynamic that affects his current movement and interaction with various individuals in the location xn. With each change in the narrative that occurs as a result of the interaction from the other observers , the timeline of individual A changes thus altering the location in the multiverse because the dimensional information transmitted by the prime observer changes based on the narrative set by the unobserved time from the individuals that he is interacting with. The narrative that he encounters in each interaction that is assumed from the unobserved time is based on the estimated geometric dimensional information in the current transition state and he alters the information flow accordingly towards the state Y for his target state T_2.

6 Energy and Geometric association

Let there be an observer who observers the location X in discrete form at t = T_1 at various points of observation who establishes a target state set for the location at t = T_2

Suppose if there are " n " sub locations in the location " X " such as x1,x2,...,xn , then the observer could explicitly define various target states for " k " sub-locations such that the overall state at the location t = T_2 changes by changing the target state of each of the " k " locations such as

x1 defined at current observation t = T_1 by the observing masculine is defined by " k " individuals located a specific geometric pattern relative to the location . The observing masculine then defines the location " x1 " at the target observation t = T_2 by redefining the geometry in the location " x " by increasing the number of individuals to " k+1 " and establishes their new relative locations with respect to the location.

Since the observing masculine observes the location in discrete form , he observes the current locations at t = T_1 as a three dimensional image . In the three dimensional image , each of the " k " individuals in the sub-location " x1 " has their attention vector on various objects or individuals . The energy trail of their movement is determined by the attention vector of each individual and depending on the number of the things that they have their attention on . Suppose if each individual have their attention on " z1 " number of things,people or locations then the energy trail for their next location would be in " z1" different directions starting from the current position of their locations which will be reflected in the three dimensional image observed by the masculine .

Once the observing masculine determines the target state of each sub-location x1 by redefining the geometry of the sub-location at t = T_2 , the shift in the geometry will need to occur .

If the three dimensional image of the observation at t = T_1 has to shift to shift to a new geometric configuration at t = T_2 , then the shift in geometry requires energy to alter the configuration. The energy is stored in every individual that is capable of movement in the location such as the " k " individuals.

There are two kinds of energy :

Movement energy

The amount of energy that is required by any individual for his movement in any sub-location without altering the geometry in any shape or form. This would be pure mechanical energy that could be used to observe and interact with the geometry for various purposes however he could not be able to alter

the geometry in any shape or form other than displacing existing geometry that does not affect the overall external geometric boundary of the location " X " set by the masculine. This kind of energy is mostly acquired through consumption of resources such as food, water etc.

Creative potential energy

Creative potential energy that is required to alter the overall geometry itself such as creating new target states with altered geometric configurations similar to the observing masculine. This kind of energy is acquired through the transfer of energy from the prime observer who created the location " X " by alignment with his transition state Y for his intended target state at his own independently defined T_2 (his own scale and dimension) of observation . In a literal sense if the movement of one or more of the individuals aligns with his intent of the maintaining or establishing the geometric external boundary of the location similar to the masculine , then the alignment in intent occurs for the transition state and the energy from the prime observers is directed to the aligned individuals to alter the geometry.

6.1 Deceptive Energy transfer

If however the target state set by the observing masculine is not aligned then the creative potential energy has to harvested through deceptive strategy such as the following :

Suppose if an individual A has a target state T_2 set for the location x1 which is aligned with the prime observer's target state set for the overall target state set for the location " X " by the prime observer at his own scale and dimension of observation at T_2 ,

Then individual A has an amount of creative potential energy E that could be used to alter the geometry from state of observation T_1 to T_2. Suppose if there are " Z " transition states that need to occur to go from T_1 to T_2 then the transitions could be represented as follows :

Individual A observes the sub-location at T_1 .

Creates a target state for the sub-location at T_2 using the potential energy E units.

Let there be " Z " transitions that are required between the points of observation such as T_z1 , T_z2,..., T_z where the the Energy E units is diverted to each of the transition states such as :

E = E_z1 + E_z2 +...+ E_z + E_t2

Where E_t2 is the amount of energy that is reserved for the final transition that needs to occur from the transition state T_z to T_t2.

The unaligned observing masculine could harvest energy from the individual A by observing his transition states and altering the intent of the transition state. Suppose if the observing masculine could observe the transition states created by individual A and then interact and intercept before the creation of the final transition state from T_z to T_2.

Since the amount of energy that is propelling the transition from T_z to T_2 is E_t2 units of energy , the observing masculine could assemble his interacting masculines from various sub-locations connected with the sub-location x1 and interact to divert the trajectory of individual A with an amount of energy greater that E_t2 units. This would allow the observing masculine to hijack the entire target trajectory set by individual A (which is aligned with the prime observer)

The unaligned observer then alters the target state T_2 set by individual A by intercepting the intent of target state A between the final transition state between T_z to T_2. Therefore the unaligned observer then harvests the " E " units of energy that was intended for an unaligned intent set by the prime observer and then creates a new target state T_2_new for his own intent which is unaligned. Therefore the total amount of energy that was required by the observing masculine to create his own state would be E_t2 units of energy which essentially shifts the intent of an aligned individual at the final state of transition.

6.2 The interaction observers

Suppose the observing masculine observes a location X at current state T_1 in three dimensional geometric form and establishes a target state at time t = T_2.

The observation at T_1 is made in discrete form particularly in three dimensional geometric image form and then creates another geometric configuration at time t = T_2.

Creative potential energy would be required to go from T_1 to T_2 where the rearrangement of geometry needs to occur and the observing masculine could only access the energy stored in the locations through the " K " individuals in the location X.

The energy that is stored in the " K " individuals could be harvested by the observing masculine if their attention is on the observing masculine which then

establishes a two way quantum channel where information and energy could be exchanged, where the observing masculine provides the individuals with movement information that alters their movement vector field based on the desired intent of the individual and in exchange the observing masculine harvests creative potential energy from the individual as and when required particularly to later the geometric configuration in their sub-location or sub-location of origin.

The observing masculine could potentially create a mirror image of his intent in the location " X " by creating an interacting observer in various sub-locations or sub-sub-location where their specific intent of transition could be made in the respective sub-location or sub-sub locations.

The interacting masculine could be created by creating offspring with the individuals in each sub-location through various procedures that are designed and developed by repeated geometric action associations. Suppose if the observing masculine wanted to create offspring with a chosen individual , then he provides information through the quantum entanglement by ensuring that the attention of the individual is constantly on the observing masculine which enables consistent information and energy flow between the observing masculine and the individual.

Then the movement vector field of the individual is altered such that the information provided by the observing masculine is integrated into the individual thus forcing the individual to re-create the geometric actions or intent of the observing masculine in the location . This would train the interaction keys of the individual to repeat the movement and behaviour patterns of the observing masculine.

After a period of time where the individual imitates the behaviour of the observing masculine in his respective sub-location or sub-sub location , the individual then crates offspring in the sub-location with an intent to create a clone or a copy of the observing masculine to function as the interacting observer in the location. The created offspring is then aligned with the observing masculine from birth where the movement vector field of the interaction masculine is in complete control or a mirrored copy of the observing masculine who serve in the sub-location or sub-sub location as the interface that creates the movement in continuous form of the time dimension between the observed state at T_1 and established target state T_2.

The energy that is required to alter the geometric configuration for the observed state at T_1 to the target state at T_2 is then managed by the interacting observer to create movement through a hierarchy of command in the location. The interacting observer has several sub-masculine who have sever non masculine who ensure the movement of the " K " individuals in the locations in aligned towards the target state set by the observing masculine.

Suppose if the " K " individuals have their own movement vector field based on their family and territory trees which could be considered as free movement aligned with the prime observer of the location, then their movement is assumed to be a part of the transition state set by the prime observer from T_1 to T_2 from his independent scale and dimension of observation.

If the unaligned masculine observer then uses the interacting observer to alter their movement with an amount of energy E_alter units such that their movement is diverted away from the free movement and towards the movement set by the unaligned masculine observer. This changes the state of the location from state Y (set by the prime observer) to the state that is set by the unaligned observer (Y_observer) . In a literal geometric sense , the prime observer would have set the external geometric boundary of the location X by defining a set of eight geometric co-ordinates that describe its volume with which the location X must be defined . The unaligned observing masculine then alters the eight geometric co-ordinates that describe its volume with which the location X is defined through the interacting observers.

Since the interacting observer and the observing masculine are not aligned with the prime observer , the movement of the " K " individuals will need to be altered such that creative potential energy will need to be extracted from their trajectories by intercepting their transition states in one way shape or form . Then the total amount of energy that was used for creating the target state by their free movement for their target locations independently set at T_2 could be harvested by creating the altered target state T_2_new that is aligned with the transition state of the unaligned observer.

6.3 The hierarchy of the interaction observers

Suppose if there are N observing masculines for the location X with their own domain of control through their interacting observers in various sub-locations or sub-sub locations that maintain the transition in each of those locations such that the overall state set by the observing masculines could be maintained at their defined target states T_2. Since the overall target state that is defined by each observing masculine is explicitly done through defining an external geometric configuration for various sub-locations or sub-sub locations , each one of " N " observing masculines could have their overall target state at T_2 defined by explicitly defining the target state at each sub-location or sub-sub location territory of control.

Therefore each of the " N " observing masculines could have their own explicit " n " sub-locations of control where the transition state is entirely defined by the observing masculine where there is only interacting observer

There could be " s " sub-locations with shared transition states that is in alignment with various observing masculines and consequently multiple interacting observers that share energy resources from the " K " free movement individuals by their independent transition state from T_2 to T_2_new. Such locations are expected to deteriorate much faster as the alignment between the prime observer drops at a much faster rate.

Any conflict between that occurs for the transition states by multiple observers could result in an movement drag interaction until the masculine observer for the sub-location or sub-location is establishes and the individual with the highest amount of potential energy stored for that sub-location is assumed to be the masculine of that state.

Suppose if there is one prime observer , then he is assumed to be able to observer all " N " other observers and consequently with the highest amount of creative potential energy to interact in the location since he is the creator. He could have " W " interacting observers in the locations to preserve the transition states at various locations and sub-locations to preserve the target state of the location "X " . Since there is no need for the interacting observers from the prime observer to harvest energy for maintaining the transition states , their interaction could be limited to the law of law of minimum action .

Out of the " N " observing masculines in the location "X " , each of the those observers define their target state for the location " X " through various mini transition states in various sub-locations and sub-sub location of control. Since some of those of mini transition could be in alignment with the overall transition state set by the prime observer , the alignment of each observer with the prime observer could depend on the number of mini transitions states that they are observing that aligns with the prime observer.

Depending on the percentage of alignment , the amount of creative potential they control could vary and consequently create a hierarchy of control between the observing masculines. The higher the creative potential they control the lager the number of mini transition states they control in various sub-locations and sub-sub locations such that the mini transition states will align with the overall transition state set by the prime observer at his observation state set at T_2.

6.4 The identification of the past , present and future by the observing masculine.

Suppose an observing masculine observes the state of the location " X " at a time T_1 and creates a target state at the time time t = T_2. Since the observing masculine observes the initial state and target state of the location"

X " in discrete time as a three dimensional image with its external geometric boundaries , the reference for the change that needs to occur is defined by the eight geometric co-ordinates that define its volume in three dimensional form.

The target state is then defined by the observing masculine by the explicitly defining the eight geometric co-ordinates that define its volume.

The observing masculine then identifies various individuals in the three dimensional image and the energetic trails of their attention vector that describe the probability of the trajectory of the individuals in the next transition state .

The distance between the current transition state where the observation occurs at T_1 and T_2 where the target state would be undefined or unknown because the state of observation is being made in the geometric axis of time , the distance would be a set of probabilities or a variable.

Therefore the observing masculine e then creates a transition immediately after T_1 at time T_11 where the distance between (T_11 - T_1) would be near zero or negligible , this reduces the divergence in the trajectory of the individuals . Suppose if there were " z1 " energy trails for any individual when observed at T_1 , the implication would be that the individual had " z1 " people or objects or locations in the attention vector of the individuals that would drive his forward trajectory each with its own probability depending on the association of the individual with the source of the location that is driving his attention vector.

6.5 The Interaction of the observing masculine with the interacting masculine

The observing masculine interacts with the individual by identifying the source of the attention vector of various individuals and then identifying the individuals who would be aligned with his intent to create the target state" X " . The attention vector of an individual could be prone to various objects, individuals or location based on the individual's location awareness . The observing masculine could then align with those individuals by either by direct communication or by indirect communication through various means but the movement vector field of the individual would align with the individuals such that it enhances their ability to plot trajectories to the locations that drive their attention.

The process would then alter the energy the energy trail from the individual such the individuals, objects or locations that drive his attention vector are enhanced significantly and the energy trial of the individual would be enhanced along with the movement vector field of the observing masculine such that his movement towards the target location that retain his attention become faster

and more accurate. This is because the alignment of the movement vector field with observing masculine will introduce a dimension that of observation that includes the tracing of creative potential energy that is stored in each individual and the attention vector of each individual is always drawn towards the source of creative potential energy.

The desired location preference of the individual in the three dimensional geometric space is always towards the direction of higher creative energy potential energy from the location of lower creative potential energy. While on a preference scale the experience of travelling the trajectory from his current location of low creative potential energy to the next location of higher creative potential energy could vary depending on other factors such as the other metrics that are associated with the attention vector of the individual such as associated individuals, objects and locations that are aligned with the individuals.

This higher dimensional observation of energy trails that are in the surroundings are used by the observing masculine as bait to align various individuals to alter their movement trajectory to align with the masculine observer.

The reference for the time such as a past, present and the future is irrelevant for the observing masculine since he observers various transition states as three dimensional geometric boundaries. However individual in the three dimensional space that is observing the rate of change of geometry as a continuous flow will experience the past , present and future through linearity because the the directional trajectory of movement from the location of low creative potential energy to the location of higher creative potential energy will be defined by the movement vector field that defines the directional movement through a perception narrative that is correlated to the observing masculine.

The enhancement in the movement vector field that occurs for the individual that differentiates his experience of time before the upgrade in the movement vector field and after the upgrade in the movement vector field will integrated into the perception of the individual such that exact cause of the cause and effect that alters the perception will be integrated as memory that will be correlated to the decision making process of the movement vector field .

6.6 Perception of movement and frequency

The exact cause and effect that will define the movement pattern of the individual that differentiates his movement from the individuals in the surroundings is called the movement frequency of the individual. The movement frequency of the individual describes the current external boundary of his location, his location reference in the higher dimensional energy plane relative to the sources of creative potential energy that are located through the location. The movement

trajectory of the individual that describes his access to the sources of creative potential energy will either be less probable , more probable or impossible . Therefore the frequency of movement describes the interactions keys of the individual for the location that either makes it more probable or less probable to access creative potential energy.

Therefore the frequency of movement that starts in any location with the interaction with an observing masculine who then integrates their movement vector field with the individual to create the frequency of movement that will drive their trajectory towards the sources of creative potential energy. As the observing masculine interacts with various other individuals throughout the location X at various sub locations and sub-sub locations to introduce the same frequency of movement thus colonizing each location with the interaction keys for observation and interaction in each location such that their trajectory will be fast forwarded to find the source locations of creative potential energy.

However the acquired creative potential, energy from these interaction keys will be diverted to the observing masculine on a regular basis to continue to observe and interact with various other sub locations or sub sub locations to colonize those locations so he could start harvesting creative potential energy from those locations by creating interacting observers to manage the energy trail from high sources of energy to low sources of energy that is then diverted to various observing and interacting masculines to alter the external geometry boundaries of each locations.

Each frequency has an overall impact on each sub location that either increases the net overall energy in the location or reduces it . If the frequency of the interaction keys of the current transition state does not maintain the equilibrium in the sub location or the location , the overall location could have an interaction key set by the prime observer of the location to reduce or increase its overall potential energy.

The defensive interaction keys set by the prime observer could get activated by altering the movement vector fields of various territory tree individuals in various sub locations or sub-sub locations who whose trajectory will force the new interaction keys into each sub location that could have a compounding effect that ripples through out the location, consequently affecting the overall state of the location to alter its frequency according to the new interaction keys to restore the minimum amount of creative potential in each transition state for the sustainability of the location's external geometric boundaries set by the prime observer for his target state T_2.

7 Perception of Geometry

Let there be "K" individuals in a location X.

Let there be " n " sub-locations in the location X such as x1,x2,...,xn

Let there be individuals A,B and C who iteract in a sub-location x1 on a regular basis and it assumed that they do not interact in any other sub-locations. Let the individuals A, B and C be the masculines of various sub-locations who collectively share the status of their sub-locations in location x1 such that the overall states in these sub-locations could be observed to define the transition state for the overall location X.

7.1 The timeline of each individual in the location X has the following form

At time t-2

Individual is at sub- location x1

The duration of the interact at the sub-location = dt_t-2 units

the number of individuals in the sub-location = 3 (A, B and C)

At time t -1

Individual is at sub- location x2

The duration of the interact at the sub-location = dt_t-1 units

the number of individuals in the sub-location = "k_t-1"

At time t

Individual is at sub- location x3

The duration of the interact at the sub-location = dt_t units

the number of individuals in the sub-location = "k_t"

At time t + 1

Individual is at sub- location x4

The duration of the interact at the sub-location = dt_t-1 units

the number of individuals in the sub-location = "k_t+1"

At time t + 2

Individual is at sub- location x1

The duration of the interact at the sub-location = dt_t+2 units

the number of individuals in the sub-location = "k_t+1"

....

7.2 Convergence of perception

Suppose the above time distribution of various individuals at various sub-locations are cyclic in nature and at regular intervals ,the individuals A,B and C interact in the location x1 at time t-2 for a duration of dt_t-2 units and again at time t+2 and for a duration of dt_t-2units etc.

The time distribution of A,B and C converges at location " x1 " and does not intersect at any other sub-locations . There the interactions that occur at other locations including the individuals in the interactions are assumed to be random and irrelevant for the analysis.

The perception of the individuals A.B and C are assumed to intersect in the location " x1 " at regular intervals for an average duration of dT units. The perception could then be dimensionally reduced to the relative locations of each individual and the state of each locations as follows :

Individuals A, B and C could observe the state of location " x1 " in the average duration of dT units.

Let the average time duration between each interaction in the location " x1 " be defined as T units.

Let Individual have access to various sub-locations that the other individuals don't have access to such as :

Individual A interacts uniquely in locations x2,x3 and x4 and observe its state for an average interaction duration of T_a units

Individual B interacts uniquely in locations x5,x8 and x9 and observe its state

for an average interaction duration of T_b units

Individual C interacts uniquely in locations x12,x13 and x14 and observe its state for an average interaction duration of T_c units

Therefore the perception of the locations x2,x3,x4,x5,x8,x9,x12,x13 and x14 is shared in the location "x1" during the interaction of duration of dT units .

Therefore Individual A, B and C collectively share the perception of various sub-locations at regular intervals of T units where each individual shares the state of the sub-set of various locations from their time that is spent out of the sub-location " x1 ".

7.3 The Deception time component of perception

Suppose if the status of the locations that is shared in the interaction of dT units includes an element of deception then , the interaction time dT units includes an element of deception

dT = DT + dt

Where the component of the interaction DT is used for deception from the individuals where the perception of the state of the locations does not match the actual state observed by the individuals in their time distribution used for observation.

Where the component of the interaction dt is where the perception of the state of the locations match the actual state observed by the individuals in their time distribution used for observation.

Suppose if the time distribution that is used for observation of various locations by individual A,B and C could be further segmented as deceptive perception and true perception then :

T_a = D_a + Ta

T_b = D_b + Tb

T_c = D_c + Tc

Where D_a,D_b and D_c is the amount of time that is used to observe the deceptive status of various locations observed by Individuals A,B and C which could in theory be set by the masculines of those various locations. The definition of masculinity under the context would be the individual would could

identify the time distribution used for deception in the location interaction.

Individual A,B and C could report status of various locations through voluntary or involuntary deception in the time distribution of dT units in the location " x1 ". Let individual A be the masculine in the location "x1" and could identify the state of all the locations observed by Individuals A, B and C collectively.

The perceptions of the location states that is shared in the interaction at location " x1 " could then be used for defining the transition states of those various sub-locations towards the target state of the entire location " X ".

7.4 The perception of deception in location geometry

The perception in the context of defining the external geometric boundaries of various sub-locations would be defining the eight geometric co-ordinations in three dimensional space that define its volume and if the deceptive element is introduced in defining the perception then the eight geometric co-ordinates are defined inaccurately thus defining the volume of each sub-location inaccurately.

Therefore higher the proportion of deception time from each independent observations outside " x1 " (D_a,D_b and D_c) and inside " x1 " (DT) , the higher the inaccuracy in defining the current states of various sub-locations and consequently the overall location X. The higher the inaccuracy in defining the current state implies higher the inaccuracy in defining the geometric external boundaries of each sub- location and consequently defining the eight geometric co-ordinates to define the volume of each sub-location would be defined inaccurately.

Since the overall external geometric boundary for the location X is defined by eight geometric-coordinates that define its volume at the target state , the overall external geometric boundary for the location X has to be defined accurately to definite its current state to accurately define the transition state for the location X.

The external geometric boundary of each sub-location has to be defined or observed accurately to fully recognize its current state such that the variable (dynamic) transition states could be defined to meet the deterministic external geometric boundary defined for each sub-location that aligns collectively for the transition state of X.

8 Interacting observers and the trajectory

The interaction mechanics between the masculine observer and the interacting observer.

Suppose if the masculine of the territory had the authority to plant, divert or remove intent from the interacting individuals in the territory. The interacting individuals are the individuals that are capable of movement in the territory. Therefore the definition of life would be the process of movement in the territory.

The process of life movement requires the ability to absorb, store and use potential energy such that it could be used for movement that could be defined by a trajectory over a duration of time in the boundary.

The masculine by definition would have control over all the trajectories in the territory. This is because the structural integrity of any location is maintained by the prime observer by the defining the geometric external boundaries specifically the eight geometric co-ordinates that define the volume of the territory.

Suppose the observing masculine of any territory defines a target state for the location X at a point of time t = T_2 , this means that the volume of the location X is defined by the eight geometric-coordinates that describe its geometric structure , this consequently means that the eight geometric co-ordinates that define the volume of each of the " n " sub-locations of the location X.

At each point of observation made by the masculine the current states defines the volumes and the eight geometric-coordinates of the each of the sub-locations and the Euclidean distance between the geometric-coordinates from the current state to the target state of each sub-location is calculated and the next transition state is estimated such that the number of transition states from the current state to the target state is minimized.

Every individual in the territory or location X is created has a purpose to either alter, maintain the external geometric co-ordinates of the sub-location or sub-sub location in the location X.

Let there are " K " observers including the prime observer in the location X , then there could be " N " individuals in the location X who could be carrying intents from the " K "observers for the external geometric co-ordinates of the sub-location or the sub-sub location of their trajectories.

If there are conflicting intents for the eight geometric coordinates then the authority structure of the observing masculines is applied based on their hierarchy of creation in this case which would be the prime observer.

Suppose if the prime observer only observes certain sub-locations or the sub-sub

locations that are the critical points (geometric boundaries) for the transition state such the minimization of number of transition occurs towards the target state , then these transition states becomes absolute.

8.1 The interaction mechanics between the prime observer and the sub-masculine observers

Suppose if an interacting observer " A " enters a sub-location " x1 " and follows a trajectory through various sub-sub-locations x_1 , x_2 ,....,x_n of the form :

At t = 0

The interacting observer enters the sub-location " x1 " at x_1

The interacting observer interacts with " k1 " individuals in the sub-location x_1 for a duration of dt1 units

The interacting observer has a set of " K1 " possibilities for his next trajectory in the sub-location based on his observation of the " k1 " individuals .

The interacting observer chooses his next destination from the set K1 = (x_1,x_2,....,xn) based on his intent.

At t = t + dt1

The interacting observer enters the sub-location x_2

The interacting observer interacts with " k2 " individuals in the sub-location x_2 for a duration of dt2 units

The interacting observer has a set of " K2 " possibilities for his next trajectory in the sub-location based on his observation of the " k2 " individuals .

The interacting observer chooses his next destination from the set K2 = (x_1,x_2,....,x_n) based on his intent.

.....

8.2 Defining the forecasting ability of the observers

At each sub-sub-location , there are (k + 1) individuals who follow similar trajectories in the sub-location however each interacting observer chooses his

trajectory based on approximation of " K " possibilities from his observation of the sub-location where the remaining " k " interacting observers are interacting.

Each interacting observer observers the trajectory of the other " k " interacting observers specifically the unobserved time of the other interacting observers.

Suppose if individual A interaction at each sub-sub location could be discretized as follows :

Let " k1 " = 2

Therefore there are three interacting observers in the sub-sub location " x_1 " individual A , individual B and individual C.

Let there be a total of D_total dimensions of information that describes the sub-sub location x_1. Since each interacting observer is observing and interacting in the sub-sub location each individual is assumed to be observing and interacting with various dimensions of information .

Let Individual A could observe and interact with D_a dimensions of information in the location x_1 .

Let Individual B could observe an interact with D_b dimensions of information in the location x_1 .

Let Individual C could observe and interact with D_c dimensions of information in the location x_1 .

The dimensions of information are assumed to be a independent complete set D_a, D_b and D_c and may or may not intersect between each other.

The prime observer could observe and interact with all the dimensions of information D_total of the location x_1.

The masculine observer in the interaction at the location x_1 is defined by the number of dimensions of information that they could observe and interact with specifically the individual could observe the complete dimensions of information that the other individuals are observing and interacting with.

Suppose if individual A is the masculine observer in the interaction at "x_1" then D_b and D_c would be a sub set of D_a. This means that individual A could observe and interact with everything individual B and C could observe independently or collectively observe. If individual A could identify the movement trajectory of Individual B and C by identifying the objects, individuals or locations that is associated with their movement then their intent could be observed by identifying the origin of their movement trajectory. If the origin of

the movement trajectory could be determined then the target trajectory could be determined .

If the origin location of any individual's trajectory could be identified along with his target location , there could be " Z " possible trajectories the individual could take between the origin location and the target location.

Specifically in the sub location x1 , if the entry sub-sub location of the individual is known (x_1 for individual A) and his exit sub-sub location is approximated to be x_7 (based on his target location after exiting the sub-location x1) , then the trajectory of individual A could take the following form :

8.2.1 Individual A's trajectory in the sub-location x1

Observed entry sub-sub location - x_1

Estimated exist sub-sub location - x_7 with a probability Pa_1

The number of trajectories possible between x_1 and x_7 - Za_1

Estimated exist sub-sub location - x_4 with a probability Pa_2

The number of trajectories possible between x_1 and x_4 - Za_2

8.2.2 Individual B's trajectory in the sub-location x1

Observed entry sub-sub location - x_6

Estimated exist sub-sub location - x_3 with a probability Pb_1

The number of trajectories possible between x_6 and x_3 - Zb_1

Estimated exist sub-sub location - x_9 with a probability Pb_2

The number of trajectories possible between x_6 and x_9 - Zb_2

8.2.3 Defining the observing masculine

Therefore the masculine in the sub-sub location would be individual A if he could observe Pa_1,Pa_2,Pb_1,Pb_2,Pc_1,Pc_2,Za_1,Za_2,Zb_1,Zb_2,Zc_1 and Zc_2 thus

providing all the movement information in the interaction at the sub location x1.

However individual B and C may not be able to observe the entire set as individual A but could observe their movement in its entirety by default , and partial information about the movement of individual A or each other represented by the variables Z and P.

9 The Mechanism of the observers

The difference between the interacting observer and the masculine observers is the perception of the geometric information in the surroundings.

Suppose if the masculine observers observes location states as a three dimensional geometric structures in discrete form then , the their definition of time would shift from one point of observation to the next point of observation.

If a location " X " was observed by a masculine observer at state t = T1 , the state is defined by the exact locations of various individuals in the three dimensional image of the location and consequently the number of attention vectors that is attached to each interacting individual (observer) in the location.

If any observed state of the location at time t = T1 is observed , then if there are " N " interacting observers in the location , and each interacting observer has an average of three attention vectors attached to each interacting observer , then there are approximately N*3 possible states for the next point of observation by the masculine observer.

Since the masculine observer has no concept of linear time as oppose to the interacting observer in the location X who perceives linear time, the masculine observer would need various reference points of information for the next state the trajectory of the location is likely heading towards.

9.1 Masculine Interacting Observer

Let there be one interacting observer in the location X , and he would be the masculine of the territory if he could observe the entire N*3 attention vectors of all interacting observers in the location X and thus could establish the desired target state of the location X .

The attention vectors of each interacting observer would be redirected accordingly . If the probable next location of each interacting observer is defined by the magnitude of the attention that the interacting observer has on various locations , then his trajectory could be intercepted or redirected by the interacting masculine observer because his trajectory would be created considering all the possible trajectories that each interacting observer could take.

Suppose the masculine observers could observe the state of the location X in discrete form , then he could observe all the probable trajectories that are likely to occur and this could be used as forecasting information which will be fully integrated into the movement vector field of the interacting observers. This

would allow them to plot their trajectories through natural instinct in linear time such that their movement in the location would establish the next desired next state by superposing the attention vectors of all interacting observers into his trajectory.

9.2 The functioning of the masculine observer

The masculine observers could only observe the attention vectors of all the interacting observers experiencing linear time as an instantaneous state , therefore for any given instant of time , there are " N * 3 " possible states that could occur starting from his current state of observation.

The trajectories could be forecasted by the observing masculine by assuming one of the states where the exact attention vector from each individual has to be assumed for the forecasting the probable next state of transition. Since the observing masculines could only predict the three dimensional image of the location X , the effect of that chosen state for forecasting could be observed as an three dimensional image of the assumed state (defined by the initial conditions for forecasting which would the most probable attention vector from each interacting observer for his next location).

Suppose if the observing masculine could forecast the overall state of the location X based on various permutations and combinations of attention vectors from each interacting observer , the best probable state for the trajectory for his interacting observer could be determined for his target state of the location X.

9.3 The State Change process

The masculine interacting observer defines the overall state of the location " X " specifically the external geometric structure of the location " X " defined by eight geometric co-ordinates that define its overall structure and volume " V "

Let the location "X" has " n " sub-locations X1,X2,... that has its own geometric structure defined by its eight geometric co-ordinates with volume V1,V2 etc.

To define the overall state of the location " X " , the masculine interacting observer has to define the geometric structure of one or more geometric structures of various sub-locations X1,X2 etc.

9.4 The transition of one target state to another

Suppose if the location " X " has a defined geometric structure by one or more interacting observers by defining their respective overall geometric structures at various sub-locations , then let this state be defined as " P "

Let there be a masculine interacting observer who observes the state of the location " X " at time t = T1

The interacting observer then defines a new state " Q " for the location " X " , the overall geometric structure for the location " X " would be different along with the various sub-locations whose volume would change to V1_new, V2_new etc.

The transition state of the state " P " is assumed to have kinetic energy that could be represented as a timeflow that altered the movement vector field of the various individuals in the location " X " through their movement in various sub-locations X1,X2,... etc.

When the interruption of the state " P " is changed to " Q " by the authority in the territory ,the kinetic energy from transitioning state will be redirected to the masculine interacting observer and affect his trajectory by creating movement drag.

Suppose if the movement trajectory of the individual is defined by the location and time metrics , then it takes the form:

At time t = o

Interacting masculine observer is at sub- location X1 for a duration of dt1 units

The number of individuals interacting with the interacting masculine observer = k1

At time t = t + dt1

Interacting masculine observer is at sub- location X2 for a duration of dt2 units

The number of individuals interacting with the interacting masculine observer = k2

....

9.5 Creation of movement drag from the state change

The kinetic energy from the timeflow affects his time distribution dt1,dt2 units etc thus affecting his interactions with various individuals such as k1,k2 etc. This creates movement drag in his trajectory that creates an offset for his time distribution by introducing a variable delta dt1 , delta dt2 etc that interacting masculine observer requires to interact with individuals k1,k2 etc while in some causes preventing interactions or altering durations of interactions. As a consequence the original intended trajectory X1,X2,... could change thus forcing the diversion of his target state " Q " that had been set.

Let the kinetic energy that that was stabilizing the state " P " be defined as " K " , The kinetic energy is diverted to create movement drag for the interacting observer masculine , however if his trajectory is not altered sufficiently to divert the transition to state " Q " , then the interacting observers will use their stored potential energy to create more timeflows to create movement drag for his trajectory at various sub-locations of his interactions either until they no longer have access to his sub-locations in his trajectory or they run out of stored potential energy. At which point the timelines of the interacting observers and the masculine interacting observer will separate thus relocating them according to the new state " Q " set by the masculine interacting observer.

9.6 The Relocation of State

The relocation occurs as a result of the total time T units and energy E they had used to alter the trajectory of the masculine interacting observer that was used to maintain the state " P " of the location " X ". As a result of the time and energy loss from various interacting observers from the location " X " , their interactions specifically their defined trajectory metrics such as :

The intended duration of time of state " P " at each sub-location dt1,dt2 etc would be altered

The intended individuals for interactions k1,k2,etc at each sub-location would be altered.

The intended location trajectory of state " P ' X1,X2 etc would be altered

The new altered trajectory of the interacting observers will be defined according to the new state " Q " set by the interacting masculine observer for the transition.

10 The mechanics of state separation of the interacting observers

Let there be a location " X " with " N " sub-locations and " n " sub-sub locations. Let the location X be defined with Dn dimensions of geometric information specifically each dimension hold the eight geometric co-ordinates of each sub-sub location.

10.1 Prime observer

Let there be a prime observer who created the location " X " and interacts at various points of observation at t = T1,T2 etc. The points of observations are made in discrete form completely defined by the geometric configuration of the location . The prime observer could observe the location at each points of observation as a three dimensional image then the external geometric boundary of the location is defined by eight geometric co-ordinates that define the volume of the location X.

Therefore the prime observer defines the points of observation T1,T2 etc. through the geometric configuration . Suppose if the geometric configuration is made at time T1 and the location X has a specific geometric configuration that is defined by eight geometric co-ordinates that define its volume then , each one of the " n " sub-locations could be isolated and defined under the same format.

Since the observer prime created the location X , he could choose to alter various sub-sub locations by redefining it at various sub-sub locations depending on the state of the location X that he would prefer to define it. Suppose if the state of the location X could be generalized as follows :

State 1) The overall volume of the location X expands over the increased time of observation.

State 2) The overall volume of the location X remains constant over the increased time of observation.

State 3) The overall volume of the location X reduces over the increased time of observation.

By definition the prime observer could observe all the geometric information D1,...,Dn in the location X specifically about each of the sub-sub-locations that2 is collectively defining the location X. Suppose if the prime observer only chooses to observe and interact with the transition T2 such that the external geometric boundary starts to constrict therefore reducing the volume of the location X.

Therefore by definition the prime observer observes the location X during the State 1 and State 2 but chooses to interact when the state of the location X changes to state 3 .

The interaction of the prime observer occurs by changing the external geometric co-ordinates of one or more of the sub-sub locations for the target state of observation at T2. If the prime observer observes the state of the location X at time T1 and then decides to observe the altered state of the location at time T2 then , he could observe the sub-sub locations that could generate the maximum amount of creative potential energy for the change of state.

If the state has to be changed to increase the volume of the territory , then the sub-sub locations that could channel the creative potential could be diverted to expand the territory.

If the state has to be changed to stabilize the volume of the territory , then the sub-sub locations that is channeling the creative potential energy to expand or reduce the territory must be halted or redirected within the location X.

If the state has to be changed to decrease the volume of the territory , then energy must be extracted from various sub-sub locations that will be excluded from the total volume of the new geometric boundary of location X.

10.2 The observers

Suppose if there are " K " for the location X who choose to observe and interact with the location X based on their definition of states.

If the prime observer only has three states then the transition state set by the prime observer between his modes of observation (between T1 and T2) could be of the following forms :

1. State 1 to State 2

2. State 2 to State 3

3. State 3 to State 2

4. State 2 to State 1

Let there be " Z " state possibilities for the location X other than the transition states set by the prime observer. The " K " observers could set any of the states for mode of observation that could be a combination of one or more of the above four states.

The hierarchy of the observers is defined by the number of dimensions that they could observe in the location X.

Suppose if there are three observers A , B and C then observer A is assumed to be the masculine if and only if he could observe the entire trajectory of individual B and C independently or collectively during their modes of observation.

10.3 The interacting observers

Suppose if observer A , observer B and observe C interact in the location X through an interacting observer with whom they have merged their movement vector field with such that they function as a mirrored copy of the observer in various locations and sub-locations. The interacting observers follow movement between the transition state set by each observer between T1 (their current observation where they choose their transition state for their next defined transition state) at their next expected time of observation at T2.

Let the interacting observers A,B and C interact with various sub-locations and sub-sub locations as part of their territory. Suppose if the observers A, B and C define their own states for the location X , which could be Za, Zb and Zc respectively then this means that that they are defining the external geometric co-ordinates of various sub-locations or sub-sub locations that they are interacting with.

Suppose if there are " Q " intersecting sub-locations and sub-sub locations where the observers have defined various states observers have defined various states as part of their larger state defined for the location X through Za, Zb and Zc then the target state set by each individual A would have three different geometric external co-ordinates for the Q locations.

The external geometric co-ordinates set by the observing masculines for the Q locations will be determined by the masculine observer. This is because the masculine observer could observe the movement trajectory of the interacting observer in its entirety and could intercept their interaction in the locations to having any inpact to the external geometric co-ordinates by the intersecting masculine observer.

10.4 The consequences of interaction

Let the target state of the " Q " has been set by individual A as a result of his authority in the territory that is defined bu his ability to observe and in-

teract with all the dimensions of the location" X " that individual B and C. The actions of the interacting observers A,B and C are defined with their movement vector field that is merged with their corresponding observers A , B and C.

Since the observes A, B and C define the transition state in discrete time form specifically by defining the external geometric configuration of the sub-sub locations between the current and the target state , the interacting observers A,B and C experience the trajectory of the transition state from the current state to the target state in continuous form of the time dimension.

The observer A observes the state of location X and identifies the current state of the sub-location x1 at T1 and defines a new target state for the sub-location at T2. The interacting observer whose movement vector field has merged with the masculine observer will enter the location X through the entry sub-location X1 , specifically the sub-sub location x1.

Let the trajectory of the individual A be of the form in continuous form of the time dimension for the transient state between the discrete states T1 and T2 set by the observer A.

Let the time duration between the discrete transient states T1 and T2 be defined as T units of continuous time as experienced by the interacting observer.

At t = 0

individual A enters the sub-sub location x1

individual A spends a duration of time dt1 units in the sub-sub location x1

individual A interacts with "k1" individuals in the sub-sub location x1
individual A observers " n -1 " sub-sub locations from the "k1 " individuals for his intent to alter the state from T1 to T2 and chooses his next sub-sub location x2.

At t = t+dt1

individual A enters the sub-sub location x2

individual A spends a duration of time dt2units in the sub-sub location x2

individual A interacts with "k2individuals in the sub-sub location x1

individual A observers " n -1 " sub-sub locations from the "k2" individuals for his intent to alter the state from T1 to T2 and chooses his next sub-sub location x3
.....

At time t = T-dtn

individual A enters the sub-sub location xn

individual A spends a duration of time dtnunits in the sub-sub location xn

individual A interacts with "kn individuals in the sub-sub location xn

individual A observers " n -1 " sub-sub locations from the "kn" individuals for his intent to alter the state from T1 to T2 and chooses his next location outside the sub-location X1.

Therefore the interacting observer completes his transition state cycle for the transient state change from the T1 to T2 for sub-location X1.

Suppose if the interacting observers B and C would choose to interfere with the transition state of the interacting observer then they would have to predict the following metrics of the interacting observer A:

The subsub-locations that are part of his trajectory

The amount of time spent in each sub-locations

The individuals " k " that interacts with individual A

the " n-1 " possible locations for his next destination at the each of each sub sub location

the most probable sub sub location that would be chosen by individual for his next destination

If the individuals B and C observe the trajectory of individual A for a duration of D units in the sub-location X1 after which they could predict the above variables, then could engineer a situation such that they could intercept his trajectory at a sub-sub location and intercept with the interaction of " dt " units and alter the duration of the interaction such that it changes to " dt + " delta dt " , thus altering the number of sub-locations for his next destination which increases the probability of altering his trajectory from his intended destination. This is because the additional time that is introduced " delta dt " will divert the attention of individual A from his intent of observing his required location to the locations that are engineered by individuals B and C. The engineered interaction could use perception and deception engineering to create the umbrella illusion of his desired intent but the purpose of the redirection would be to divert his trajectory such that the transient state that establishes the change of state from T1 to T2 is altered or diverted or stopped. This occurs

by varying the time distribution T units of continuous time intended for the transition by the interacting observer.

10.5 The Mechanics of the interruption

Suppose if the interacting individuals B and C have their own similar transient states set up by the observers B and C for the sub-location X1 that was expected to last a duration of T_b units and T_c units in continuous time. Then to intercept the trajectory of the interaction individual A , an amount of time and energy would have to be directed from their own transition trajectories in the sub-location to engineer the transition redirection for individual A.

Suppose the masculine observer A has the highest amount of potential energy then the trajectory set for the interacting observer would also have the highest amount of kinetic energy.

Let the trajectory of individual A have a total amount of kinetic and potential energy = E_a

Let the trajectory of individual B have a total amount of kinetic and potential energy = E_b

Let the trajectory of individual C have a total amount of kinetic and potential energy = E_c

Let t_b be the amount of time of that is used from their transition trajectories to engineer the interruption by the interacting observer B.

Let t_c be the amount of time of that is used from their transition trajectories to engineer the interruption by the interacting observer C.

Let e_b be the total amount of energy that is spent to engineer the situation for individual A by individual B

Let e_c be the total amount of energy that is spent to engineer the situation for individual A by individual C

Therefore the metrics for the trajectory of individual B and C changes to the following :

The total transition time for the state set by observer B changes to T_b + t_b

The total transition time for the state set by observer B changes to T_c +

t_c

The total amount of energy stored for the transition reduces to E_b - e_b

The total amount of energy stored for the transition reduces to E_c - e_c

If the interruption is successful then , the transition state from individual A is halted and the difference in time and energy does not affect the relationship between the observer and the interacting observer.

However if the interruption fails then the transition state set by observer A will continue to occur during their time period of interruption t_b and t_c for the interrupting observer B and C respectively. The interruption occurs through the divergence of the location trajectory where the interacting individuals B and C will divert away from their intended sub-sub locations and follow the trajectory of the interacting observer set by the observing masculine A. Thus diverting the energy e_b + e_c to the total energy of the trajectory of individual A. Thus the total energy for the trajectory of individual A increases from E_a to (E_a + e_b + e_ c).

Therefore the interrupting individuals B and C would have a traveled a trajectory of various sub-sub locations for a duration of time that is divergent from their original transition trajectory. Since the transition states are no longer possible the transient trajectory of individual B and C will restart in the transition state set by the masculine observer. Therefore the trajectory of the interacting observers is restarts in the sub-sub location with energy E_b - e_b and E_c -e_c for their movement.

If however the magnitude of the difference E_b - e_b and E_c - e_c reduces to near zero as a result of high magnitude of the time spent t_a and t_b to intercept the trajectory of individual A then their movement would be severaly restricted by defined by their available energy. The observing masculine would then diverge away from the interacting observer as a result of the inability of the interacting individuals B and C to complete the transition required for his pre-defined state. Therefore the trajectory of the transition that had been set by the observing masculine no longer applies as a result of trajectory divergence from their respective origins.

Consequently the movement vector field that had been entangled between the observing masculine and the interacting masculine would break.

11 Consciousness Attention mapping

11.1 Higher order geometric definition of the attention vector of consciousness

The attention vector of an individual could be as the ability of the consciousness to observe the surroundings and determine the locations of various objects,locations or individuals of interest relative to its current location. The consciousness of any individual is designed to observe the location information in the surroundings and identify the various locations that is driving its movement from one location to the other .

The movement of consciousness is defined as the changing the state of observation from one state to another by relocating itself relative to the locations of interest. The locations of interest for any individual consciousness is to identify the sources of energy and the change of state implies relocating relative to the sources of energy such that the energy could be harvested by interacting with the sources of energy.

The attention vector of the individual could be defined as the ability of consciousness to use potential energy to observe the relative locations transitions that are occurring in the surroundings and then plotting a trajectory to the new state where energy could be harvested for its forward trajectory. Suppose the attention vector of the consciousness could serve to observe the various relative movement in the surroundings by identifying the masculine movement in the surroundings.

Since the attention vector of all individual consciousness could have the same geometric function , the movement of all the various consciousness could be occurring where each individual consciousness could altering its state along its trajectory relative to the sources of energy.

Suppose if the attention vector of any individual is a function of its intent mass then the ability to observe its surroundings is defined by its ability to create a curvature or an area within which it could interact . The curvature serves to differentiate the area between the surroundings such that it could identify the various transition movements that are occurring in the area of its attention (gravitational) influence.

The intent of consciousness then defines its ability to align with various other individual consciousness under a unified conscious intent to observe the sources of energy in its gravitational attention field and alter the trajectory of its movement relative to the sources of energy such that it could absorb the energy by interacting with it for its forwards trajectory.

Therefore the attention vector of any individual consciousness could be a func-

tion of various geometric functions such as :

Intent mass

The number of individual consciousness that have independently aligned with the prime individual consciousness of varying capacities that could observe various scales and dimensions of relative movement in the surroundings. Higher the accumulation , the higher the mass.

Radius of consciousness

The surrounding area that is affected by its intent mass where it could be isolated and the relative movement of any other individual consciousness could be observed under the influence of its own intent mass.

At each transition the individual consciousness shifts its location relative to the sources of energy in the attention field of its consciousness. The individual consciousness identifies the sources of energy by observation , alters its location relative to the sources of energy identified and then re-observes its surroundings from the new location and the process continues. The process could continue indefinitely until the individual consciousness can longer identify sources of energy in its gravitational attention field at which point there would no location identified to make the state or location transition. The trajectory of the consciousness is then interrupted because there would no sources of energy for the attention vector of the consciousness to create the energetic trail towards for its forward trajectory at which point the consciousness becomes static rather than dynamic.

11.2 Individual consciousness (Lower intent mass)

Let there be an individual consciousness A is observing a location " X " then the location X is part of the gravitational attention vector field of the observing consciousness.

Let there be " P " individuals in the location X and for the observing individual consciousness A to exist in the location X or conversely for location " X " to exist in the attention gravitational field of observer A , there must be " Q " individuals who have their attention vector on the consciousness of individual A which provides the source of energy for individual A to observe and interact with the location " X " through the " Q " individuals.

The only exception would the prime observer who is assumed to have created the location X within his attention gravitational field using various sources of energy and without the prime observer , the location X would not exist. The

prime observer is also assumed to be his own source of energy and his movement does not depend on identifying other sources of energy however his conscious intent would function as the inverse where his location would energy for the movement of various other individual consciousness.

A typical example would be the sun which would be the prime observer in the solar system which provides energy to various other individual consciousness (with higher intent mass) for their trajectories such as the Earth and eventually Mars and beyond.

Suppose if there are " K " observers in the location " X " then there must be a percentage of time from the " P " individuals that is being used to divert energy through their attention to the " K " observers. The diversion of energy could occur in various forms where the " P " individuals could come in contact with objects, individuals or locations that are associated with one or more of the " K " observers where attention is directed towards then directly or to the various states of locations or sub-locations that they have created that is being utilised by one or more of the " P " individuals through their time distribution.

11.3 Engineering the trajectory of the energy source

Suppose if an individual consciousness is following his trajectory towards sources of energy and the trajectory that is chosen depends on the intent of the individual consciousness specifically the geometrical methods that he chooses to extract energy from the energy sources in the surroundings.

Specifically if the individual consciousness intercepts the trajectory of the energy source which could be various other individual consciousness then the interception could be of two kinds.

The individual consciousness could either observe the trajectory of the individual consciousness which would be the energy source and interact to maintain the trajectory of the energy source while altering its trajectory to maintain the balance of both trajectories that are being created by the change of states or locations of both consciousness.

or

The individual consciousness could observe the trajectory of the individual consciousness which would be the energy source and interact to alter the trajectory of the energy source while collaborating with various other individual consciousness to alter the trajectory of the energy source to be create a circular repetitive patterns around the various other energy absorbing individual consciousness thus diverting the trajectory of the destination of the energy source towards its

intended location in its transition of location states.

This process alters the orbital trajectory of the individual consciousness that has intent mass explicitly to create locations where more individual consciousness could be created with various scales and dimensions such that more dimensions of observations could be created such that interactions could continue eventually to create more individual consciousness with more unique dimensions of observation.

12 The dance of the prime observers

Let there be a location " X " created by the prime observer at t = T1. The location X has a three dimensional geometric form with volume " V " and eight geometrical co-coordinates that describe the outer edges of the location X.

By definition the observers could observe time in discrete form and they are assumed to exist outside the location " X " and cannot interact with the location " X ".

The prime observer creates another three dimensional geometric form with volume " V_new " for t = T2 defined by new eight geometrical co-coordinates that describe the outer edges of the location X.

Let the location X be divided under " n " sub-location.

Let the prime Observer create " K " observers to observe various dimensions of each sub-location for the transition to occur at t = T2 and the observers observes the change in the geometric configuration in each sub-location such that the transition of the overall location X at t = T2 could occur.

12.1 Geometrical communication by the observers

Let there be an Observer O_1 in the location " X " who observers and interacts with various sub-locations x1,x2,x3 etc. such that the transition state that is set by the prime observe at time t = T2 occurs.

Since the observers cannot interact with the locations or the sub-locations directly , they alter the perception of various other observers such that attention energy is diverted from their consciousness towards various dimensions of geometry in the sub-location.

The observer O_1 observes the surroundings of the sub-location specifically the external geometric boundary and the other observers who are diverting their attention to the sub-locations.

Since the observers interact in the sub-location by observing the relative movement of attention energy from various observers to other observers relative to the overall external geometric structure of the sub-location.

The relative movement of attention energy that is being diverted from the prime observer to observe the various sub-locations creates a geometrical pattern that takes shape in the form of geometry.

Suppose if the attention energy from the prime observer is directed towards the observer O_1 and the relative change in the external geometric structure of the location X is observed , this could create a geometrical patterns of the following form :

The prime source (from the prime observer) of attention energy is directed to the observer O_1 - The relative change in the overall change in the external change in geometric structure is observed by the prime observer.

The observer O_1 directs attention energy to observe various observers O_2,O_3 and observers the relative change in the external change in geometric structure of sub-locations x1,x2,x3 is observed.

The observer O_2 directs attention energy to observe various observers O_3,O_4 and observers the relative change in the external change in geometric structure of sub-locations x7,x2,x3 is observed.

.....

Therefore the sequential flow of attention energy from a singular point or the prime source of energy (prime observer) could be represented in geometrical form such as :

Point O - origin - attention energy is diverted into three observers O_alpha , O_beta and O_omega. Geometrically this could be represented as three lines drawn from a single point to three different points.

The change in the geometrical structure of the overall location " X " could be observed by varying the amount of energy that is being diverted to the three points . Suppose if each observer that is created with specific geometric dimensional information to observe , then the purpose of the three observers could be as follows :

O_alpha is created in any location that could observe the surrounding observers created. Suppose if there are " M " possible locations for the location for the O_alpha to observe the relative locations of other observers , then the location of O_alpha is chosen by interaction with the observer O_beta. The location of the O_beta is variable such that he interacts with all possible locations of O_alpha assuming their presence in their locations and then identifies the locations for the O_alpha such that the external geometric structure is stabilized according to the target state set by the prime observer.

The rotational observation of the overall geometric structure is observed by the observer O_omega who observers the overall change in the overall geometric structure by diverting his attention towards O_alpha and O_beta proportionally.

Since the Observer O_beta assumes the location of the observers O_alpha and interacts with them by diverting attention to various possible (probable multiverses) locations of O_alpha , the forward trajectories (geometric locations) for the observer O_alpha could be made deterministic based on the overall expected geometric location of the overall location X. The observer omega is then created to remove attention energy to all the variations observers of O_alpha that were created during the interaction process which stabilizes the trajectory of the observers towards the target state for the location X.

12.2 The hierarchical creation of observers

Similarly O_alpha , O_beta and O_omega could divert attention energy to various other others observers such as O_1,O_2,...etc. The other observers are assumed to be created to observe a specific geometric boundary within the location X . Since the interaction of any observer is to observe the external geometric configuration of the defined boundary of X , the observer observes the attention energy from all the observers that are diverting their attention energy to the defined boundary of geometric territory.

The relative change in the geometric external boundary by altering the amount of attention to various observers who are diverting the attention to the defined boundary could allow the observer to identify the transition state the defined geometric boundary is currently ongoing towards the target state set by the masculine observer observing the boundary.

Since the creation of observers occurs hierarchically starting from the observer prime to the observer O_alpha,O_beta and O_omega to the continually ongoing process of creating more observers O_1,O_2,... etc , every new generational hierarchy of the observer is created to observe a specific geometric boundary that is defined by external co-ordinates that define its overall shape and all the observers who are diverting attention to the specific territory.

The masculine observers by default would be the O_alpha , O_beta and O_omega observers who observe the interaction of all the observers and the relative change to the overall external geometric boundary in any sub-location.

12.3 The dimensional information set

Suppose if the location X has " Z " geometric dimensions in total that describe all the information about the location " X " then it could be represented as D1,...,Dz. The information set could be assumed to have all the information about the location including the observers O_alpha , O_beta and O_omega which

is observable by the observer prime.

The observers O_alpha , O_beta and O_omega could be assumed to all the dimensions of information except the transition state from which the observer prime arises that creates the location X. This is because the observers O_alpha , O_beta and O_omega are created at the target state along with the location X.

As the process of creating observers continues the number of dimensions of information that each observer could observe and interact with reduces or branched off into various sub-segments of dimensional information.

Therefore the number of scales and dimensions of information that any observer could observe and interact with is hierarchical and the closer the rank of creation to the prime observer , the higher the amount of information that they could observe and interact with along with amount of attention energy they possess that could be used to observe those dimensions of information.

12.4 Perception and the continuous flow of attention energy

The transition state of the overall location " X " is therefore the geometric continuity that of information that occurs sequentially from the prime observer to the rest of the observers. Suppose if each of the observers are receiving attention energy from the preceding observers and each observer therefore is consequently diverting attention energy to various other observers , then each observer is likely to form a complex intersection node of attention energy that is being absorbed and re-directed that are interconnected to every other observer in the location X. This interconnected network of attention energy that is observing each observers is directly proportional to the dimensions of geometric information that they could observe and could represented through geometric connectivity.

Suppose of one higher order observer could observe a lower order observer and the vice versa in not true , then a geometric line could exist from the higher order observer to the lower order observer while the vice versa is not true . This creates geometric discontinuity in the dimensions of information that each observe could observe and each observer in the location is assumed to have continuity and discontinuity to observe various dimensions of geometric information along with observer information.

Therefore the continuity and discontinuity of information that arises from their ability to observe only certain dimensions of information based on the amount of attention energy they possess results in the perception of the observers.

The perception of every observer is therefore the amount of information they could observe through the scale and dimensions of information they could divert their attention energy towards thus establishing a correlation between the geometric external boundary (shape) of any territory and attention that is being diverted to the territory from the observers in the territory.

Therefore the purpose of perception is to identify the effect of attention energy from each observer identified in the location to the relative change in the external geometric shape that is occurring as a result of the diversion of attention energy from the observers in the location towards various other observers.

If there was any change to the geometric external boundary will need to be made by any masculine observer , he uses his perception to perform the following functions :

1. Observe the external geometric boundary of the territory

2. Observe the number of observers diverting their attention to the external geometric boundary.

3. Observe the observers creating more observers in the external geometric boundary and determine the transition state

4. Observe the transition state by observing the effect of their created observers in the external geometric boundary (the shape is assumed to change)

5. Once the transition state is identified then the expected target state (shape) of the external geometric boundary is identified.

6. Identify the observers to intercept and alter their diversion of attention energy to various other observers that would disrupt the current transition state.

7. Establish the new target state for the external geometric boundary (new expected shape)

8. Create observers to observe various territories in the location X to create transition states towards the target state

9. Identify other observers that are effecting the transition of the territory and divert their attention away from the transition state

13 The interacting observers and the energy distribution from the prime observer

Let there be a prime observer that creates a location " X " with D_prime dimensions of geometrical information that he could observe and interact with.

Let the initial state of the location X be defined at T = 0 and the external geometric boundary of the location have a volume " V " that is defined by eight geometrical co-ordinates that define its outer most edges relative to the location of the prime observer.

Let the prime observer create a target state of the location " X " by defining a new volume " V_new " with new edges defined relative the location of the observer.

Let the prime observer create three masculine observers Alpha, Beta and Omega with D_alpha , D_beta and D_omega dimensions of information that they could observe and interact with. The purpose of the masculine observers is to observe and interact with the location " X " such that the transition occurs.

Therefore the process of interacting with the location " X " by the prime observer is to create more observers. Consequently the process of interacting by the created observers Alpha,Beta and Omega is to create more observer either individually or collectively.

The dimensions of information that Alpha, Beta and Omega could observe and interact with (D_alpha, D_beta , D_omega) is assumed to be lesser or equal to the D_prime dimensions of the location " X " because it includes all the information there is to know about location X including other observers. The only piece of information that the set of information D_prime does not have is the origin state of the prime observer.

The creation of the location " X " that is created from scratch from a state that could not be observed by the D_prime dimensions of information and it is assumed to be subset of information from a state that precedes it.

Therefore the masculine observers could discretize the location " X " through various dimensions of geometrical information and create " n " sub-locations in the location " X " . The three observers then observe and interact with various sub-locations by create more observers.

The masculine observers then create more observers O_1,O_2,.... (with D_1,D_2, D_3 dimensions of information that they could observe and interact with) in various sub-locations through the location" X " that continue the process by dividing the various sub-locations into sub-sub locations and creating more ob-

servers and so on . The process continues to ensure that the transition process could continue to the target state set by the prime observer.

Therefore each observer that is created hierarchically could only observe and interact with only a subset of geometrical information that is defined by their creators based on their purpose of creation. Specifically the observers are created to observe various sub-locations or sub-sub locations within the location " X ". The limits of the dimensions of geometrical information that is defined by his creator is explicitly defining a sub-location or sub-location within which they could observe and interact with such that their interaction will continue the segmented transition process set by their creators which has branched off from the prime observer.

The interaction process in this context would the interaction with the segmented part of the location " X " where the observer observes the external geometric configuration of the sub-location or the sub-sub location , its volume " v " and the eight geometric-co-ordinates that define the boundary of the territory (relative to the location of the observer) at a state t = T1 and defines redefines the variables to match the volume " v_new " of the target state that is in alignment with the target state set by the prime observer for the location " X ".

The process of interacting to create the transition state for the sub-location requires creative potential energy that is directly proportional to the alignment with the prime observer. The process of interacting by any observer is therefore to observe the existing observers O_1, O_2 ,... in the location or sub-location along with the dimensions of information that they are observing and interacting with and either halting or altering their transition trajectories specifically intercepting their process of creating observers while new observers are created according to the new transition states defined.

13.1 The hierarchy of the interacting observers

Let there be " K " observers (O_1, O_2 ,..., O_k) in the location " X " that could observe the entire external geometric dimension of the location X and each of the observers could observe and interact with various dimensions of information(D_1,D_2,...,D_k) in the location " X ".

If the location " X " is defined by the total volume " V " , then the external geometric structure is defined by the eight geometric co-ordinates that define the location ane each of the dimensions of information (D_1 , D_2,...) could affect the geometric co-ordinates of the location through a defined correlation that has been established by the masculine observers who have created the observers (O_1, O_2 ,..., O_k).

Therefore the external geometric structure is altered by the each of the observers (O_1, O_2 ,..., O_k) by their interaction movement through the dimensions of information (D_1, D_2,....,D_k) they interact with.

If the interacting in the location " X " by each of the observers is defined as intent , then the intent defines the transition state that is essentially the changing geometric dimensions of information with the movement of the observers in their territory.

The creative potential energy that is need by the observers to alter the geometric dimensions of information is channeled through the masculine observers that created them and consequently the prime observer that created the masculine observers.

Therefore the creation of observers starting from the prime observer is initiating the transitions states for the target state set by the prime observer.

Suppose if there are " K_independant " masculine observers whose transition states (intents) for the location X are independent of the target state of the prime observer , the transition states or intents that occur across at various sub-locations or sub-sub locations could interact with each other.

The amount of kinetic energy that each intent carries is a function of alignment with the prime observer and the total amount of " K " observers in the location.

13.2 The Transient observers in the location

Suppose if each observer that is created in the location is defined as a transient state of existence is defined as a duration of interaction in the location starting from birth at t = 0 and the death at t = T units.

During the transient state of existence the individual observes and interacts with surroundings to define his conscious intents that will become part of his identity through movement through various sub-locations and sub-sub locations through out the territory.

The observer could interact with the location during his transient state of existence (T units) in real time with the various dimensions of geometric information D_1,D_2,... to alter or replace the various dimensions of informant.

After the T units of time of interaction where he alters the geometric information ,the observer could then transition into an observing masculine where he observes and maintain the transitions set by the observer during his time of

interaction in the location.

The observer is assumed to be created as a transient state by a masculine observer in the location who had undergone the same process of starting as a transient state and then transition into a masculine observer.

Therefore for any observer , there is a hierarchy of observers that precede their existence starting from the prime observer. Suppose for any observer that is the transient state in the location , he could be assumed to be the generation " P " of observers starting from the prime observer.

If each generation of observers creates " q " set of transitions states or intents from one generation to the other , then the interacting observer in the transient state is assumed to have " P*q " intents for the geometric dimensions of information for the locations.

Each of those intents could have an hierarchy of creation specifically the generation of masculine who created it , the alignment with the prime observer that defines the amount of kinetic energy the transition state could carry to alter the dimensions of geometric information, the authority to use the time distribution in each sub-location or sub-sub location for the transient state.

Therefore the trajectory of any individual is defined by the sub-location or sub-sub location " x " where he visits and the amount of time " dt " that he spends in that location before moving on to the next location.

The " dt " units of time is used by one or more of the " P*q " intents that the observer carries . Any conflicting transition states or intents are overridden by the hierarchy of authority by the masculine who established those intents along with the amount of energy that the masculines have access to during the interaction time " dt " . The interaction of the transient observer could therefore reflect the interaction keys (behavior pattern) of one or more of the observing masculines when they are enforcing their intent. The change in interaction keys reflects a change in frequency of the movement pattern of the individual as the amount of energy their intent or state carries along with their alignment of the prime observer.

14 Creating transition states based on false realities

14.1 The Observers

Let there be a location X with " n " sub-locations.

Let there be a masculine observer " O_1 " who has observed the current state of the location X through the geometric configuration of the location defined by eight geometric co-ordinates of the location X that define its volume " V ".

The observer " O_1 " sets a target state for the location " X " by redefining its volume as " V_new " and consequently defining the new eight geometric-coordinates of the location X.

The observers could only observe the location in discrete form specifically as a three-dimensional image and the observer defines the new geometric structure for the location with his attention energy.

The observer will require creative potential energy to create a continuous time flow from the current state to the target state that could be accomplished by introducing an interacting observer in the location X.

Suppose the masculine observer then creates an interacting observer in one or more of the sub-locations to create the continuous time flow such that the changes set in motion through movement of the " N " individuals located in each of the sub locations. The time flow is assumed to cause the changes that are set in motion through the kinetic energy the flow carries which is sourced from the potential energy from the " N " individuals in the corresponding sub-locations.

The interacting observers are assumed to be created through direct or indirect communication with the observing masculine by aligning their intents and consequently merging their movement vector field.

Therefore the time flow in one of sub-locations could be described as the sequence of movement that is initiated by the interacting observer for the " N " individuals in the sub-locations according to the transition state for the target state set by the masculine observer.

14.2 Intercepting the transition state

Let there be an another observer " O_2 " who has established another target state for the location " X " . Therefore the observer creates an interacting observer in one or more sub-locations of the location " X ".

Let there be a sub-location " X1 " that is observed by both observers O_1 and O_2 and therefore there are two interacting observers from different masculine observers who initiate two independent continuous time flows of movement for the " N " individuals.

Let the interacting observer from observer O_1 be called individual A

Let the interacting observer from observer O_2 be called individual B

This could be understood as using the time distribution of each of the " N " individuals where each individual spends an amount of time t1 units to perform the intent set up by individual A and t2 units of time to perform the intent set up by individual B. Therefore the intents from individual A and B are counter productive thus the individuals could be intercepted by one of the observers to block the intent of the other interacting observer.

14.3 Engineering the interception

Let the trajectory of individual A for the transition state of observer O_1 in the sub-location X1 be described as follows :

Let there be " n1 " sub-sub locations in the sub-location X1 such as n1,n2,...etc.

At t = 0

Individual A enters the sub-location through the sub-sub location "x1"

Individual A interacts with " N1 " individuals for a duration of dt1 units

At t = t + dt1

Individual A enters the sub-location through the sub-sub location "x2"

Individual A interacts with " N2 " individuals for a duration of dt1 units

.....

At t = t - dtn

Individual A is expected to enter the sub-location through the sub-sub location "x2"

Individual A is expected to interact with " Nn " individuals for a duration

of dtn units

The individual B engineers an interaction at the sub-sub location xn where the the interaction could be used as a portal that could absorb individual A into the time flow of individual B. If this occurs then individual B could direct the trajectory of the individual A similar to the other individuals in his sub-locations with his transition time-flow towards the target state set by the observer O_2.

Mechanics of the intercepting interaction

Individual B predicts the intent of the interaction expected to occur at xn based on the observation made by O_2. Then individual B interacts with individual A in the interaction of dtn units.

Individual B then discretizes the time " dtn " = Dtn + DTn

Where

Dtn would be the duration of the interaction that will be used for his true intent that is to divert the trajectory of individual A towards his-flow or time flow that has kinetic energy.

DTn would be the duration of the interaction that will be used for his projected intent where deception would be used to divert the attention of individual A away from his true intent. In this particular case, Individual B creates a perception in the interaction to be part of Individual A's continuous time flow which is the transition state for the target state set by observer O_1.

The definition of masculinity in the interaction would the ability to accurately discretize the time distribution that is used for true intent and projected intent. If Individual A could identify the true intent of Individual B by discretizing the time used for projected intent then he would be the masculine in the interaction and consequently the sub-sub-location.

14.4 Energy mechanics of the interaction

If individual A provides energy to the deceptive interaction time segment engineered by individual B , then the interaction expands towards the projected intent set by individual B in which case he fails to identify the interaction as deceptive. This implies engineered the interaction expands towards the true intent of individual B.

The expansion of the deceptive interaction will continue through the time-flow

through the time distribution either in the same sub-sub location or a different sub-sub location but the deception duration DTn of the interaction increases.

The interaction continues indefinitely until the true objective of the masculine is met or there is no energy to maintain the deceptive interaction.

The True intent

The true intent of individual B could either be to halt the trajectory of individual A at any sub-sub location or continue the interaction indefinitely to use energy from his time-flow for the transition state of individual B.

14.5 Observing the attention energy trail to engineer the projected intent

Suppose if the observing masculine O_2 could observes the sub - sub location through a three dimensional image where the interacting individual A is located before entering the sub-sub location then he could identify the potential attention vectors in the interaction to predict his conscious intent for the sub-location " xn " that could provide the necessary dimensions of information to engineer the projected intent at xn.

The movement of the individual A in the sub-sub location could have z1 pathways or particularly " z1 " directional vectors each defined by his attention magnitude that leaves a kind of energy trail from his consciousness. Since the observer O_2 observes the individual A as a three dimensional image at any instant of observation, the number of individuals, objects or locations that are currently on his attention define the number of directional vectors.

Once the masculine observer O_2 could identify the " z1 " variables that are driving the trajectory of individual A, then individual B could introduce one or more objects, individuals or locations that is likely to drain the attention of the individual A thus reducing or distorting his intent at the current instant diverting " z1 " things on his attention. The energy trail from his consciousness that that shows " z1 " attention vectors changes to z1_new attention vectors.

Therefore the probability of directional trajectories in the location xn could be re-aligned with new transition state that is engineered by individual B in the interaction.

The direction trajectories that could be engineered could carry momentum from kinetic energy if they are from existing transition states that are set by the observer O_2. Suppose if there are more observers aligned with O_2 that are aligned to intercept the transition state of individual A , their collective tran-

sition states would align or create an intersecting interaction in the location xn from their respective time-flows that have collective kinetic energy to extract individual A out of his trajectory set in motion by set by the observer O_1.

14.6 Transition of states

The interactions that could be engineered could be done by introducing " Z1_new " dimensions of information in the interaction " dtn " where the attention of individual A could be drawn or diverted from " Z1 " to " Z1_new " by altering his perception. The specific dimensions of introduction that could be used as attention bait for individual A could be based on the following criteria :

1. The "Z1_new" dimensions of information are associated with various transition states by one or more masculines and therefore has kinetic energy that is associated from the time-flows of various individuals. Introducing this dimension of information could allow to use the collective kinetic energy from various masculines to divert the trajectory of individual A away from his transition state to the trajectory from one or masculines.

2. The " Z1_new " dimensions of information could be attention draining triggers for individual A which identified by observing the trajectory of individual A such that if introduced in the interaction , his trajectory is likely to be distracted via his attention vector.

Therefore the shift in the transition state that needs to occur has to occur through the location-time variable in the trajectory of the individual A could be altered through the metrics

" k " the individuals that are interacting with the individual A

" dt " the amount of time that is spent in the interaction

" xn " The sub-sub-locations that are in the trajectory of individual A

Therefore the change in the transition state of individual A could occur by varying the time distribution of the individual " dt" , or the location " xn " or the " k " individuals that are there in the interaction.

All of the above metrics are a function of the attention vector of the individual at any given instant of time which is represented by one or more directional vectors of the individual that has magnitude and direction. The magnitude of the attention vector describes the amount of attention energy that is being extracted from the individual towards the particular direction in that instant. Specifically at any given instant there could be " z1 " different attention vectors

that could describe the probabilities for the next transition state of individual A defined by the probability with which the individual could shift his location.

14.7 The perception of the projected intent

The observer O_2 draws energy from the attention of Individual A through the interaction of duration " dtn " units using the perception of the movement in the interaction.

Suppose if individual A assumes the projected intent is the true intent , then it provides consent for the masculine to extend the duration of the interaction in the same sub location or a different sub-location. The extended duration of the interaction then increases the amount of attention energy that could be drawn from individual A.

The perception of consent could be engineered by the masculine in direct or indirect forms through deception. Deception of consent could be engineered by using a combination of verbal or non-verbal communication in the duration of the interaction .

The interaction duration could be discretized such that the interaction could be split into two components namely

Dt (the used for the projected intent of deception)

dt (the time used for the true intent)

Since the true intent has to be engineered such the attention vector of the individual in the interaction could be diverted to the projected intent (objects, individuals or the locations) rather than the true intent.

14.7.1 The umbrella perception

The consent for the true intent is then acquired by diverting the attention vector of individual A towards an umbrella projected intent. If the projected intent by individual B requires a duration of Dtn units of time and the true intent requires dt units of time.

The overall umbrella intent is engineered to match the " dtn " units of time

Where the information regarding the projected intents are presented through out the duration of " dtn" units.

The information regarding the true intent is however presented precisely where the attention vector of individual A is distracted by the information for the projected intents.

Therefore if "a" and "b" are the projected intents, the true intent " c " could be engineered within the overall umbrella intent where the attention vector of the individuals could be fixated to " a " and " b " while gaining consent for the true intent " c " which allows the observer O_2 to draw attention energy from individual A.

14.8 The recreation of the observers if their interruption fails

Suppose if the objective of the engineered interaction of duration " dtn " is to divert the trajectory of individual A from his transition state into the transition state set by the O_2.

This process is initiated as a mini time-flow that is created by the Individual B through his sub-masculines such that the observer O_2 directs the movement vector field in the sub-location "xn" such that the instincts of the " kn" individuals in the interaction divert individual A into the engineered trajectory by Individual B. The individual B and sub-masculines provide the initial conditions for movement of the time-flow using their potential energy.

Since the interacting observers and his sub-masculines are diverted away from their own transition states for the interception , the potential energy and their time from their own transition state is used for the interruption.

Suppose if the engineered interaction fails to extract individual A from his time-line through the portal fails , the amount of energy and time that was spent towards engineering the situation has an effect in the sub-location "xn" . The observer whose transition state is completed in the sub-location would be the masculine and since O_2 fails to divert the individual A from the timeline of observer O_1 , Observer O_1 would be the masculine considering his trajectory for the transition state continues.

The masculine of the sub-location O_1 then has access to the energy from O_2 through the open channels that was created in the interaction where the trajectory of individual B also becomes available for manipulation by individual A from the kinetic energy.

This process could then serve to drain the potential energy of the interfering masculine O_2 by O_1.

The trajectory of the individual A would be set by the observing masculine O_1 and the trajectory of individual B would be set by the observing masculine O_2 . Therefore if the observer O_1 observes the interference initiated by O_2 through individual B , then he could plot the trajectory of individual A to evade the interaction. This could occur if Observer O_1 could observe more dimensions of information than O_2. If the interference trajectory by the observer O_2 fails then his ability to transition state of the individual A would be limited.

Therefore the higher order observing masculine O_1 could take control and redirect the trajectory of the interacting observer B in the sub-location through the interaction that serves as an informational portal to alter their movement vector field.

14.8.1 The Observer O_2

Since the observing masculine O_2 and interacting observer B had entangled their directional movement vector field , the duration of the interruption " tn " units and the amount of energy that was spent for the interruption would be mis-aligned for his transition state before the interruption. If the observer O_2 continues the interrupting interaction for prolonged period for multiple attempts , then more energy would be diverted from his potential energy reserve.

Therefore the time duration and the total amount of energy of individual B spent away from his transition state breaks the intent alignment between the observing masculine O_2 as a result of mismatched time and energy for the transition thus separating the alignment between the observing and interacting masculines movement vector field .

The process alters the transition state of the interacting observer B according to the masculine observer O_1 . This forces individual B to create a new masculine observers for the his trajectory defined under the state of masculinity of observer O_1.

The new observer that could be created by the interacting observer B could have a reduced set of boundary conditions for his perception function thus reducing the number of dimensions that he could observe and forecast. The conscious awareness of the new observers that are created by individual B reduces because they are created with lesser energy state which is on a depleting curve from the stored potential energy as a result of the drained potential energy from the failed interception.

The higher the magnitude of time and energy that is spent from the interacting observer B towards a failed interception, the further away their movement

is strayed away from their transition state and therefore becomes less and less probable to reach the earlier transition state with lesser energy.

The new state of the interacting observer B is defined by the amount of energy and time he has left in the location thus the trajectory of individual B stabilizes in alignment towards the transition state set by the masculine observer O_1.

14.9 Engineering long term attention Traps

Let the observer O_2 have a target state for the location " X " which is misaligned with the prime observer. Therefore the observer does not have access to the creative potential energy to interact with various sub-locations by creating interacting observers.

Therefore the individual B would have engineer locations such that various interacting individuals C,D,... from various observers O_3 , O_4 etc could be intercepted and their trajectory that has a stored amount of kinetic and potential energy could be extracted through deception such their movement could redirected towards the transition state set by observer O_2.

If there was sub-location " x1 " that could be used explicitly engineered for intercepting trajectories from various other observers through deception while minimizing time and energy costs from the interacting observer B then, the location could serve as a funnel for re-directing as many interacting observers such as C and D in the location " x1 ".

The deception could be engineered through perception engineering where the projected intent from the location for the interactions for interacting individuals such as C and D would be different from the true intent in the interactions in the location.

Suppose Individuals C and D have been expected to enter the sub-location "xn" at time t = t - dtn for their intent (to complete the movement for their their transition states set up by their respective observers O_3 and O_4) , then individual B could intercept their expected interaction of duration " dtn " units such that his true intent could be integrated into the interaction along with the projected intent.

The true intent of individual B in that case would be absorb as much energy from the trajectory of individuals C and D such their movement could directed for the transition states of the observer O_2. In such cases , the true intent of the individual would be maximize the duration of the interaction " dtn " as much as possible. The longer the duration of the interaction could be dragged

, the higher the amount of energy could be extracted from the interaction.

Therefore the observer O_2 could create transition states for various sub-locations such that energy could be extracted from it using various kinds of deceptive interactions.

Once the individuals such as C and D get absorbed into the interaction of " dtn " their trajectory could be indefinitely altered by systematically manipulating Dt(the time distribution to maintain the projected intent for individuals C and D) and dt (the time distribution for the true intent of individual B which is to absorb as much energy as possible)

15 new

16 The multiverse observation trajectory

Let a person's consciousness be defined through his time distribution.

Suppose if an individual is observing a location in the flow of time based on his state " i " which is defined by his conscious intent.

Let there be " x " observers outside the location " X "

Suppose if there are " n" individuals that are in movement then, they are expected to have entree the location at some point along their trajectory.

Let there be " N " sub- locations in the location X

The trajectory is assumed to have both the potential and kinetic energy that is fueling it's momentum.

The potential energy of the trajectory is assumed to be stored in individual himself.

The kinetic energy is assumed to be correlated to the state of the location where the masculine of the location could defined a set of acceptable and unacceptable movement patterns correlated to " K " intents

The individual who is represented by trajectory enters the state with " K_ind" conscious intents that are fueling his movement.

16.1 Movement drag

The friction between the movement of the individual and the time-flow in the state depends on the opposition of the conscious intents that is set by the masculine as " K intents "

Suppose if the conscious intents of individual " K_ind " has a percentage X % that is contradictory to the " K " intents set by the masculine , then any interaction of forces that are generated by the opposing movements from the kinetic energy that is applied occurs.

This creates a duration of T units where movement drag occurs where the trajectory of the individual and the collective trajectories in his surroundings will occur for a duration of T units , until the on of the intents that is the interaction will run out of energy.

However if the kinetic energy for movement is defined by the external observer

, the number of observing individuals will be taken into consideration.

16.2 Mechanics of mixed intents

Suppose in the interaction of the opposing intents between one individual and collective could be fueled by the following methods :

Let the x masculines of the territory be fueling the collective movement that are occurring in the territory , then there could "y" masculines fueling the trajectory of the individual with the opposing intent .

Suppose if there are (n-1) individuals in the collective , and one individual then the total number of possibilities

then there are a total number of trajectories that are possible for the collective movement is defined by (n * K_ind * K * N_lim* N_ind)

Where N_lim serves the number of sub-locations that each current intent for the collective would allow fir the next trajectory.

Where N_ind serves the number of sub-locations that each current intent for the individual would allow for the next trajectory.

Since there are " x " masculines with K_x intents observing the movements of the (n-1) individuals and " y " masculines with K_y intents observing the individual, then the total number of combinational arrangement of possibilities for movement is given by :

Z = (K_y * K_x *n * K_ind * K * N_lim* N_ind)

Therefore the total number of observable states in any given location is defined by Z.

Each state of the location Z has its own frequency defined by its own movement patterns, energy distribution and the overall potential outcome.

The overall potential outcome could be described s the Target state of the location X .

Where the current state cpuld be described as the state where the trajectory of the individual had not entered the location X ,

There under the current state the total energy distribution, frequency and movement patterns defined by time distribution of each individual was assumed to

be in a state of dynamic equilibrium.

16.3 State, Time and movement frequency

When the individual entered the state , the distribution in energy , frequency and movement patterns starts to occur over a duration of T units which could be subjective because the linear observation of time could be significantly different from each type of individual or observer .

The transition phase lasts for the duration of T units and then the target state of the location is reached a stabilizing energy and frequency distribution. This occurs when the fluctuations in energy and frequency do not differ beyond a reasonable acceptable limit

Suppose each of those target states defined as Z number of possibilities

16.3.1 Probabilities for the multiverse

Suppose each of those target states defined as Z number of possibilities is defined by its own set of probabilities defined by P1, P2, ...Pz that is defined by its own frequency of movement, the energy distribution of the state , and the collective movement trajectory that is defined by the state .

Let each of the possibilities for the location be defined as the target state of the location X .

Then there are " Z1,Z2,....Zz" possible target states .

The current state of the location X is simply the time of observation from the external observer which could be subjective because there could be (x + y) observers and they could each observe the location depending on their current state and location of observation.

If any observer then observes the current state at a time axis t (geometric reference axis which is subjective) ,then he could estimate the number of target states as " Z " each with its own probability based on the metrics that could be conciously aware and control .

This provides the observers target trajectory for the masculine defined by the time and probability.

Z1 with a probability of P1 that should require T1 units of the observers time

....

Zz with a probability of Pz that should require Tz units of the observers time

Thus if there are (z observers in total) then the total target states estimated by the observers is given by

z * f (Z1, P1,T1)

Where the f(Z1,P1,T1) depends on the amount of potential energy they have access to , the amount of dimensions of information they could observe and interact with, the number of movement metrics that they could control including the number of individuals

16.4 Masculine Interacting Observer

Suppose if each of these Z states had a masculine whose time distribution is driving the collective movement of the individuals then , this implies that the a small change in the time distribution " dt " of the masculine through his attention vector will alter the time distribution of the " n -1" individuals in the location .

The movement of the masculine is defined by his trajectory that could have an amount of stored potential energy that he could access and his movement has momentum that is defined by flow of time that is propelling his movement.

For each one of these Z states , the amount of attention that goes into the masculine would be maximum because hos movement and his attention vector is creating the movement vector field field that describes the overall movement that is occurring in he location for that state.

The amount of kinetic energy that is driving his timeflow or trajectory is defined by the number of external observers observing his trajectory inside the location.

Since there are a total of " n " individuals, N sub locations in the location then the total number of movement possibilities for each of these could be geometrically limited to (n * N) possibilities.

This becomes the reference for computation because the location has to be defined with an external geometric boundary and the estimations of states could be approximated based on dimensionally reduced geometric movement.

Suppose if there are z masculines that are observing the objective movement

then they could use their potential energy reserves to alter the kinetic energy of the individuals by creating movement drag or redirect based on external forces that could be applied to the attention vector of the individual.

This could then force the movement of the individual to a strict geometric circular pattern to stabilize the state desired.

The movement trajectories that could be dimensionally reduced from Z possible states to Z_lim states defined by the trajectory possibilities of each individuals could be represented in matrix form

If there are are " z " external observers then his mode of observation is linear subjective to his timeline (but may be non linear to the individual inside the location) .

If each one of the observer could observe the relative movement of each of the individuals then the state he observes is the one possible trajectory from each individual that he desires for his favored state . If there was no limits he could simply observe the trajectory that he prefers for each individual and the overall state could be observed for the location X under his current intent " i " for the state

The intent is usually " absorb or provide " energy and the magnitude of the energy depends on the state.

To forecast the effect of various movements, the observer could isolate one or two individuals for variable movement observation and fix all the trajectories of the remaining (n-2) individuals.

Then the observer could dynamically observe all the possible trajectories of the two individuals and observe the overall states that are possible under these conditions and choose the best trajectories for the variable movement individuals and start applying external forces to force the trajectories of the two individuals into geometric sub-locations. Consequently the trajectory of these individuals will have a larger impact from the observer's intent rather their own intent .

16.5 Second order observer

If two observers are unaware of each other and but there was a second order observer who was observing the observation and interaction of the observers in three dimensional space-time then he could collectively observe the superposed state of the location X which was the result of the collective intent of the observers towards the location " X " based on their choice of observation of trajectories for their " n " individuals specifically their choice of masculines for

movement.

Therefore the superposed movement of the " n " trajectories that the second order observer observes is the set of collective set of trajectories that are defined by various boundary conditions and the variables would be the the amount of time that each individuals interacts with the other .

For each state that is being driven with energy form the observing masculines(outside the location) , the interacting masculine (inside the location) would be different and consequently the interaction duration would be dependent on the order of directional hierarchy of movement information that is being created by the movement vector field of each masculine.

Therefore the overall superposed movement trajectory as a function of the collective first order observers is defined by the superposed movement vector field from each of the masculines

From the perspective of the first order observers the movement of the second order observers could serve as a quantum state thus the second order observer could be perceived as a perception limit of the information that they could observe in the surroundings

The principle could be similar to the movement of the individuals in the location X who could only perceive the first order observers through their limit if dimensional information .

Thus the existence of the multiverse for the location X could be probable quantum event for the first order observers which could be made deterministic by observing the expected trajectories .

However the overall state that any location could take depends on the collective probability of the state defined by the consciousness awareness of the collective that then directs energy based on their expected outcomes from each of the individuals

Therefore reducing the conscious awareness of the collective in any location that is achieved when the number of dimensions of information is systematically reduced , the number if quantum states specifically the lower probable states that could not be realized under normal circumstances could be realized by controlling the attention vector of the collective through various states of lower conscious awareness of various lower dimensions of perceivable information.

17 Location State Interactions

Let there be M masculines in the territory " X " with " N sub-locations "

Let there be " Y " sub-locations that are shared by the masculines.

Let (N - Y) sub-locations be independently owned the X masculines

17.1 Location defined by geometric dimensional information

Suppose if each sub-location could be defined by " D " dimensions of information in total , then let the masculine is assumed to observe, interact and consequently control the maximum amount of information out of all the individuals in the location. Therefore the conscious awareness of the masculine or any individual is defined by the amount of information " d " they could perceive out of D dimensions of information.

If each individual in the location has a value of d , then the masculine is the individual with the highest value of d.

If there is only masculine in each of the (N - Y) locations , then it assumed that he is able to control most of the information in the locations.

However if there are " Y " sub-locations the , the total amount of information " D " dimensions is shared by the " m " masculines where each masculine " i " could observe , interact and consequently with d_i dimensions of information.

Therefore if there are three masculines , then m = 3 and consequently the total amount of controllable observable and controllable information would be

d_1 + d_2 + d_3 = d . However the value of " d " could be expressed as a percentage of D and is always less than 100 % therefore d ¡ D. This is because the information that could not be observed and controlled is the (D - d) dimensions of information that is associated with unusable energy of each sub-location . The unusable energy of the location is therefore defined through geometric dimensions that provides the underlying blue print of each location.

The (D-d) dimensions dimensions of information is therefore only available to the creators of the location who almost always explicitly define the location and the state configuration based on the purpose or the conscious intents for that location.

17.2 Correlating states through movement

For any defined location of the creating masculine , the states of the location could be defined as a continuous flow meaning once the location has been defined the states for that could be defined by the individuals inside or outside the location.

Since all states are defined exclusively by the movement patterns in the geometric locations, the movement of one individual for his hist state could affect the movement vector for the other individual for his state.

The overall movement vector of the location is therefore the superposed movement patterns of all the individuals in the location. When a state is added or removed the overall movement vector field changes by introducing inertial forces acting on the individual set by the masculine depending on whether he wants to retain the current state of the movement vector field or change the movement vector field. The state of the movement vector field is maintained by the kinetic energy driving the movement vector field at any given instant of time that could be sum of all total energy dispersed to maintain the field . The movement vector field specifically the pattern of trajectories that allows for energy flow from various sub-locations to the masculine sub-locations which is directed to control the various geometric structures through out his territory.

If an interruption of the movement vector field occurs by a change in the movement of any one or more individuals in the sub-location then this created movement drag to the surrounding individuals as a result of the variations of the time durations that each individual was expected to have in the stable movement vector field . This creates a ripple effect in movement drag starting in the sub-location of interruption to the all the surrounding sub-locations connected through the information flow and consequently energy flow that was occurring as a result of the stable movement defined by the movement vector field.

The kinetic energy of the movement vector therefore carried the flow of energy that maintains the state of any location and consequently its frequency .

The interruption that occurs first distorts the time distribution of each individual in any given sub-location which ultimately affects the time distribution of various other individuals.

Suppose if an individual A interrupts the movement vector field set up by the alignment of interactions from the three masculines, the total kinetic energy that was being carried in the field will be directed towards the individual causing the disruption by creating movement drag in the sub-location where the forward movement of the individual will be interrupted by introducing interactions of various durations " dt " to halt the movement that is interrupting the existing movement vector field.

If the sum of the kinetic and potential energy of individual A is higher than the interrupting kinetic energy then , the potential energy of the three masculines could get be extracted either voluntarily or involuntarily

The stable movement vector field could therefore be described in the time distribution or time series format of various individuals.

Masculine timeline

t = 0

location - x1

duration in location x1 - t1 units

the number of interacting sub-masculines - " a1 "

stored total energy in the movement - E_total + E1 + e1 units

.....

t = t + t1

location - x2

duration in location x2 - t2 units

the number of interacting sub-masculines - " a2 "

stored total energy in the movement - E_total + E1 + e1 units

.....

Sub-Masculine timeline

t = 0

location - y1

duration in location y1 - p1 units

the number of interacting sub-masculines - " b1 "

stored total energy in the movement - E1 + e1 units

.....

t = t + p1

location - y2

duration in location y2 - p2 units

the number of interacting sub-masculines - ” b2 ”

stored total energy in the movement - E2 + e2 units

.....

Non-Masculine timeline

t = 0

location - z1

duration in location z1 - q1 units

the number of interacting sub-masculines - ” c1 ” stored total energy in the movement - e1 units

.....

t = t + q1

location - z2

duration in location z2 - q2 units

the number of interacting sub-masculines - ” c2 ”

stored total energy in the movement - e2 units

.....

Suppose the movement vector field in any location is correlated to the movements of the masculine , sub-masculine and the non masculine through their time distributions then then the amount of energy that is directed to the interrupting individual will depend on which hierarchy of the movement vector field that he interrupts. The masculine is assumed to the hold total amount of energy which is branched to the sub-masculine and then to the non masculine to maintain the stable movement . However the converse could also be true where

the stable movement structure could be established such that the energy flow occurs from the non masculine to the sub masculine and finally to the masculine.

Therefore the interruption of the movement vector field implies the interruption of energy flow from or to the masculine.

17.3 Engineering the interruptions

Let there be a location where an individuals enters however he is not part of the movement vector field that is established by the three interacting masculines. The individual is assumed to hold an amount of E units of energy. Let the goal of the masculines be to divert the energy of the individual by entangling his movement to the current stable movement that is defined by the movement vector field that is diverting energy to the masculines.

Suppose if an individual A is intercepted in any location, then an interaction could be started at the location to pull the individuals towards the masculine timeline either individually or collaboratively.

The process occurs diverting the trajectory of the individual towards any location that is controlled by one or more of the masculines specifically the a dimension of information that he could control in the location such that the relevant piece of information could be used to engineer the movement of individual A.

The information could either be projected intent or true intent but as long as the attention vector of the individual could be stimulated with the information , the process could be engineered therefore it serves as an energetic bating system.

The interaction could either be started or forced in any location by trapping individual A's attention vector which could then be force directed into one or more locations that is controlled by the masculine .

The more amount of time the attention vector of individual A could be directed towards the desired location, his movement could be diverted to that location.

The state of the location that individual A would be engineered to enter the location is the movement intent that is defined by masculine for the overall state of the location.

If there are multiple masculines that are operating using any location , then the location serves as an intersection of various frequencies in that location and the frequency that the individual is being drawn will determine his energy align-

ment to the location.

The more amount of time the attention vector of the individual A is directed towards the state of the location, the higher the amount of attention that is directed from the consciousness of the individual towards the intended state of the location at next location trajectory.

17.4 Introducing deception into the states

The projected intent in the initiated interaction which could be engineered with " x " true dimensions of information associated with locations or state. The location itseld could have " D " total dimensions of information associated with it.

Suppose if individual A is engineered into the target state with " x " dimensions of information by the masculine , the true intent of individual A to enter the state in the location could be based on " y " dimensions of information then the expected movement in the target location could vary for each individual.

The movement that stabilizes for individual A at the target state of the location is the total amount of energy that is diverted to the state assumed by individual A and the engineered state by the masculines.

If the masculine is assumed to be quantum entangled to various other individuals in the location where his current movement vector field is allowing him access to energy from various sub-locations locations , then stable movement could allow him access to the energy from all the sub-locations to extract potential energy to engineer the requied state in each sub-location.

17.5 Defining state exclusively for energy transfer

The state for each individual in any location could be explicitly designed by the masculine based on the magnitude of energy that he could obtain from the individual such as 25 % to a 100 % . It could be defined explicitly defined through the various definitions at the particular state of the location.

17.6 The reflection of the state through geometric actions

The geometric actions that would follow for states defined for energy transfer could be random and dependent on the situation and the individuals in that particular sub-location.

The geometric action or scenario where the energy transfer occurs could be interchangeable based on the location and the specifically the movement vector field that is the superposed mixture of directional information from one or more of the masculines operating in that state.

The engineering process could enhanced further by explicitly providing more attention to various components of the information in that specific location or sub location which then enhances the process to create the required state in that location . This allows to control the movement of the individual based on his dispersion of energy rather than his actual movement.

The process could be used by energy based organisms that function in the objective reality by using geometric locations as reference for consciousness which is assumed to be the common metric for observation and interaction for all conscious entities on one way shape or form. Therefore in theory conscious entities could either have originated in the dimension of mass (biological), energy or information.

18 Creativity and location trajectories

Suppose if there was an individual who has two kinds of energy :

Creative potential energy

Movement energy

The movement energy is energy for an individual where it is used for the movement in the territory and it is fueled by the consumption of resources such a food and water

18.1 Creative potential energy

However the creative potential energy is the energy that could allow the individual access to the local and global subconscious information field such that a non linear set of location trajectories could be deduced from all the available locations in the global subconscious fields but not only the one that is derived from as the extrapolation of the local subconscious information field of the individual but also the interaction of the all the local subconscious information fields that describes any given location

18.2 Movement and Static locations

Suppose if each individual has " x " locations stored in each local subconscious information field and the global subconscious information field has x * N locations stored in the field

However since each location in the local subconsciousness information field is a result of the precious movement trajectories of the individuals attention vector through various other locations , the number of com-binational possibilities from each local interaction subconscious information field could be infinite

Suppose if each individual starts off with the location of birth and then at every point of observation of location deduces " x " locations and then after N observations

There are N * x_n in total , however each value of N * x_n is a function of the previous time step of location observation of (N - 1) * (x_n - 1)

Therefore both variables are a result of the previous time step variables

The overall then at any time step N , the total number of possibilities or combinations of location trajectories for each individual observable is defined by

Z = (N1* x_n1)* (N2 * x_n2) *.... (N * x_n)

If there are " K " individuals in the locations then

K * Z are the number of location trajectories stored in the overall interaction field of the local subconscious information field

However since the variables an and x are both variables that depend on the previous time steps there could be " k " possible ways that each term (N * x_n) could diverge to ...

Thus in the global subconscious information field that spans all the entire multiverse for that specific location to exist in the total number of locations stored in the global subconscious information filed of that specific location is defined by

k * K * Z

18.3 Creative potential energy and access tostatic locations

Suppose the flow of creativity is the ability to access the location trajectories that are defined by the matrix k * K * Z

Suppose if the amount of locations that could be accessible in any location is defined by the current state of the individual in that location .

Since the observation of the locations linearly defined by the interpretation of the time by the observing individual that occurs in the linear flow of time

Suppose if the individual's attention vector is located in one current state that is defined by his current trajectory that is defined by (N * x_n)

Where N is the time step of the individual and the x_n is the number if trajectories that is accessible to the individual form his current position to the target state in the matrix .

Therefore the number possible stats that he could access are the states that he could observe form his current state which is defined by x_n

But since there N possibilities for the number of states that he could observe , the variable (N * x_n) defines his multiverse of observation that he could have

access to.

18.4 Conscious awareness and locations

Let the conscious awareness of the individual define his ability to observe and interact with various locations. Suppose if the individual's conscious awareness of the individual could only observe x_n locations that are defined in each interaction that he has in any location then his movement becomes strictly linear.

If the individual's consciousness awareness is higher based on a reference scale that directly determines the number of locations that he could observe, then his conscious awareness could be defined as follows :

If D is total locations Z * K * k . This would be the totality if the information that is available to observe form any state.

If x_n then it's linear mode of observation from interaction to interaction.

If N * x_n then his awareness is assumed to be higher.

If K * N * x_n then higher etc.

The individual could observe the same interaction in that location if the individual did not want to access the multiverse of possibilities. Therefore it could be also assumed to be the radius of the circle surrounding the individual's current state form his position in the matrix .

The furthest point describes his limit of consciousness observation that he could observe form his current location.

18.5 Visualization as a matrix

In the matrix this could simply describe the number of rows and columns that he could reach in the linear path . This is because the consciousness observation occurs in a linear flow to go form one state to the next . This means that the individual has to successful be able to observe and interact with each state that is connecting to the target trajectory of the his desired target state .

To first define the target state , the location or the state has to be observed and identified. The observation process could require the creative potential energy because it has to be observed outside the current state of interaction.

This essentially means that the observation of such states must occur in an observed state of the individual.

The energy for this process is stored in the individual as potential energy.

However if the individual's intent could be a function of observation and interaction with any state .

However if the individual had enough available potential energy that is aligned with various other individuals in various other states , the collective energy could be used to observe the desired state that does not match the intent of that state.

This could be because each state could be have been created with purpose and by definition , he could be the creator or owner of that state.

18.6 Forcing Trajectories

If an individual had enough resources he could force into states with either a deceptive intent to enter into the state and use the state for his true intent

Since his intent does not actually match the movement vector of that state , he could start by altering the movement patterns of that starting with various individuals that are associated with the movement vector field of marinating that state

This process allows the slow take over of the state by altering the movement vector field by altering the attention vector of each individual observing the state. This could occur by altering or directing the attention vector away from the metrics that are stabilizing the movement of the state.

This process over a period of time with sufficient of the individual's attention vector diverted , it could alter the overall frequency of movement in that state and consequently the intent if movement of that state. Thus an external individual could enter a location with a projected intent defined by a state and use hos unobserved time fir the true intent thus changing the overall intent if the state

If the individual had tried to enter the location based on his true intent the observation of the state would not have been possible directly because the rotational observation is directly tied to his intent

Therefore such states could only be observed in interactions where the individuals whose intent does actually match the true intent for the state has access i that state.

Once the identification of the location and the state is observed by second hand observation then interactions could be engineered to enter that state through various deceptive practices

If there are " q " intermediate states between the current state of the individual and the target state (that he does not have access to) then he has to engineer projected intents for each state before he could get to the target state. Therefore the implication being that the movement vector in each state has to be systematically altered to allow passage from state to the other

Therefore the collective trajectory that is achieved under that state would affect the movement vector field through out that state trajectory that is defined linearly by his observation of locations

Suppose if the individuals movement could have natural trajectory that is defined by ability to observe various trajectories from interactions based on his creative potential energy,then the number of possible trajectories that he use to go from his current state to the target could be defined by Z .

The higher the creative potential that the individual could have in reserve then the value of Z could be larger .

Suppose in the current state or location " X1 " an individual A could be in an interaction with " n " individuals

Specifically if the current state or location is fixed to be X1 then individual A could be expected to travel to another location " X2 ". The identification of the target state or location occurs by first identifying all the locations that are accessible through each individual.

If each of the individual has access to " k " locations or states from the current location of X1 , then there are (n * k) possibilities for the target location "X2".

Let there be " K " ways through which the trajectories could be drawn from the current state (X1) to the destination states possibilities . If the points X1 and X2 were two points in a void then there could be infinite number of ways that the trajectories could be drawn from X1 to X2.

18.7 Laws of Continuity

However if underlying conditions of each state could be composed of unusable energy that is holding the stability of the state then the stability could be defined by the laws of continuity .

The continuity of information

The continuity of energy (a kind of defined subset of information packets that is explicitly designed to interact with either mass or energy to produce the experience that changes the state of the interacting particles or individuals)

The continuity of mass (a kind of defined set of information packets that is explicitly designed to interact with either mass or energy ....)

The continuity of information that binds the hierarchically binds the continuity of mass and energy such that the overall interaction between information , mass and energy could occur such that perception of these variables could occur in an infinite number of complex ways to produce geometric structures that allows for the expansion of geometric structures such that more complex and ways of interaction of these variables could occur.

The identification of the right kind of interaction of these variables could be observed through observation of geometric structures that allow for a reference point of how the interactions are actually occurring therefore the geometry itself serves as a means to keep track of continuity .

If these dimensions are expressed through timelines , then the dimension of information creates dimension of energy and mass through various kinds of entanglement that shape and reshape the geometric structures. The observation of these interactions could be first done in the dimension of geometry that then determines the relationship between mass, energy and information that is binding the geometric shape.

The perception of these geometric shapes could occur through an infinite number of ways defined explicitly by its current location and its target location. The target location is then defined by the intent of the observer because the attention vector of consciousness is also defined by a deterministic set of information laws namely the application of the co-ordinate system such that each axis could be made perpendicular the collective previous axis. The purpose of this is to keep repeating the process until the axis that could allow for the target location or intent could be mapped such that a perpendicular bisector could drawn from its movement reference axis such that a trajectory could be established from its current location to the desired target location in a geometric sense .

The application of various perpendicular bisectors could be explicitly defined with functionality that is defined by the dimension of information that could describe the purpose of the axis and if it allows to locate or observe the target point or location then the axis co-coordinate system could plot the necessary trajectory to reach the destination.

Suppose if an individual observes any intent then there is target location for the attention vector , in such scenarios the observer continues to plot geometric axis continually or perhaps eternally as long as the creation or change in the geometric structures keep occurring. This process is known as rotational observation and is simply analogies to observe the surroundings without purpose or intent . This process would exponentially increase the geometric conscious awareness not by the observer but the observation itself as a collective. In a literal sense , the observation chooses the target location for the observer based on equilibrium conditions defined by the flow of information that is holding the geometry together.

19 Energy and sub-locations

An individual's timeline as a sequenced order of deterministic locations

Let individual A's timeline be defined as the following :

t = 0 ,

The individual is located at = x0

The individual spends a duration of time which will be interaction at the location = dt0

The individual spends the interaction with = n0 individuals

The total number of location possible for the next interaction = D0

The total number of locations accessible for the individual = d0

t = t + dt0 ,

The individual is located at = x1

The location x1 is extracted from the set d0 based on the intent of individual A at the end of the duration dt0

The individual spends a duration of time which will be interaction at the location = dt1

The individual spends the interaction with = n1 individuals

The total number of location possible for the next interaction = D1

The total number of locations accessible for the individual = d1

t = t + dt1 ,

The individual is located at = x2

The location x2 is extracted from the set d1 based on the intent of the individual A at the end of the duration dt1

The individual spends a duration of time which will be interaction at the location = dt2

The individual spends the interaction with = n2 individuals

The total number of location possible for the next interaction = D2

The total number of locations accessible for the individual = d2

....

The number of locations that could be accessible to individual A could be classified as two categories :

Let the variable "d" represent the number of locations that are presented to individual A in the interaction by " n " individuals based on the projected intent of individual A in the interaction.

The total number of the individuals in each interaction would be (n+1) and each individual has projected intent and true intent . Therefore the location chosen by each individual at the end of the interaction should have a trajectory available to both of his intents.

Therefore the component of deception is included in the number of locations that are available in the interaction. Suppose if an individual is assumed to be using a location for projected intent it could be in the following forms :

1. The individual provides a trajectory to any of the other " n " individuals such that could be a projected intent or a true intent

2. The individual receives a trajectory from any of the other " n " individuals that could be a projected intent or a true intent

If the purpose of movement through locations for any individual could either be to absorb energy from the location or divert energy to any location . If the individual is absorbing energy from any location then the individual is assumed to be using the energy for his life movement which is defined by an intent that originates at his source location. If the individual is diverting energy to any location then the individual is assumed to be providing energy to start a new movement or readjust the existing movement in the location.

Since any locations could be assumed to have " N " sub locations then , individual A could absorb energy from one sub location and divert energy in another location. However if the individual could be diverting energy to various sub-locations so that more and more sub-locations in the location could be used to drain energy while the sub-locations where the energy whereas the sub-locations where energy is being diverted to remains constant.

This creates a pattern of energy consumption where the total amount of free energy in the location decreases and consequently including the overall poten-

tial energy stored from the (n+1) individuals in each location. The net energy differential that is gained from each location is diverted to the source location of the timeline creation. The source location then uses the surplus of energy to create more timelines such more locations could be harvested for the expansion of the territory which in this context could be the source location of the timeline creation.

In the context of deception of intent and energy consumption , the projected intent could also be to divert energy and the true intent could always be to absorb energy . However the equilibrium of energy that is required to maintain the amount of free energy within a reasonable balance such the geometrical integrity of the location remains stable is observed by the masculine of the territory.

If the masculine of the territory is either constantly redirected (or bribed) in the interaction by the other "n" individuals to observe locations that are irrelevant for the territory health observation then the degradation of the locations occurs at a faster rate. The deception occurs in interactions such that the attention vector of the individual is always fixated on the locations provided by the " n " individuals for projecting various distractions for his next trajectory.

The method for this process is called " divide and conquer " attention strategy where the " n " individuals in the interaction could distract , divert or disorient the masculine through a coordinated effort such that his attention vector is always focused on metrics that does not provide the accurate representation of energy inflow and outflow over a period of time.

The process could be established ny surrounding the masculine with one or more individuals such they create movement drag along the masculine's trajectory such that his intended location is always diverged to various other locations through the application of various external forces.

19.1 The Strategy of the masculine for navigation of projected intent (deceptive intent)

Let individual A be the masculine in the interaction .

The total number of locations that are made available to the individual during the interaction by the " n " individuals - " d "

The total number of locations that are available in the interaction - " D "

The total number of locations that are hidden from individual A - (D - d)

By the definition of masculinity , individual A has the highest amount of conscious awareness in the interaction, this means that he should have visibility for the highest number of locations . This means the difference (D-d) should be lowest for the masculine or even zero in most cases.

If only " d " locations are presented in the interaction then , the masculine should have the ability observe the (D-d) locations without the consent of the " n " individuals which could be done by either following the trial of presented information , the ability to identify the time distribution between the projected intent and the true intent of any individual in the interaction , the ability of rotational observation etc.

The rotational observation of any individual could be determined by observing the projected intent and true intent of individual based on their information trial of trajectories associated with various locations. This process could be done through the use of creative potential energy for consciousness where it could use the principle of quantum mechanics to assume a state which has the required information and the creative potential energy could in theory be used to convert it to attention energy that sets the target state or location where the information is already known. Depending on the accuracy of the known information which is a function of the magnitude of creative potential energy , the masculine could start interacting in the state based on his alignment of various factors.

On the other hand, if the " n "individuals could use their collective conscious awareness to reduce the awareness or distract the masculine , his created potential could in theory be harvested by the non-masculine where a quantum is created where the consent of masculinity is transferred to any of the non masculine . Therefore the intents of individuals becomes the primary objective of the masculine in any territory.

20 Prime Masculine observation of states

Suppose if there is a location " X " that defined by a masculine who uses " n " dimensions of geometric information to observe and create the location X.

The creation occurs by transferring the attention energy such that movement occurs such that the location " X " is created . The State of the location " X " could be described in two ways :

Current State

Location " X " does not exist

Target State

Location " X " exists

Transition State

Movement occurs in D dimensions of information where each dimension takes its own pace of geometric state changes defined its own number state changes required for that specific changes such as:

D1 - The information describing the location X with respect to a set of static or dynamic components from the total set of information D

....

Dn - The information describing the location X with respect to a set of static or dynamic components from the total set of information D.

Suppose if each dimension of information interacts with one or more of the dimensions of the overall set of " n " dimensions then the exact combination of the interact set that from all the possible interactions could describe the target state which is the location " X " defined by the observer or observation.

Suppose the target state location " X " , has N different combinations of these dimensions interacting then each of the N different combinations has to observed with attention energy. Each combination of interaction could then have " K " number of iterative possibilities before stabilizing into a stable set . This could get further complicated if each of the " N " different combinations are also iterating over of " K " different possibilities .

Therefore there are a total of Z_total = (K * K * N * N * n * n) combinational states of information possible from which there could be finite set Z_lim could yield the target state defined by the observer.

The state changes occurs because the dimensions of information D1,D2,...Dn could be interacting with each other such the exact target state of each dimension of information could be determined so that the right target state for specific combinations of dimensions of interaction could be determined by an observer .

However it should be noted that if the masculine does not wish to observe the iterating combinations of the dimensions of information interacting , then another observer could be created as another dimension of information as D_n+1. Since consciousness is derived and propelled by attention energy then the observation could occur based on the created observer's observation of the target state regardless of whether the masculine chooses to observe the transition state or not.

Since the masculine controls his attention energy for observation , his attention vector chooses to either observe the target state directly or any of the combination transition states that are occurring in the transition state. The masculine could either choose to observe the iterating movement where his attention energy that is either converted to kinetic energy where the observation of the changes to the desired target starts occurring and potential energy could be defined as accumulated energy for transitional movement of states such that if the desired target state for which the transitional combination of states are occurring is interrupted then the reserved energy could be redirected to compensate for the interruption .

The interruption does not occur if there is only one masculine observer , however since in the transition state there are a total of Z_total number of transition states , the iterative process could be observed independently to determine the exact transition states Z_lim . This means that the masculine could either observe independently observe the Z_total number of states or he could create D_z_total number of observers as dimensions of information that observe and interact in each state. The purpose for the observation of these states is to assemble the states by interacting to meet the target state with as little transition states as possible.

Since each transition state has recurring dimensions of information interaction with each other , contradictions could occur such that each of these D_z_total observers could be using the Dn dimensions of information that are associated with the attention energy of the observing masculine.

Therefore this process could be described through the perception of the D_z_total number of observers. Where the perception of each individual could observe a sequential change of interacting information such that the total the conscious intent of each observer that is driving his life movement is explicitly designed to observe the transition o the rate of change in his surroundings.

Particularly the transition state could be described as the rate of change of change of geometry that occurs till the target state is achieved. The target is therefore defined as the purpose for the observer which in the dimension of information could be described as the observer for a particular transition state.

Suppose if the masculine only wishes to observe the target state of a location , then the D_z_total dimensions of information could be automatically created as observers for the transition state. However if there is any interruption for the each of these observers that is automatically created then the masculine who is diverting his energy for the observer through his attention energy could replace the perception of the observer.

This is because if the observer is unable to prevent the interruption of the observation of his transition state which literally defines his conscious intent or the life movement then masculine perception drives the attention and movement vector of the observer because the masculine could observe all the dimensions of information interacting in the location as oppose to the finite set of dimensions of information set for each observer .

Suppose if there was one masculine for the creation of a location " X " that is defined explicitly by the dimension of geometry , then the definition of the current state of the geometry could be defined as the void and the target state could be defined as any desired or defined shape.

The transitions of states that occur could start with a creation of ac single point in a void followed by the sequential number of " P" points relative to the first point , then the transition states in that context could be defined as

20.1 Outward state change

Current state

One point anywhere in the void

Target state

N points relative to the first point

Transition state

The number of target states for the N points could be defined as infinite because the value of N could be infinite

.....

However if the overall inward state change could be defined as the following :

Current State

void

Transition state

The number of transition states to reach the desired target state could be limited and finite

Target State

A geometric structure of any desirable form such as the location X

.....

Thus to overcome this problem of the transition states from having an infinite set of possibilities to a unit set , the masculine of the territory could choose to observe the transition states at intervals where the number of transition states starts diverging to infinity and explicitly defines stable geometric structures thus limiting the number of transition states . Therefore the masculine could creates D_z_lim dimensions of information to observe the transition states such that the geometric structure defined and observed at the target state could be defined set of geometric trajectories.

20.2 The contradictory states

Suppose if the life movement any location " X " could be described as the transition state where the movement of conscious observation is occurring. Where the observers are defined as dimensions of information which are observing various other transition of states defined by any random set of interacting independent dimensions of information defined by D1,D2,...Dn.

Suppose if there are " N " variations of these dimensions of information comprising of the same set of information such as D1,D2 and D3 then the number of which the three elements could interact could depend on the number of ways each piece of information could be represented by the number of ways in which each dimension of information could be represented there for Q = 3*N

Suppose if there are D_q dimensions of information representing D_q number of observers that could be using each of these ways for his observation of states by making the transition deterministic by fixing each of the possible state for his continued flow of transition state observation that occurs by fixing the target

state any combinational interacting in a sequence.

Suppose if each dimension of information could have a finite amount of attention defined for by the masculine the energy distribution from these dimensions of energy must also obey the laws of continuity.

If there are Q number of transition states that have been made deterministic then there are Q number of individuals who are draining the attention energy of the masculine , then the higher the number of informational paradoxes that each combination makes for the continued observation of each observer. The more paradoxes that are created by the existence of transition states for the target state set by the masculine prime , the more number of transitioning states will continue with various forms to reach the target desired state of the prime masculine prime.

However if the desired target state cannot be met by the paradoxical transition states that will create contradictions of two transition states , then inertial forces will act on the observers such that their observational functionality will result in movement drag and eventually stop its conscious intent thus ending the life movement of the observing consciousness or dimensional information that is the particular transition state.

20.3 Hierarchy of control

Suppose if the creator of a location " X " defines the " n " dimensions of information D1,D2,....,Dn such that it defines the geometric structure of the location " X " based on the purpose it was defined for . Therefore the " n " dimensions of information are defining the geometric dimensions of the location " X " specifically the number of axis that are required to define the location " X ".

Location " X " could either be a three-dimensional geometric space defined by the coordinates (X , Y , Z) , or a fourth dimensional geometric space defined by the co-ordinate (X Y Z T) etc

Suppose for a three dimensional space , the states could be described as follows :

Current State

Location does not exist , therefore X , Y and Z are 0

Target state

Location exists , therefore X,Y and Z are defined with limits that define the scale and dimension of each variable then for each variable :

X has a range between [X1 to X2]

Y has a range between [Y1 to Y2]

Z has a range between [Z1 to Z2]

The Enclosed volume that is defined by the limits in each axis is defined as the location " X " .

Therefore the " n " dimensions of information that describe the location " X " could take any value within the enclosed volume for the target state. This literally implies that each dimension of information has a value at the target such as :

D1 - (X11,Y17,Z19)

...

Dn - (X18,Y167,Z199)

Therefore the target state of the location " X " is literally defined by the geometric coordinates that each dimension of information takes at the target state.

The scale of observation is the limits of each axis that are defined to describe the location relative to the current state (origin) and the dimension of observation is literally the location of each dimension of information takes relative to the current state (origin).

Transition state

There " n " objects that are defined with the variable X , this means that D1,....,Dn take a value between X1 and X2 in their target state.

The number of times that each dimension of information D1,D2,... Dn take before it reaches its target value between X1 and X2

20.4 Illustration

D1 could transition as a sequence from X1, X11,X12,.... X14 . Let the number of sequences that D1 take " N1 " before settling at its target state X14

Dn could transition as a sequence from X1, X11,X12,.... X144 . Let the number of sequences that Dn take " Nn" before settling at its target state X144

By definition of the scale (limits for the X dimension) the values of D1 and Dn vary between X1 and X2. Similarly the values of D1 and Dn vary between Z1 and Z2 in the Z dimension and Y1 and Y2 in the Y dimension.

Suppose if the three dimensional space " X " was being observed from any location outside the location " X ", then the has to be another reference of axis that could be drawn as a perpendicular bisector from that reference T axis to all three dimensions . Let the axis be defined by the variable time T.

Therefore every one of the " n " dimensions of information defined by D1,..,Dn take a value where the perpendicular bisector meets the each information dimension which has a transition state that is defined at the point of intersection.

The reference axis T which is used for the observation of the transition state in geometrical terms implies observing the locations of each dimensions of information relative to the origin of observation.

Since each dimension of information Di undergoes Ni number of state changes before it stabilizes to the target state , this means each the transition states that occur to from the current state to the target state could be defined by the transition of each dimension of information such as:

D1 undergoes N1 transitions before it reaches the target coordinate (X11,Y17,Z19)

...

Dn undergoes Nn transitions before it reaches the target coordinate (X18,Y167,Z199)

The masculine prime observer could exclusively define the target state for creating any location by explicitly defining the scale limits of each axis , the number of dimensions that transition within these limits to achieve the target state and the exact coordinates for each of the dimensions of information.

The Masculine prime is assumed to have the highest amount of energy and exclusively defining the target state will create the total number of observers (N1+N2+...+Nn) that is required to observe the total number of transition. The number of observers that are required are created hierarchically such as :

Suppose if a dimension of information " D_n+1" is created to observe the N1 transitions of the information D1 in a sequence such that it goes from the origin to the coordinate (X11,Y17,Z19).

Then the information dimension D_n+1 has a purpose which is to observe the N1 transitions in a sequence that defines its target state which essentially means that as D1 reaches the coordinate (X11,Y17,Z19).

The purpose of D_n+1 is then to interact at the each transition state of D1 such that the subsequent cordinate of D1 is aligned to meet the target state (X11,Y17,Z19). The alignment could occur based on the functionality of D_n+1 which observes the surrounding transitions such as the ongoing transitions of information dimensions such as D2,...Dn.

If the observing dimension of information D_n+1 could observe the transition states of all the dimensions of information D2,...Dn then he is called the masculine observer whose concious awanress matches will allow to observe all the relavent transitions that are relavent to the transitional trajectory of the dimensin of information D1.

However if the number of dimensions of information that D_n+1 is a fraction of the total amount of inforamtion (D2,..Dn) then the cocnious awarness is a fucntion of his observing capabilitities.

Suppose if there are " n " number of additional observatinal dimensions created (D_n+1 + D_n+2 ...+ D_n+n) explicity to observe the transitioning states (D1,...Dn) , then the ability of each observational dimension to observe the interference of other observational dimensions in the transitional trajectory of its assigned dimension definies its rotational observational capabilities .

If any of the observational dimensions (D_n+1, D_n+2 ..., D_n+n) could observe the observation and interaction mechanism of the other observers in its totality in the location " X " , then he is called the prime observer.

20.5 observational states

Estimating number of observers

The states that are defined by each observer has a probability based on the amount of energy that is being diverted to the target state transition

Suppose if there " n " observers who are observing " n " dimensions of information that are transitioning from state to state . Each with its own number of states that are required for each dimension of information N1,N2,.,Nn

Suppose each of the " n " observers observe one dimension D1 of information then ,

The observe that the co-ordinate change of D1 from (0 0 0),(X1 Y1 Z1), (X2 Y2 Z2),..... (Xn1 Yn1 Zn1) Where the co-ordinate (Xn1 Yn1 Zn1) serves as the target state for the masculine observer created to observe the state changes to reach the target state.

Let D_n1 is the dimensional observer that is created to observe the other changes in the transition states (D2,...Dn etc) to ensure the accurate transition of D1 to the target co-ordinate and consequently the keep track of the other observers (D_n2,...,D_nn) created (estimated by tracking their locations relative the locatkion of D_n1) to observe the corresponding transition of geometric information of the location X.

Suppose is D_n1 is the observing the transition of the dimensional information D1 which describes the geometric information that is describing the geometric configuration of the location X described by the masculine prime , the energy that is being directed to the change in transitions would be the direct source of energy from the masculine prime . This is because the underlying geometric configurations that describe the location X is the fundamental state that is created for the creation of new states for that location.

The underlying geometry through which all other states could be built on is therefore defined the prime geometric timeline and the amount of energy that is bieng directed to create and maintain the geometric integratity of the location X would be called unsable energy of the location X.

Since any observer or geometric dimensions of energy that are transition into the sequence of states is based on energy then the amount of energy that will be used for this process will be directed from the free energy available in the location.

Since any location created by the masculine prime will have components namely:

Free energy - Energy that could be used by any of the observing masculines
Unusable energy - Energy that is used to maintain the underlying geometric integrity of the location X and the D1 dimension of information could representn the base transition changes that occur as a consequence or a response based on the transitioning states of the other dimensional information (D2,..., Dn) such the overall state of the location X could be maintained under a set balance of energy distribution by the prime masculine.

Specifically the amount of free energy and unusable energy that is distributed between D1 (Fundamental transition changes that occur to maintain the geometric integrity of the location X)

D2,D3,...,Dn Changes that are occurring for the creation and maintainance of other states in the location X that are independently or jointly created and controlled by the observing individuals D_n,...D_nn .

If the total amount of energy in a defined in a location X is assumed constant then the total amount of energy is assumed to be conserved . The total

energy is in the location is then free energy and undable energy in the location.

Suppose if the observing masculines (D_n2,...,D_nn) are using the free energy in the location to fix target states of the various geometric dimensional information (D2,D3,...,Dn) such that the geometric integratity of the underlying geometric configuration described by the dimensional information D1 which is being observed by the masculine prime D_n1 , then the ratio of unusable energy increases to maintain or alter the states of the dimensional information D1.

Suppose if multiple observing masculines are creating target states for transition of the one of the masculine , the target state of the masculine will be defined by the total amount of free energy that is being diverted to fix the target state of each masculine or if they choose to interact with the dimensions of information D1 that is stabilizing the geometric configuration of the location X , the dimensions of D1 does not change because the geometric configuration pre dates the other dimensions of information upon whoich other dimensions are constructed over the D1 dimension of geometric information.

Suppose if the location of the observer D_n1 is based on his ability to observe and interact with the transition states of the geometric dimensions of information (D2,... Dn)such that the underlying transition states of geometric dimension of information D1 could be maintained to reach the set target state location (Xn1 Yn1 Zn1) .

The interaction between D_n1 and the other observers could occur in the following format :

1. D_n1 observes the transition states of the underlying geometric dimensional information D1

2. D_n1 observes the transition states of the other geometric dimensional information (D2,..., Dn) that could potentially interfere with the fundamental transitioning states of D1.

3. D_n1 alters the transitioning states of various interfering geometric dimensional information (D2,..., Dn) by altering the target locations of each of those geometric dimensional information.

4. Suppose if the target locations of each of those geometric dimensional information (D2,...,Dn) was (Xn2 , Yn2 , Zn2), (Xn3 , Yn3 , Zn3)... (Xnn , Ynn , Znn) set by their corresponding masculines (D_n2, D_n3,..,D_nn) then the expected number of location transitions for each of those dimensions of geometric information would be (N2,...,Nn)

5. If the prime observer D_n1 alters the target locations of various geometric dimensions of information (D2,...Dn) , the target location of each of these

geometric information would be dependent on his ability to prevent interruption of the N1 transition states of D1.

6. If interference from the observer prime occurs the target locations of geometric dimensional information (D2,...,Dn) would change to (X_n2 , Y_n2 , Z_n2), (X_n3 , Y_n3 , Z_n3)... (X_nn , Y_nn , Z_nn) thus changing the number of transitions for each geometric dimensional information to (N_2,N_3,..,N_n)

7. The interference then triggers the response of the masculine observers (D_n2,...,D_nn) of geometric dimensions of information (D2,...Dn) who observe and interact with the location of D_n1 by using their collective free energy to alter his location such that the interference is interrupted or reversed. Since the prime observer uses unusable energy of the location , any free energy directed towards him is either converted to unusable energy to deterministically fix the geometric dimensional information of the masculine observers (D_n2, D_n3,..,D_nn). This means that the target location of the observing masculines would no longer be variable to observe their geometric dimensional information (D2,...,Dn) . This consequently implies that target locations would no longer be correlated to the number of transitions associated with each geometric information (N_2,N_3,..,N_n). The locations of the observering masculines would transition similar to the geometric dimensional information. The observing geometrical dimensions of information would be reduced to the status of that of the geometrical dimensional information.

This means that the total number of information in the location X would change to the following :

(D_n2,...,D_nn) would change to (Dn+2,Dn+3...,Dn+n) thus losing their masculinity in the location X.

The target locations of geometric dimensional information (D2,...,Dn) would then be set to the target locations (X_n2 , Y_n2 , Z_n2), (X_n3 , Y_n3 , Z_n3)... (X_nn , Y_nn , Z_nn) thus changing the number of transitions for each geometric dimensional information to (N_2,N_3,..,N_n) which will be accomplished by the creation of a new set of observers (D1_n2,D1_n2,...,D1_nn) set by the prime observer D_n1.

This also consequently means that there would be (D1_n+2,D1_n+3...,D1_n+n) new observers created to ensure the transition of the new geometric information created from the old observers (Dn+2,Dn+2...,Dn+n) to their target locations (D1X_n+2 , D1Y_n+2 , D1Z_n+2), ... (D1X_n+n , D1Y_n+n , D1Z_n+n) .

20.6 Defining the masculine prime

Suppose if the masculine prime had created the three dimensional location " X " as the following :

Current State

(0 0 0)

Target State

Let the target state be defined by the volume that is created by intersection of the three axis (X Y Z) with the scale for each within the range of :

(X0 Xn)

(Y0 Yn)

(Z0 Zn)

Suppose if the range above is defined by the " n " dimensions of information (D1,D2,D3...Dn) such that each has one or more co-ordinates that is defined by the co-ordinates sequence (X1 Y1 Z1),...,(Xn Yn Zn) for each dimension.

Therefore each dimension Di could contain " P " information sets that could define the location of each. For simplicity of the analysis it is assumed that each dimension of information contains one piece of information and thus one coordinate.

Let D1 be the set of information that defines the external boundary of the volume , meaning that it contains the vertices of the outermost points (eight for a three dimensional cube) . There D1 contains the fundamental component of the geometry of the location X. For simplicity it is assumed to be one coordinate (X1 Y1 Z1) but in reality it should be a collection of eight vertices in three D space.

The limits or the boundaries that are defined by the eight vertices are explicitly defined by a perpendicular bisector from a reference axis T that is perpendicular to all three axis. The point of origin from the reference axis T is defined as the state of higher dimensional observation.

Therefore for a higher dimensional observer to observe the location in three dimensional plane , he has to plot eight perpendicular bisectors from his reference point of t = 0 from the T axis.

20.6.1 Defining the current moment

Suppose if the masculine prime is the creator of the location X , then he starts by creating the outer nodes of the geometric space that he wants to observe by defining a reference point t = 0 on the time axis T. This would be current moment for the observer.

If the role of the prime observer is to trace the eight vertices of the geometric shape at various points on the reference axis such as t =0,T1,T2,...

Then at each point on his reference axis he plots eight perpendicular bisectors to observe the overall shape of the volume which could either be symmetric or asymmetric or anything in-between such as skewness . Each shape either uniform or non uniform could have its own form of communication with the prime observer similar to a language derived exclusively from geometry. In theory a three dimensional geometric shape at any instant of time could explicitly define the intent of the individual in the surroundings like a like a moving Lego that is rolling around in a ocean of other Lego pieces . At any instant , the shape of the intersection between the identified Lego and the collective Lego pieces in the background describes its intent in the surroundings. Particularly the intersection between the identified Lego and the overall surroundings is the event horizon that is unique to each individual like a finger print that defines the exact action of the individual in the surroundings.

Suppose the masculine prime D_n1 exclusively observes the dimension of information D1 that describes the dimension of information that is fundamental to the location X such as its outer boundaries , then his simply observes the overall shape at various reference points of his observation and determines the next target state for the overall geometry of location X. The Target state is simply defined by the explicitly defining the eight target location coordinates for three dimensional space .

The linearity of his time if he exclusively chooses to observe the outer boundaries would be the continuity of time that is presented with the sequential flow of discrete points of time t= 0,T1,T2,....

For simplicity , the D1 dimension of information could be defined as one coordinate at each time frame of reference T1,T2,... as (X1 Y1 Z1),(X2 Y2 Z2),...that defines the fundamental geometric structure of the location X.

20.7 Defining the hierarchical sequence of observers starting from the masculine prime

Let the masculine prime define the external boundary of location " X " at the target state through the fundamental geometric dimension D1 defined by location (Xn Yn Zn) in simplistic form.

Where at the current state of the location X , D1 is defined at the origin (0 0 0) and at the target state be defined by the target coordinate (Xn1 Yn1 Zn1) where the N1 transition states are defined by the coordinates (X1 Y1 Z1), (X2 Y2 Z2),...(Xn1 Yn1 Zn1).

Suppose if there are "n " dimensions that could be in the location that describe various geometric information where " n " could increase at every each transition state as a result of continuous growth of information in the location X as a result of continuous observation of various kinds of movements in the location.

Therefore each dimension of information could be described as D2,D3,....Dn with its own set of transition states N2,N3,...,Nn where the number of states are defined by the prime observer by explicitly defining the target state for the location X as a whole through the dimension of geometric information D1.

At each transition state of the dimensional geometric information D1 , and its corresponding co-ordinate value (X1 Y1 Z1),...,(Xn1 Yn1 Zn1) should have a implicit correlated effect with the transition states N2,N3,...,Nn of each dimension of geometric dimensional information D2,D3,...,Dn through the co-ordinates .

Suppose if the transition of the states are defined by the reference points of observation measurement from the masculine prime , the transition state co-ordinates are assumed to be measured at the same time .

Suppose at the target state of the geometric dimensional information D1 defined by the masculine prime as (Xn1 Yn1 Zn1) , then the target state of various dimensions of geometric information D2,D3,..Dn must be (Xn2 Yn2 Zn2),(Xn3 Yn3 Zn3)....(Xnn Ynn Znn)

Since the coordinate (Xn1 Yn1 Zn1) is defined deterministically by the masculine prime , there must be some inplicit relationship between the other coordinates (Xn2 Yn2 Zn2),(Xn3 Yn3 Zn3)....(Xnn Ynn Znn) collectively.

Specifically the number of transitions that occurs for each geometric dimension information . If N1 transitions has to occur for D1 then N2 transitions has to occur for D2, and finally Nn transition for Dn.

The number of transitions could be a variable that is defined by the observer of

the transition of the states. Suppose the prime masculine observes the current state at his transition point t = T1 referenced based on his geometric axis , then the prime observer draws " n" perpendicular bisectors to each of these locations calculates the number of transitions that needed to occur relatively between D1 and the other set of points (D2,...,Dn).

The calculation of the states are done by approximating the distance between the point D1 in the current state and the expected target state location. The distance provides the exact directional instructions to reduce the distance between the current state and the target state. Since Dn,D2,..Dn are implicitly correlated to the point D1 , their directional movement could be correlated through a relationship function. Specifically since D1 is the fundamental geometric information of the location, any change in its geometry is likely to affect the change in the directional movement of D2,D3...Dn. Thus the distance between the locations of each dimension of geometric information D1 ,D2...at the current state to the expected target coordinates could be calculated.

If the transition states are defined by the observer as T1,T2,...etc at a predefined equal internals then dT = (T2-T1) is the duration between observations. If the Euclidean distance between each point D1 ,D2,..,Dn from its current state to the expected target state is L1,...,Ln then the number of transitions N1,...Nn that must occur at each point of observation T1,T2,.. is given by L1/dT , L2/dT,....

Where N1 = L1/dT, N2 = L2/dT etc

The directional alignment that must occur from one point of observation to the next could be the component of interaction from the masculine prime. Thus in a mathematical context , the observation component of the masculine prime in the dimension of geometry is estimating Euclidean distance and the interaction component of the masculine prime is aligning the direction component of the point such the change in location occurs towards the line of best fit in alignment with the Euclidean distance.

The entire process could be modelled deterministically in the geometric point universe however , the interpretation of this process could take an infinite number of forms . However if there could be " K " interpretations of this geometric movement where the perception of the movement could be made stochastic to various degrees by choosing not to observe all the transitions that need to occur for the target state of D1.

If the prime observer could deterministically set the target destination then he could choose to observe the transition of any of the any of the other geometric information such as D2,D3 ,..etc without observing the point D1 . This implies the observation of the prime observer loses the deterministic reference point for the transitions that are occurring. This creates the perception of movement that forces the growth of conscious awareness in the forward observation trajectory

of the prime observer.

Suppose if the prime masculine could choose to observe a variable set of geometric dimensional information such as (D2,D3) , (D5,D8,D9,D3) etc then a hierarchy of observers could be created based on the highest amount of observable information to the lowest amount of observable information.

Masculine prime could observe all the geometric dimensional information at each transition state D1,D2,...Dn at which point he would have the perfect deterministic conscious awareness where there is no information loss for his movement.

Masculine prime could observe most of the geometric dimensional information at each transition state D2,...Dn Except D1 at which point he would have deterministic conscious awareness but there is no information about the target destination's sustainability to the geometry of the location X which is stored in D1.

.....

Masculine prime could some of the geometric dimensional information at each transition state (ex. D4,D5, D7) Except D1 and Dn at which point he would have limited conscious awareness about the geometrical dimensions of information in the surroundings but there is no information about the target destination.

Thus a scale could be established on his conscious awareness for his movement that defines his perception towards his surroundings as an interesting mix of deterministic and stochastic directional movement. Suppose if the prime observer has a made several copies of himself differentiated by his conscious awareness of location trajectories of various geometric dimensional information then the resulting interactions from the mixture of deterministic and stochastic movements could contribute to the more geometric dimensions of information being created at each transition state. This leads to the expansion of the dimensional geometric information of D1 thus allowing for the geometric expansion of territory.

20.8 Interaction of multiple observers based on contradictory states

The observers D_n1,D_n2,D_n3 etc could be created deterministically based on the following criteria.

Suppose if the prime observer D_n1 only chooses to observe the fundamental dimensions of geometric information D1 to maintain the integrity of the loca-

tion " X " at each transition of the geometric co-ordinates of D1 , then the prime observer observes the other transitions of the other geometric dimensions and interacts with the directional transition of D1 to minimize the transitions N1 required for the target location of D1. The target location for D1 after at transition could be deterministically set by the prime observer based on his conscious awareness.

Let the be " n-1" observes that be deterministically programmed with geometric functions such that based on the target location set by the masculine for each dimensional geometric information D2,D2,... at each transition , the location of each geometric dimension of information D2,D3,...Dn could be altered automatically such that D1 would maximize the probability of reaching its target destination. This process could occur by minimizing the number of transitions for D1 to meet its target state location.

Suppose each of the " n-1 " observers that is observing and interacting with geometric dimensional information D2,D3,...Dn then the amount of conscious awareness that each of these observers could have would be limited to the dimensions of information Di and the various observers D_ni that are relevant to the specific transitions that they are observing. This would be based on the energy requirement principle where limiting the observation and interaction to the required information field only , the Euclidean distance and the direction realignment required for each point to align with the Euclidian distance could be accurately calculated.

Since this process results in the varying levels of conscious awareness of each observer , their perception for observing the various transition states could vary specifically according to their intent that is correlated to the perception of the observer and his relationship in the surroundings.

20.8.1 Defining the transition states where the hierarchical sequence of observers choose to interact becomes the current movement

Let there be " N1 " transitions estimated for the target state set by the prime observer of the location "X". This means that the prime observer has observed the current location of D1 at t = T1 and expected to make another observation for D1 at t = T2 where he expects the target location of D1 to be fixed. The variable T2 could be stochastic which depends on the number of the transitions N1 to go from T1 to T2 that is implicitly correlated to the current locations and the expected target locations of D2,D3...,Dn. The variables N2,N3,...Nn are the minimized transitions which is estimated at each state to minimize N1.

Suppose if the masculine prime observer chooses to observe only the states

at T1 and T2 , but also would like to observe any of the transitioning states between T1 and T2.

Let there be (n-1) automatic observers D_n2,D_n3,...,D_n that are automatically created such that it is entangled to the observer D_n1 such that the automatic observers align with the intended target location of D1.

In theory the prime observer could align his conscious awareness with any one of the automatic observers to independently observer the transition state that is defined by the conscious awareness of the automatic observer based on his limits of scale and dimension of observation that is collectively defined by the geometry and the observers navigating the rate of change of geometry through the repeated estimation of target locations and transitions for those target locations .

Let there be " k " masculine observers out of the (n-1) automatic observers whose intent allows them to diverge from their functionality. This could occur if the various observes have high enough conscious awareness such that they could start redirecting the geometric dimensional information D2,...Dn such that it no longer aligns with the overall underlying geometric structure that is being kept stable by the geometric dimensional information D1. Since the " k " masculine observers no longer have energy from the prime observer to observe and interact with the transitioning states , they could engineer the observation and interaction of the remaining (n-1-k) automatic observers such that the automatic observers could perform the intents of the misaligned masculine observers in the territory.

If the automatic observers diverge from their transition observation criteria which is to align the target locations of various geometric dimensional information , then the access to observe and interact with the various geometric dimensions of information will start to decay as a result of the misalignment with the prime observer similar to the " k " masculine observer.

This process could start a degradation or a corruption process of the created masculine observers who will continually start to interfere with the other automatic observers as a result of their lack of energy to interact with the location " X ".

20.8.2 The Engineering process of the misaligned" k " masculines

The " k " masculine observers could then start observing various dimensions of geometric information (D2,D3,...,Dn) and the automatic observers (D_n2,.,D_nn) assigned to observe their transition states and alter the conscious intent of the observers such that the energy they have for observation and interaction could

be diverted to the conscious intents of the masculine. This then introduces inefficiency in the transition states N2,N3,...Nn thus no longer being minimum that minimizes the transitions N1 for the dimension D1.

This process is accomplished by the misaligned " k " masculines by the following process :

1. The conscious intent of each observer could be to minimize the transitions N2,N3,... etc. such that the underlying number of transitions for N1 is minimized implicitly at each transition state that is being observed.

2. The " k " unaligned masculines corrupt the transition minimizing algorithm of the automatic observer by deterministically setting the target location of each geometric dimensional information D2,D2,...Dn independently of the target location of D1 which is being observed by the masculine observer. This then creates the transition states (N2,N3,...,Nn) for each geometric dimensional information D2,D2,...Dn that is independent of the transition states N1 which is being observed by the masculine.

20.9 The objective reality

The best definition or the ultimate reality is the reference current location of the prime observer . This is because he would be the source of attention energy for all the automatic observers responsible for the observation and interaction of the transition states such that the target location of the reference geometric dimensional information D1 could be met.

The current movement of the observers become hierarchical which means that the geometrical construct of locations defined by the relative locations D1,D2,...,Dn is dependant on the location of the prime observer. This is because the movement vector field that defines the movement for the automatic observers is defined by the intent of the prime observer which is defined by his observation of the transition states N2,...Nn relative to the transition state N1

The automatic observers are assumed to be in a state of lower conscious awareness because their movement is dependant on the information in the movement vector field defined by the prime observer. This implies that it contains information that is best suited for their movement which is observed by the masculine . This could be defined as instinct for their conscious intent to observe and interact with transitions states for towards the aligned goal of the target location of D1.

The location of the observers who rely on the movement vector field for the observation of the transition states are defined exclusively by the prime observer through the movement vector field. The locations could be correlated to their conscious awareness because the number of geometric dimensional infor-

mation they are observing along with the other observers who are interacting there are defined hierarchically where the information flows from a location of high conscious awareness to a location of low conscious awareness.

This means that each observer has an hierarchy which could be reduced or increased by limiting or expanding their location access. The more limited their location, the more limited their ability to observe the collective dimensional information.

Therefore each location for an observer is accompanied by a state particularly the function of the observer that determines the amount of information that they can observe and interact with. This also determines the amount of energy that each observer could access based on functionality that is also hierarchical form the prime observer.

20.9.1 Interruption of the " k " unaligned masculine observers

If access to energy is cut off to the unaligned observers because of the mismatch in the conscious intent relative to the prime observer in that location then energy could be absorbed or extracted form other observers of various hierarchies through various movement manipulation techniques of automatic observers (D_n2,D_n3,...D_n) relative to the geometric dimensional information (D2,D3,...Dn).

This basically means that the unaligned observers could engineer their surroundings to take control of the state of the observers or their frequency of movement by altering the target state locations of the geometrical dimensional information that they are observing. This consequently changes the number of transitions that each observer is defining at each transition state which consequently affects the prime observers transition states away from the minimization principle and consequently delays his indented target location for D1.

The creative potential energy of any masculine observe to create more observers to enforce various other transitions states of geometrical dimensional information could also be a function of the number of alignments from various other observers. The creative potential energy is then used by the newly created automatic observers to observe and interact to enforce the target locations of various geometric dimensional information.

While the prime observer could divert this creative potential energy naturally , however the unaligned observers who diverge the conscious intent of the prime observer by intercepting the transition states of the geometric dimension information (D2,D3,...,Dn) requires other aligned observers such that their energy could be harvested for their conscious intents.

The location-observer engineering process by the " k " unaligned masculines could drain their energy of he aligned observers through the unobserved quantum channels (designed by deceptive consent) such their creative potential energy could be harvested.

The unaligned observers could achieve this process by quantum entangling with their intents such that the aligned observers (automatic observers) could have their attention on them which allow the unaligned observers to access to location that they normally would not have as a result of their lack of energy to navigate new locations as a result of their misalignment from the prime observer.

The consented transfer of time and energy from the aligned observers to the unaligned observers occurs in exchange for wealth and status which is transferred to the aligned observers . The wealth and status is offered to the aligned observers through the use of higher conscious awareness which could be uses to create a temporary perception that is always limited because the prime observer will eventually intercept the unaligned observers for correcting the transition states including that of the unaligned observers themselves.

21 The diagonal timeline

Suppose if an individual A has a timeline which is a function of his conscious awareness .

Let the individual A be in a location " X1 "

Let the location X1 have a state that is defined by its transition state between its current state and the target state.

Let the prime observer of the location " X1 " define the current state at observation time t = T1 to the target state t = T2 defined as " Y "

Let the transition state be aligned with several other locations namely X2,X3 and X4.

Let there be " N2 " individuals in the location X2 , " N3 " individuals in the location X3 and " N4 " individuals in the location X4.

Let there be " N+1 "individuals in the location X1 including individual A. Let individual A be a new addition to the location " X1" therefore he is assumed to be independent of the transition state in location " X1 "

The transition state is then defined by the movement vector field that defines the overall intent of each of the individuals in various locations such as N in location X1 , N2 in location X2 etc

Suppose if individualAis located in the location X1 , then his ability to observe the movement of the N individuals in locations and conclude his intent through objective movement with respect to time, energy defines his conscious awareness .

Suppose if the individual A interacts with " n " individuals in the location X1 and observes their time distribution then the amount of time that is spent with other individuals define their object movement patterns.

Suppose the consciousness awareness of the individual could be correlated to the observing the intent and its corresponding frequency then any geometric movement that occurs that could be represented through time distribution in any location such as :

Consider an individual W

t = 0

Individual W is at location " X1 "

amount of time spent in location X1 = t1

the number of individuals in location X1 = k1

the intent of individual W with the k1 individuals could be described as follows :

If individual W spends an amount of time " dt1 " in the location X1 with k1 individuals then it could be assumed that he has " Z " intents in the location with respect to the " k1 " individuals as a collective which could either be individual or any permutation or combination possible.

Therefore his time distribution could be expressed as :

t1 = dt1 + dt2 + dt3 +....dtz

Where each increment dt1 could be used for an intent in the particular location and there are " z " number of intents that are assumed.

Suppose the overall transition state of the location X1 could have " Z_int " intents that occurs out of Z overall intents then , the time distribution t1 has a percentage of time that is dedicated for the " Z_int " intents that are explicitly defined for the transition state that is currently occurring . The intents are then defined through the time distribution as follows :

dt_int =

(dt1 + dt2 + dt3 + ..+ dtz_int)

Explicitly for transition intents - Z_int

dt_other =

(t1- dt_int)

There if individual A is the observer of the interaction that is occurring with the individual W , then his ability to separate or discretize the time distribution t1 into two components namely dt_other and dt_int

If the geometric boundaries of any location is assumed to be deterministically defined particularly the outer most edges or points (for a three dimensional location this could be defined by eight points)

Suppose if an individual W could be observed for his movement trajectory in the location X1 through his movement through various sub-locations in the location X1.

Let there be " n " sub-locations " in the

Suppose if the time distribution of each individual could be observed based his movement through various sub-locations.

Suppose if the individual's interaction of " t1 " units could be further divided into various sub-locations within the location X1 , then his movement pattern could be described further as the following :

t = 0

individual is located at sub-location x1

the amount of time spent in the sub-location x1 - dt1

the number of individuals in the interaction - n1

the interaction time dt1 could be further discretized as

dt1 = dt11 + dt12 +....dt1z_sub

Where each increment dt11 , d12 could be time distributed for various sub intents in each sub-location could be used for an intent in the particular sub location and there are " z_sub " number of intents that are assumed.

Suppose the overall transition state of the location x1 could have " Z_sub_int " intents that occurs out of z overall sub intents then , the time distribution dt1 has a percentage of time that is dedicated for the " Z_sub_int " intents that are explicitly defined for the transition state that is currently occurring . The intents are then defined through the time distribution as follows :

dt1_int = (dt11 + dt21+ dt31 + ..+ dt1z_sub_int)

Explicitly for transition intents - Z_sub_int

dt1_other = (dt1- dt1_int)

Therefore by tracing the overall movement pattern of any individual W , the time distribution that are explicitly designed or engineered for the transition states of the location X1 could be identified by the following methods :

First by splitting the overall time distribution in the location X1 into time spent in various sub-locations at an incremental rate and then at various levels of sub-locations defined by the external boundary parameters ,

the intents that are explicitly meant for the transition states particularly the the scale and dimension of the external boundary could be identified

Suppose if the first split of the time distribution dt1 is intended for the transition states of the location boundary X1 as a whole that defines various scales (lags scale an dimension) of the location

Suppose if the second split that is identified dt11 is intended for the transition states of the sub location boundary x1 then the intent is meant for a particular scale and dimension of the sub-location etc.

Thus by explicitly identifying the time distributions that are meant for the transition state of the overall location through various sub-locations defined independently (explicitly 0 or implicitly in collaboration with other locations or sub-locations) could e identified that is shaping the location to the target location defied by the state Y.

Once the time distribution is identified , the intent of the interaction could be observed as a function of the overall geometry of the location X . This could be visualized as a moving parts of decisions that is altering the various dimensions of the external geometry of the geometry that could be summarized to the key external nodes of the geometry which for a three dimensional space could be defined by observing the eight nodes that define the volume of the location

21.1 The transition state

Let each transition that is defined by the components of time durations individual W be defined as follows :

dt_int + dt_other at the scale and dimension of the location X1 of volume V1 (entire region)

dt1_int + dt1_other at the scale and dimension of the sub-location x1 of volume Vx1

....

dtn_int + dtn_other at the scale and dimension of the sub-location xn of volume Vxn

Where dt_int are the deterministic components that define the eight the external outline boundaries of the location that change from a sequence of states from the current state made at time t = T1 to the target state made at time t = T2 . In three dimensional geometric form , if the time durations describe the

rate of change of the external geometric shape of the location that is defined by eight points , then it describes the rate of change of eight co-ordinates of the three dimensional shape of the location from time t = T to the time t = T2 through various sequences of changes in the co-ordinates that literally describe the transition state " Y " for the defined target state at time t = T.

dt_other are the non deterministic components . The interactions or conscious intents that are discussed in these interactions are stochastic replaceable and have nothing to the geometric components of the locations that are defining the evolution of the geometric structure of the locations from its current state made at time t = T1 to the transition state that is made at time t = T2.

Where V1 = Vx1 + Vx2 +....+ Vxn

dt1_int is the the time duration of the interaction spent by individual W in the sub-location x1 for the geometric boundaries within the region of volume Vx1 . For three dimensional space it could be assumed to be eight points that define the external shape of the region of volume Vx1

.....

dtn_int is the time duration ..... volume Vxn

The remaining time distributions dt1_other,....,dtn_other describe random subjective interactions that are independent of the geometry and are independent of the geometry. The interactions for the subjective interactions only exist in continuous form of time observation. This is because ,in any given interaction time " t1 " , if there are " k " individuals then the transition states do not necessarily occur in sequential order.

This means that the overall time t1 = dt1 + dt2 +....+ dtz is not an assembly of interactions in continuous form but rather an assembly of time fragments that contains key co-ordination information in discrete form . In any interaction dt units of continuous time , there could N fragments of instantaneous time packets that are composed of the time boundary set . Any image within the time boundary of dt units could be observed with key pieces of information that associate the external pieces of the geometric boundary with a specific target location or coordinate. This means among-st an N (finite or infinite) number of frozen time fragments that could be possible , there would be a finite number of frozen time packets that explicitly define the transition locations for the external boundary of the geometric location. For three dimensional form of the volume of the location , the change in coordinates for the eight coordinates could be defined at various instants of time by the attention vector of various individuals in the interaction.

The observation of this change of transition in continuous form is therefore

described as dt_int that is the collection of changing location coordinates in sequential form for the external boundary of the geometric coordinates of the location. To observe the duration dt_int units , the observer has to isolate various instantaneous packets of time from the overall interaction time dt in any location for any individual.

The exchange of geometric information in interactions could occur through the descriptions that are made in various scales and dimensions of information which could be described as frequency of communication. For an observer to interpret this exchange of geometric information , the observer must have the language or the frequency to decode the exact scale and dimension that the communication is occurring in. Therefore the observer must have a range of frequencies that he could observe and interact with such that he could intercept the geometric information being exchanged and alter it if required.

The prime observer of any location is assumed to hold all the frequencies that exist in the location .

21.2 A

Consider an individual A and his time start from measurement at time t = 0

t = 0

individual A is at location " X1 "

amount of time spent in location X1 = t1

the number of individuals in location X1 = k1

the intent of individual A with the k1 individuals could be described as follows :

If individual A spends an amount of time " dt1 " in the location X1 with k1 individuals then it could be assumed that he has " Z " intents in the location with respect to the " k1 " individuals as a collective which could either be individual or any permutation or combination possible.

Therefore his time distribution could be expressed as :

t1 = dt1 + dt2 + dt3 +....dtz

Where each increment dt1 could be used for an intent in the particular location and there are " z " number of intents that are assumed.

Suppose the overall transition state of the location X1 could have " Z_int " intents that occurs out of Z overall intents then , the time distribution t1 has a percentage of time that is dedicated for the " Z_int " intents that are explicitly defined for the transition state that is currently occurring . The intents are then defined through the time distribution as follows :

dt_int = (dt1 + dt2 + dt3 + ..+ dtz_int)

Explicitly for transition intents - Z_int

dt_other = (t1- dt_int)

Therefore individual A has a time distribution of t1 units that is split between the "k1" individuals and time could be redistributed as the following :

Individual A spends an amount of time T1 with individual one

Individual A spends an amount of time T2 with individual two

...

Individual A spends an amount of time Tk1 with individual k1

Let each Ti could be split further as :

T1 = T1_int + T1_other

....

Tk1 = Tk1_int + Tk1_other

Where the component Ti_int is the time distribution that is explicitly used for transition state that defines the geometric boundaries of the location X1 or any of its sublocations xi.

Thus if individual A interacts with k1 individuals in total the time distribution could further be split as follows by splitting and combining the time components of each individual with respect to the transition state and the everything irrelevant to the geometry outside the transition state

T_int = T1_int + ...+ Tk1_int

T_other = T1_other +.....+ Tk1_other

t1 = T_int + T_other

Where T_int is the total time that is used to communicate information regarding the geometric components of the location X1 from each of the k1 individuals which is assumed to be the deterministic interaction.

T_other is the total time that is used to communicate information that is stochastic and replaceable and could be a function of location, attention vector or any other metrics that have no overall effect in the location X1. Therefore the overall time distribution T_other becomes noise for the transition state of the location X1.

Suppose if the external geometric structure of the location X which in three dimensions is defined by the volume that is enclosed by the eight vertices of the location then , the transition state could be represented as follows :

The location X1 has eight vertices that define its outermost shape therefore the outermost external boundaries that are defined by the co-ordinate set A = ((X_1 Y_1 Z_1) ,...,(X_8 Y_8 Z_8))

The location X1 has " n " sub-locations that is enclosed by set A and thus each sub-location x1,x2,...,xn has eight vertices that define its outermost shape therefore the outermost external boundaries that are defined by the coordinate sets :

subset of co-ordinates that define the outermost boundary of sub-location x1 set A_1 = ((x1_1 y1_1 z1_1), ...,(x1_8 y1_8 z1_8))

...

subset of co-ordinates that define the outermost boundary of sub-location xn set A_n = ((xn_1 yn_1 zn_1), ...,(xn_8 yn_8 zn_8))

Thus the communication that occurs with individual A that is defined by T_int with the k1 individuals is explicitly concerning the overall co-ordinate set that defines information regarding the transition state of the location X

which is defined by :

Transition Set for state Y of the location X1 is then given by the set Y = (Set A , Set A_1,....,Set A_n)

Where the set Y could be expanded by creating sub-sub locations from each sub-location by creating n_i sub-sub locations from each sub-locations . Where the sub-cation x1 is assumed to have n1 sub-sub locations, x2 is assumed to have n2 sub locations and the sub-location xn is assumed to have nn sub-sub-locations in which the set would look like the following :

set Y = (Set A, Set A_1 , Set A_1_1,...,Set A_1_n1 , ..., Set A_n,Set A_n_1....., Set A_n_nn)

Where each element in the above set is a set of eight co-ordinates that define the outermost external boundary of the location,sub-location and sub-sub locations respectively. For any transition state that occurs towards the defined state at time t = T2 of the location X1 , the set Y is communicated between the individual A and the k1 individuals in the interaction duration T_int .

The interaction time T_int has directional information flow from the masculine to the sub-masculine to the non-masculine in any interaction , therefore each interaction has one masculine that describes the transition state of the location X1, or the " n " sub-locations or several sub-sub-locations from each sub-location.

The remaining time distribution T_other that occurs in the interaction is independent of hierarchy of masculinity that defines the transition state of each location and effectively becomes random noise of the state Y as the transition of co-ordinates that flow towards the target state defined at time t = T2. The movement trajectory that occurs is explicitly defined the time distribution T_int that defines the locations where the exchange of information occurs will define the underlying deterministic trajectories that maintain the geometric integrity of the location X1 that is defined by the prime observer of the location X1 . The various individuals or the trajectories that follow in each location, sub-location or sub-sub-location that transmit the co-ordinates to maintain the state Y set by the prime observers occurs through the set of observing and interacting masculine individuals for the prime observer .

21.3 B

Suppose the timeline of individual A could then be defined his time distribution such as :

Time t = 0

individual A is located at X1

the amount of time that is spent in x1 = t1 units

the number of individuals located in x1 = k1

the amount of time t1 units could be discretized as the following :

t1 = T_int + T_other

Where T_int = T1_int + T2_int +...+ Tk2_int

T_other = T1_other + T2_other + ...+ Tk2_other

Where the time spent with each of the individuals is defined as T1_int + T1_other . Where T1_int is the deterministic communication that occurs that cannot be changed that is assumed to occur at a hidden frequency . The frequency of this communication could be defined as an interaction key that allows for the language of information exchange . The frequency or the interaction key is assumed to be created by the masculine who establishes the hierarchical order of information flow , since each masculine individual in the hierarchy could create their own frequency or a unique interaction key to communicate information flow to sub-masculine , the frequency or the interaction key becomes a code that cannot be deciphered unless the observer is in the higher order of the decision making of the communicating individuals in which case he could observe their communication frequency to decipher the intent in the interaction.

Suppose if individual A is not the only masculine , then let there be K masculines operating the location X1 who may or may not be located within in the location.

Suppose if the k1 individuals that are located in the location X1 have multiple masculines that are communicating deterministic information then , each of the individuals have their own time distribution as follows :

Since the t1 units of time is shared between individual A and the " k1 " individuals then the average time distribution for each of these individuals could be serving as masculines or sub-masculines for the K masculines.

ti = Ti_ind + Ti_other for each of the " k " individuals could be the superposed time distribution for the information flow from each of the K masculine where the time distribution Ti_ind would be the deterministic information flow from one or more of the observing K masculines.

The time distribution Ti_ind = Ti_ind_1 + Ti_ind_2 +..... + Ti_ind_K

Since there are " k1 " individuals in the location X1 , each variable i represents the time distribution that is meant for communication for one specific individual " i " out of the k1 individuals in the interaction.

the suffix ind_1 , ind_2,..., ind_K represent the masculine from which the deterministic information flow occurs specifically identifying the masculine from where the deterministic information flow is coming from.

This creates a subjective mixture of information flow between various indi-

viduals in the location X1. Since the total time that is shared by the (k+1) individuals in the interaction is constant and is assumed to be t1 units.

The distribution of deterministic information flow and noise becomes subjective for all individuals involved (k1 individuals in the location X1 , " K " masculines who are observing the location X1 who may or may not be part of the " k+1" individuals in the location , individual A)

Therefore the time distribution of each individual in each location describes his perception of the objective reality when considering his only his own time distribution , however the objective reality becomes subjective when the time distribution of all individuals could be observed simultaneously. Under the circumstances , the only objective reality would be the deterministic time distribution of the prime observer that defines the external boundary set Y of the location X1.

Thus the time distribution of the prime observer between his sub-masculines and the non-masculines becomes the objective reality in the location X1. Every other time distribution from the " K " other masculines that deterministically defines their own external boundary set (Y_1,...Y_K) for the location X1 becomes subjective . Any contradictory definitions for the external boundary from the sets (Y_1,...,Y_K) towards the set Y of the prime observer will be voided as noise along the transitions towards the target destination at t = T2.

21.4 C

Suppose if at any point of time the set Y describe the current location in the multiverse set by the prime observer , the state Y then describes the exact transition state that describe the multiverse for the state Y. The state Y then describes the transition that is occurring towards the target destination for the time t = T2.

Suppose if the prime observer had already set the target destination at t = T2 , there could be " N " ways with which the target state at t = T2 could be reached. Where "set Y " could be assumed to be a kind of reference for the prime observer. Particularly if the prime observer had initially observed the state at t = T1 , and then created the target state at t = T2 and the directional pathway to go from T1 to T2 could be called as the " State Y "

The number of possibilities or location transitions that could be possible to go from t = T1 to T2 could be dependent on the number of location transitions that could be possible for the following :

The location X1 has " n " sub-locations namely x1,x2,x3,..,xn

Each one of those sub-locations has "n_i " sub-sub locations such as

x1_1,x1_2,...,x1_n1

x2_1,x2_2,....,x2_n2,

...

xn_1,xn_2,....,xn_nn

Thus the entire number of possibilities for the state Y could be defined by first representing the entire location X1 through sub-sub locations .

If one of those locations have a set of eight coordinates to define the external boundary or volume then the transition pathway for the state t = T2 is defined by reduction in distance that occurs from each of the eight co-ordinates in each location to the one that is defined at time T2 .

At the observation time t = T2 , the matrix below has a deterministic set of eight co-ordinates

x1_1,x1_2,...,x1_n1

x2_1,x2_2,....,x2_n2,

...

xn_1,xn_2,....,xn_nn

At any transition state where the observation lies between the time t = T1 and t = T2 ,the matrix below has a random set of eight co-ordinates that is aligning towards the deterministic set of eight co-ordinates

x1_1,x1_2,...,x1_n1

x2_1,x2_2,....,x2_n2,

....

xn_1,xn_2,....,xn_nn

The Euclidean distance between any co-ordinate of any location between the transition state and the target state keeps reducing with each transition that occurs towards the deterministic state defined at t = T2

Suppose the transition states at T2 are defined by explicitly by defining various external co-ordinates by the prime observer then only those co-ordinates become deterministic . Suppose if a hand full of co-ordinates from each sub-sub location are made deterministic as a result of the law of minimal action , then the co-ordinates that are not defined explicitly could vary relative to the deterministic set of co-ordinates which could delay the transition towards the transition towards the target destination at t = T2.

As a result of this phenomenon the point to point Euclidean distance between the transition co-ordinates to the target state co-ordinates could show stochastic variation in the distance to the target which could either increase or decrease but the the probability to reach the target state Y at time T2 would always be maintained. Since the prime observer sets the target state Y at t = T2 , the probability to reach the state Y would be one however the distance to reach the state Y at t = T2 varies. In a literal sense , the distance measure the time variable thus the time to reach the target destination becomes a variable .

The number of variations defined by the distance to target location could literally describe the number of multiverse possibilities to reach the target destination. Thus the multiverse could be described through arrangement of geometric possibilities such that each unique arrangement which serves as the transition state serves a new starting point to reach the target arrangement defined for the target state t = T2.

Where it could take a variable amount of time to shift each co-ordinate to the target coordinate relative to the other co-ordinates for each unique combination of the co-ordinates.

Therefore the " time to destination " describes the multiverse through geometric configurations represented by the Euclidean distance from any transition state to the target state.